# **Density-Based Clustering**

**idea**: Clusters are dense regions in feature space F. density:

l objects | volume



#### here:

- volume: ε-neighborhood for object o w.r.t. distance measure dist(x,y)
- dense region: ε-neighborhood contains MinPts objects
   => o is called core point
- "connected" core points form *clusters*
- Objects outside cluster is considered *noise*

parameters  $\varepsilon \in IR$  and  $MinPts \in IN$  specify the density threshold

 $\epsilon$  MinPts = 4



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• core points



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- core points
- direct density-reachability



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- core points
- *direct density-reachability*
- density reachability



parameters  $\epsilon \in IR$  and  $MinPts \in IN$  specify density threshold

 $\varepsilon$  *MinPts* = 4

- core points
- direct density-reachability
- density reachability
- density connectivity



### **Density-Based Clustering**

formal: [Ester, Kriegel, Sander & Xu 1996]

- Object  $p \in DB$  is a core object, if:
  - $|RQ(p,\varepsilon)| \ge MinPts$
  - $RQ(p,\varepsilon) = \{o \in DB \mid dist(p,o) \le \varepsilon\}$
- Object p ∈ DB is direct density reachable from q ∈ DB wr.t. ε and MinPts, if: p ∈ RQ(q,ε) and q is a core object in DB.
- Object p is density-reachable from object q, if there is a sequence of direct density reachable objects from q to p.
- Two objects p and q are density-connected, if both p and q are density reachable from a third object o.







#### formal:

A density-based cluster C w.r.t.  $\varepsilon$  and MinPts is a noneempty subset of DB with the following properties:

*Maximality*:  $p,q \in DB$ :  $p \in C$  and q is density-reachable from  $p \Rightarrow q \in C$ .

*Connectivity*:  $p,q \in C \Rightarrow p$  and q are density-connected.

## **Density-Based Clustering**

#### formal

• Clustering

A density-based *clustering* CL of DB w.r.t.  $\varepsilon$  and MinPts is the complete set of all density-based clusters w.r.t.  $\varepsilon$  and MinPts.

• Noise

The set *Noise<sub>CL</sub>* is defined as the subset of objects in DB which are not contained in any cluster.

idea behind the DBSCAN algorithm
 Let C be a density-based cluster and let p ∈ C be a core object, then
 C = {o ∈ DB | o density reachable from p w.r.t. ε and MinPts}.

#### Algorithmus DBSCAN

#### **DBSCAN**(dataset DB, Real $\varepsilon$ , Integer MinPts)

- // in beginning all objects are unlabeled,
- // o.Clid = UNLABELED for all  $o \in DB$

```
ClusterId := nextId(NOISE);
```

```
for i from 1 to |DB| do
```

```
Objekt := DB.get(i);
```

```
if Objekt.ClId = UNLABELED then
    if ExpandCluster(DB, Objekt, ClusterId, ɛ, MinPts)
    then ClusterId:=nextId(ClusterId);
```

#### **Density-Based Clustering**

```
ExpandCluster(DB, startObject, clusterId, \varepsilon, MinPts): Boolean
seeds:= RO(startObject, \varepsilon);
if |seeds| < MinPts then // startObject is not a core object
  startObject.ClId := NOISE;
  return false;
// else: startObject is a core object
forall o \in seeds do o.ClId := clusterId;
remove startObject from seeds;
while seeds ≠ Empty do
  select object o from seeds;
  neighborhood := RQ(o, \epsilon);
  if / neighborhood / > MinPts then // o is a core object
    for i from 1 to / neighborhood / do
        p := neighborhood.get(i);
        if p.ClId in {UNLABELED, NOISE} then
                if p.ClId = UNLABELED then
                        add p to seeds;
                p.ClId := ClusterId;
  remove o from seeds;
return true;
```

# **Discussion Density-Based Clustering**

- number of clusters is determined by the algorithm
- Parameters ε and MinPts generally less problematics
- Time complexity is O(n<sup>2</sup>) for general data objects
- Density-based methods only require a distance measure
- Border points make DBSCAN dependent on processing order
- No cluster model or parameter optimization
- Assigning new points is done with nearest neighbor classification

#### Hawkins' Definition [Hawkins 1980]:

"An outlier is an observation which deviates so much from other observations as to arouse suspicions that it was generated by a different mechanism."

#### What does "mechanism" mean?

• intuition from Bayesian statistics:

"Outliers have a small likelihood to be generated by the assumed generative model."

- connection to clustering:
  - a clustering describes the distribution of data
  - outliers describe errors/noise
  - $\Rightarrow$  max. distance to all cluster centers (part. clustering)
  - $\Rightarrow$  noise in density-based clustering

### Example: distance-based Outliers

- Definition "(pct,dmin)-Outlier" [Knorr, Ng 97]
  - An object *p* in data set *DB* is called (*pct,dmin*)-outlier, if at least *pct* percent of the objects from *DB* have a large distance to p then *dmin*.
- Selection of *pct* and *dmin* is left to the user
- <u>example:</u> *p*<sup>1</sup> ∈ *DB*, *pct=*0.95, *dmin=*8
- p1 is a (0.95,8)-outlier
   => 95% of objects in DB display a distance > 8 to p1



## **Frequent Pattern Mining**

until now: patterns describe subsets of DB

- idea: patterns might be parts of object description
- **here**: patterns are identical parts in object descriptions from large subsets of DB
- **example**: group composition in MMORPG:

Grp1	priest, mage, druid, rogue, warrior
Grp3	mage, mage, hunter, priest, warrior
Grp3	Priest, priest, paladin, druid, warrior
Grp4	warlock, paladin, shaman, <u>warrior, prie</u> s
Grp5	priest, warrior, hunter, rogue, warrior

- warrior, priest,?,?,?

# **Directions in Frequent Pattern Mining**

- Frequent Itemset Mining (=> KDD1 and in the following) objects are subsets of items => find frequent subsets
- Frequent Substring Mining (=> next chapter) data objects are string/sequences over a discrete alphabet => find frequent subsequences
- Frequent Subgraph Mining (=> KDD2) data objects are graphs with discrete labels for nodes and/or edges => find frequent groups of isomorphic subgraphs
- **Rule Mining**: find rules based on frequent patterns: If pattern A is present in a data object, then its extension A+B is present with likelihood p.

### Basic on Frequent Itemsets (1)

- items I = {i<sub>1</sub>, ..., i<sub>m</sub>} is a set of literals
   e.g., all articles in a shop
- **itemset** *X*: subset of items  $X \subseteq I$

e.g., a set of items purchased together

• **transaction**  $T = (tid, X_T)$  where tid is the transaction ID and  $X_T \subseteq I$  is the complete itemset in the transaction

e.g., all items being purchased together and the corresponding invoice number

• **database** *DB*: set of transactions *T* 

e.g., the set of all purchases in a certain time interval

• Items in itemsets can be sorted **lexicographical**:

itemset  $X = (x_1, x_2, ..., x_k)$ , where  $x_1 \le x_2 \le ... \le x_k$ 

- length of an itemset: |X|: number of items in X
- *k*-ltemset: an itemset of length *k*

{butter, bread, milk, sugar} is a 4-itemset {flour, sausage} is a 2-itemset

## Basics on Frequent Itemsets(2)

- **cover** of itemset X: set of transactions T containing X :  $cover(X) = \{tid \mid (tid, X_T) \in DB, X \subseteq X_T\}$
- **support of itemsets** *X* in *DB*: number of transactions containing X:

support(X) = |cover(X)|

remark:  $support(\emptyset) = |DB|$ 

• **frequency of itemsets** *X* in *DB*:

relative frequency of X being contained in any  $T \in DB$ : frequency(X) = P(X) = support(X) / |DB|

• **frequent itemset** *X* in *DB*:

 $support(X) \ge s$   $(0 \le s \le |DB|)$ 

*s* is an absolute threshold alternative:  $frequency(X) \ge s_{rel}$ 

where  $s = [s_{rel} \cdot IDB]$ 

### problem setting : Frequent Itemset Mining

#### given:

- a set of items I
- a transaction database DB over I
- an absolute frequency threshold s

**task**: find all frequent itemsets in *DB*, i.e.  $\{X \subseteq I \mid support(X) \ge s\}$ 

TransaktionsID	Items
2000	A,B,C
1000	A,C
4000	A,D
5000	B,E,F

support of 1-itemsets:

(A): 75%, (B), (C): 50%, (D), (E), (F): 25%,

support of 2-itemsets:

(A, C): 50%,

(A, B), (A, D), (B, C), (B, E), (B, F), (E, F): 25%

## Itemset Mining

Apriori Algorithm [Agrawal & Srikant 1994]

 start by computing 1-itemsets, 2-itemsets and so on. (breadth-first search)



- find all frequent *k*+1-itemsets:
  - Consider only those *k*+1 itemsets for which all *k*-itemsets are frequent
- Determine support by scanning all transactions in DB (only one Scan)

# Apriori Algorithm

 $C_k$ : candidate set of potentially frequent items of length k

 $L_k$ : set of all frequent itemsets of length k

```
\begin{aligned} & \text{Apriori}(I, DB, minsup) \\ & L_1 := \{\text{frequent 1-ltemsets aus } I\}; \\ & k := 2; \\ & \text{while } L_{k-1} \ ^1 \oslash \text{do} \\ & C_k := \text{AprioriCandidateGeneration } (L_{k-1}); \\ & \text{for each Transaktion } T \in DB \text{ do} \\ & CT := \text{Subset}(C_k, T); // \text{ all candidates } C_k \text{ contained in T} \\ & \text{for each candidate } c \in CT \text{ do} \\ & c.count++; \\ & L_k := \{c \in C_k \mid c.count \ge minsup\}; \\ & k++; \end{aligned}
```

return  $\bigcup_k L_k$ ;

## candidate generation(1)

requirements to candidate itemsets:

- $C_k \supseteq L_k$
- $|C_k|$  should be much smaller then the set of all possible k-itemsets

#### step 1: Join

- p and q are frequent (k-1)-itemsets
- join p and q if they share a common (k-2)-prefix

$$p \in L_{k-1}$$
 (beer, chips, pizza)  
(beer, chips, pizza, wine)  $\in C_k$   
 $q \in L_{k-1}$  (beer, chips, wine)

# Candidate generation(2)

step2: pruning remove all candidate k-itemsets containing non-frequent k-1-itemsets

example:

 $\mathsf{L}_3 = \{(1\ 2\ 3),\ (1\ 2\ 4),\ (1\ 3\ 4),\ (1\ 3\ 5),\ (2\ 3\ 4)\}$ 

after join step: candidates = {(1 2 3 4), (1 3 4 5)} pruning step:

delete (1 3 4 5) since (1 4 5) is not frequent =>  $C_4 = \{(1 2 3 4)\}$ 

# **Example Apriori Algorithms**



## What you should know by now

- What is data mining and KDD?
- Steps in the KDD process
- What is supervised learning?
  - linear regression
  - kNN Classification
  - Bayesian learning
  - metrics for supervised learning
- What is unsupervised learning?
  - clustering (k-means, DBSCAN)
  - outlier detection (distance-based outliers)
  - frequent pattern mining (frequent itemset mining ,apriori algorithm)

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