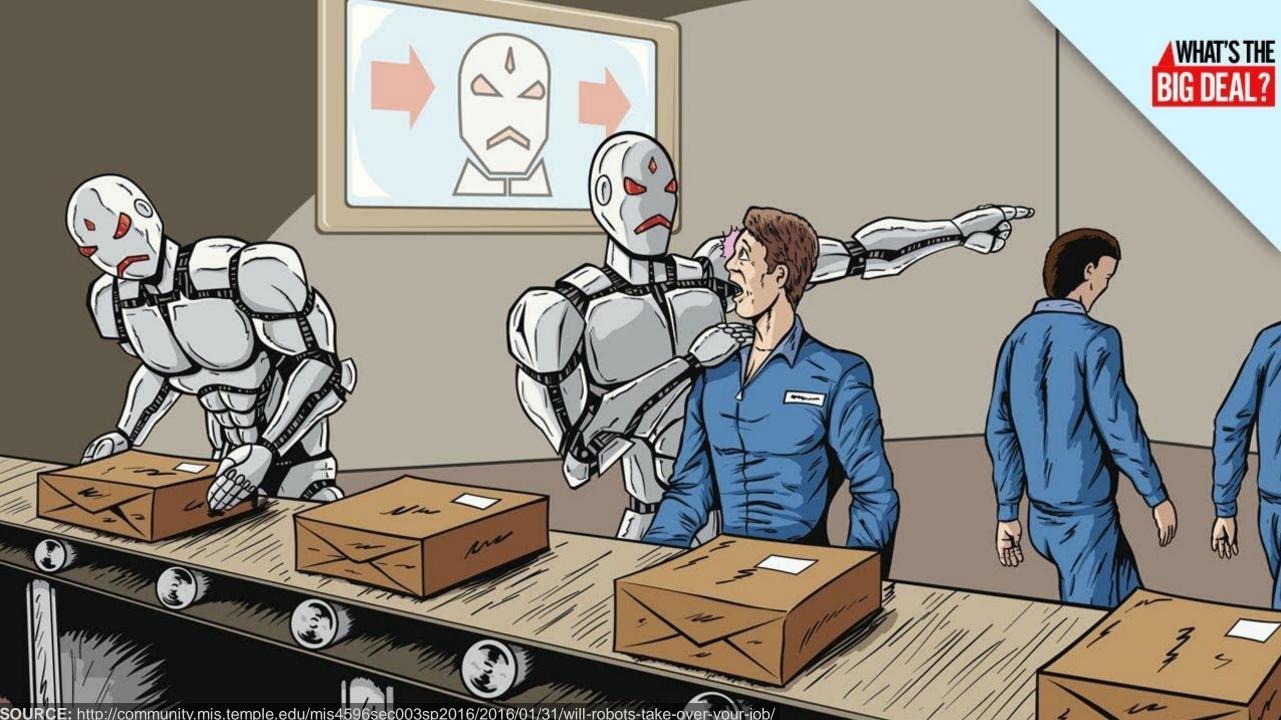


# **Deep Learning**

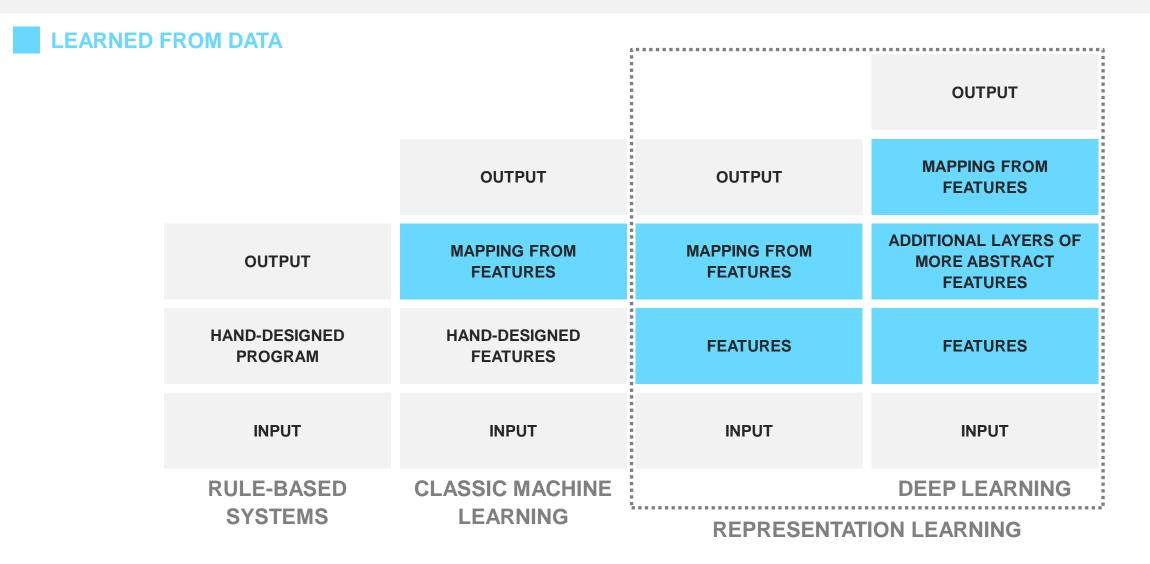
Sigurd Spieckermann Siemens Corporate Technology



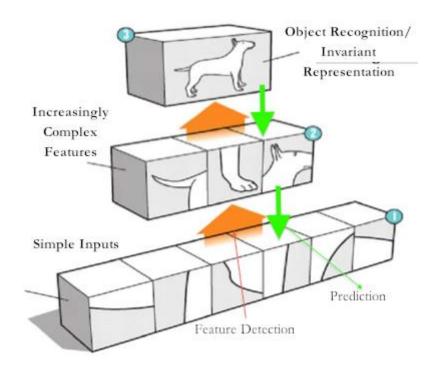


## OK, LET'S GET SERIOUS NOW ...

#### **Deep Learning vs. Classic Data Modeling**

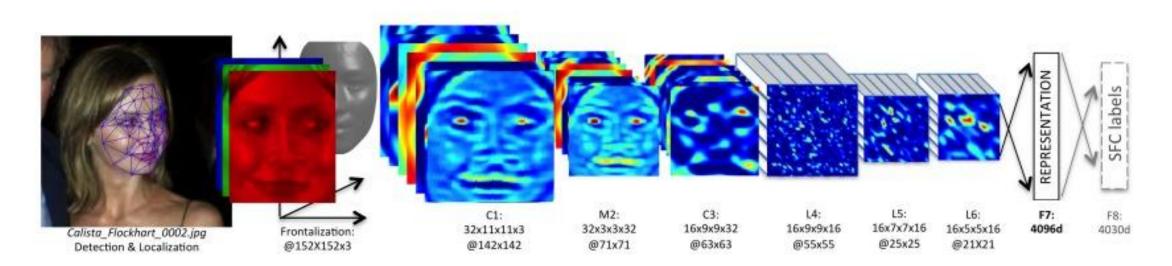


#### **Deep Learning Hierarchical Feature Extraction**



#### **Deep Learning Hierarchical Feature Extraction**

# facebook.

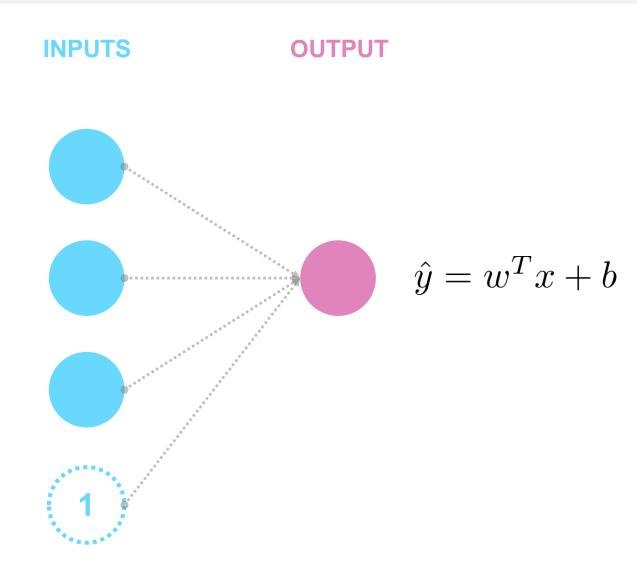


#### SOURCE:

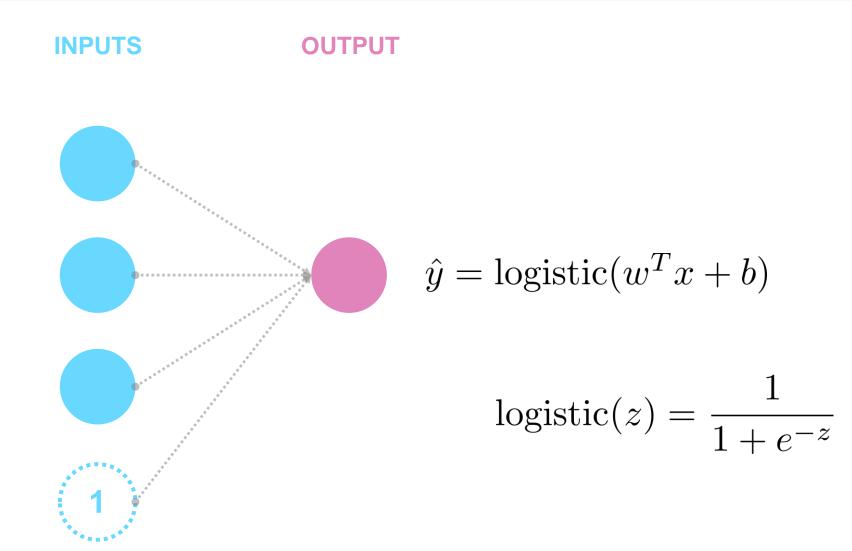
Taigman, Y., Yang, M., Ranzato, M. A., & Wolf, L. (2014). DeepFace: Closing the gap to human-level performance in face verification. In *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition* (pp. 1701-1708).

## **NEURAL NETWORKS**

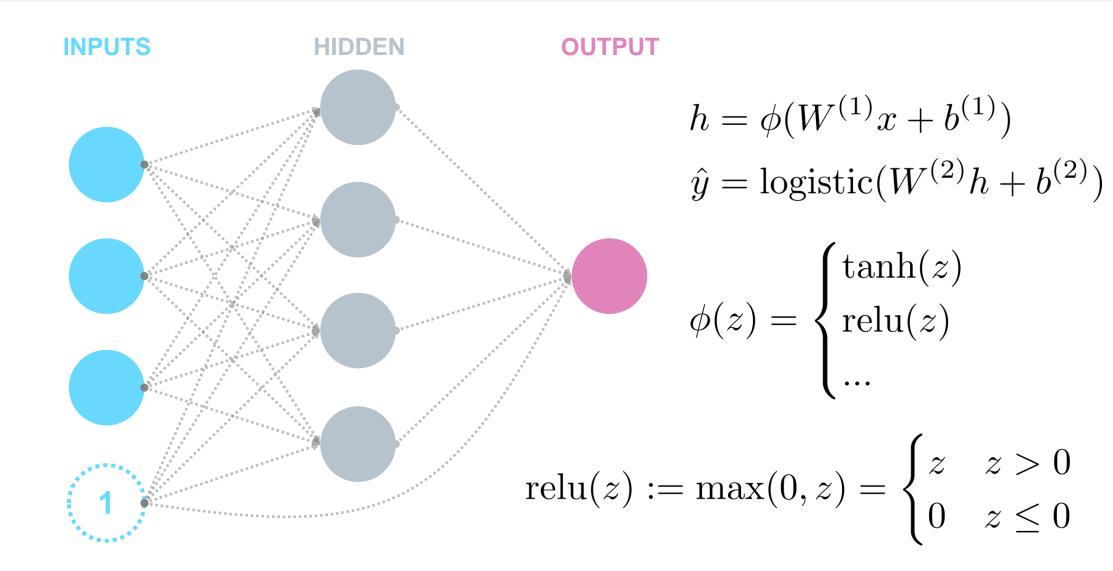
#### Neural Networks Linear Regression



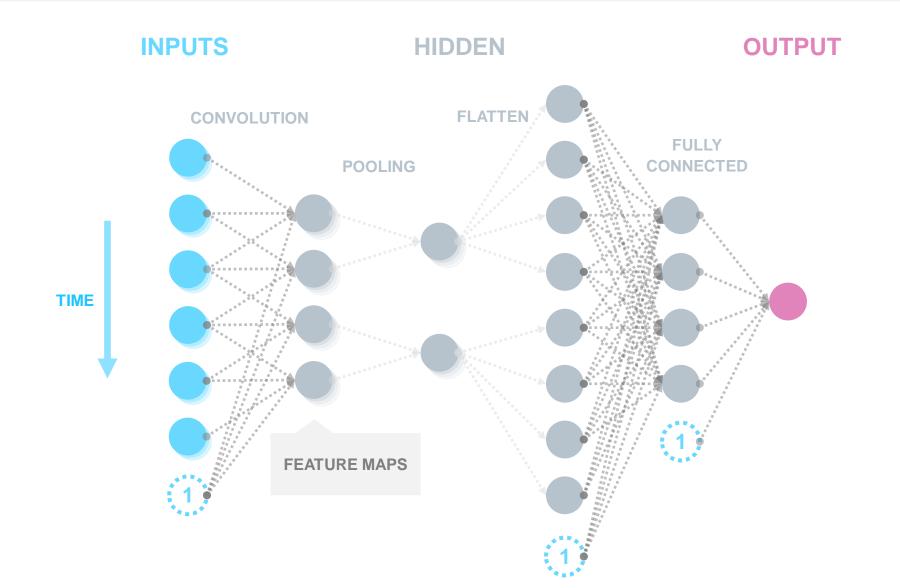
#### Neural Networks Logistic Regression

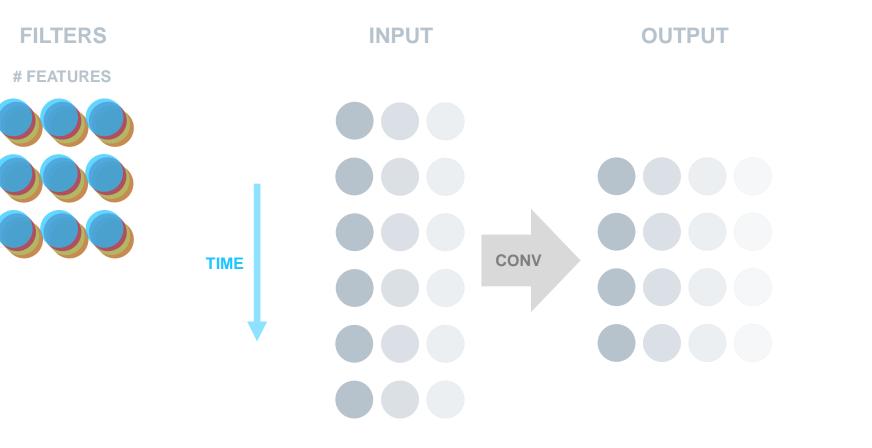


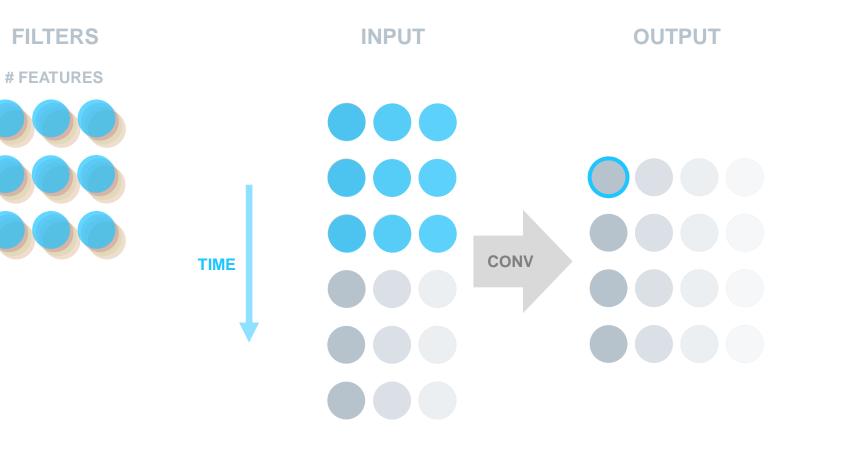
## Neural Networks Fully Connected Feedforward Neural Network

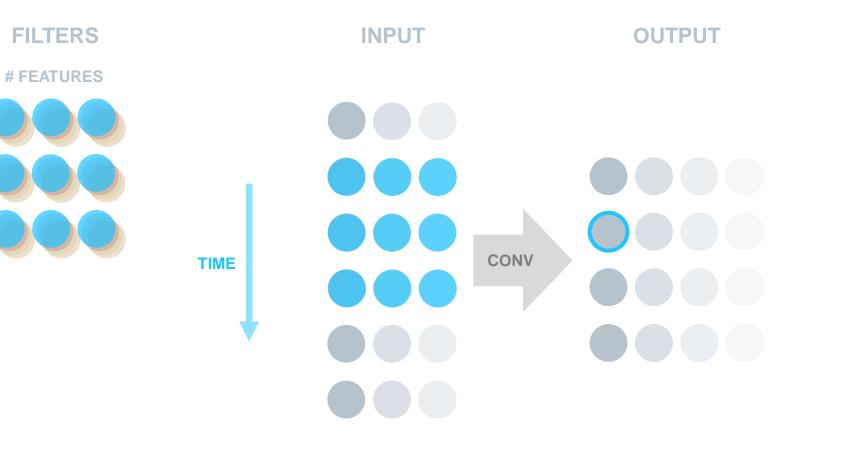


#### Neural Networks 1D Convolutional Feedforward Neural Network

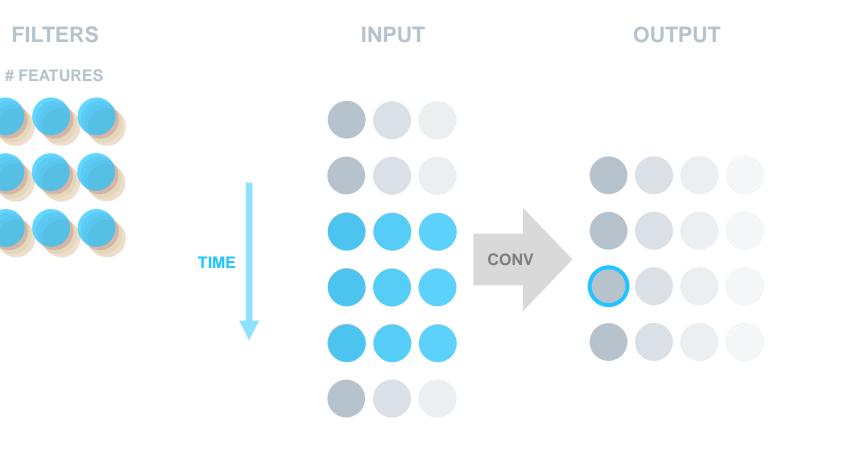


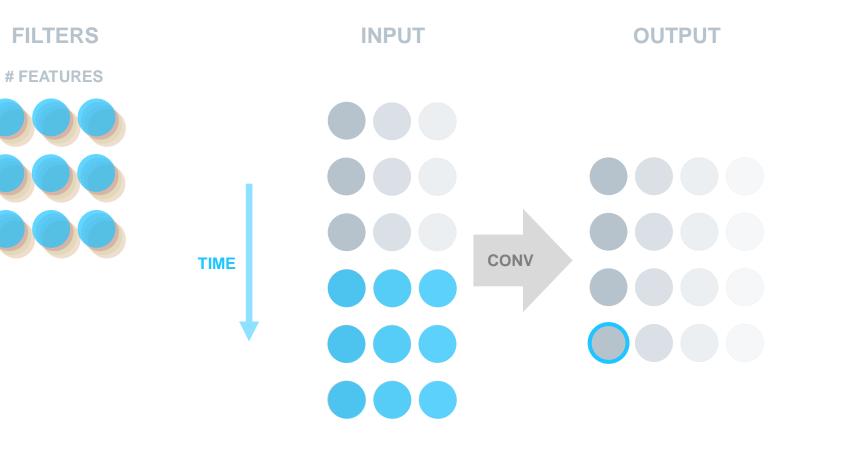




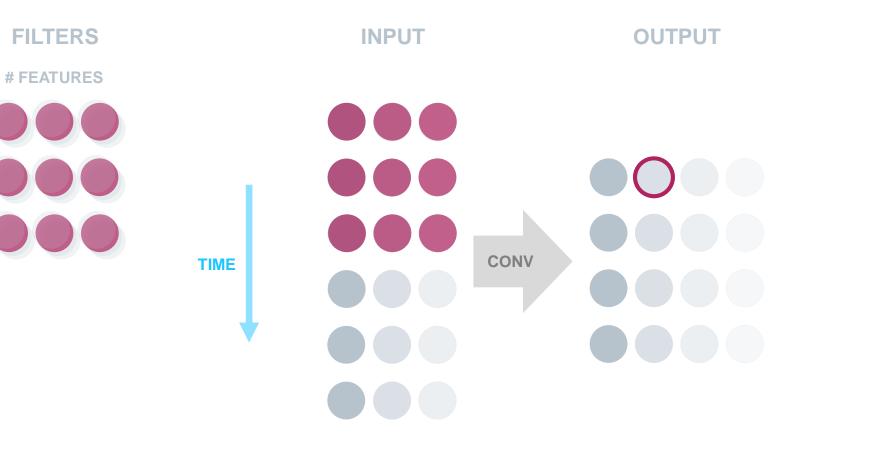


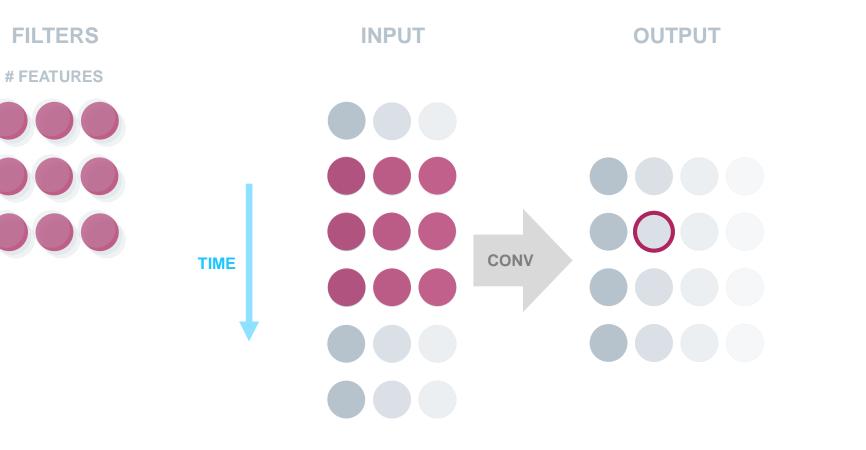
2016/06/01

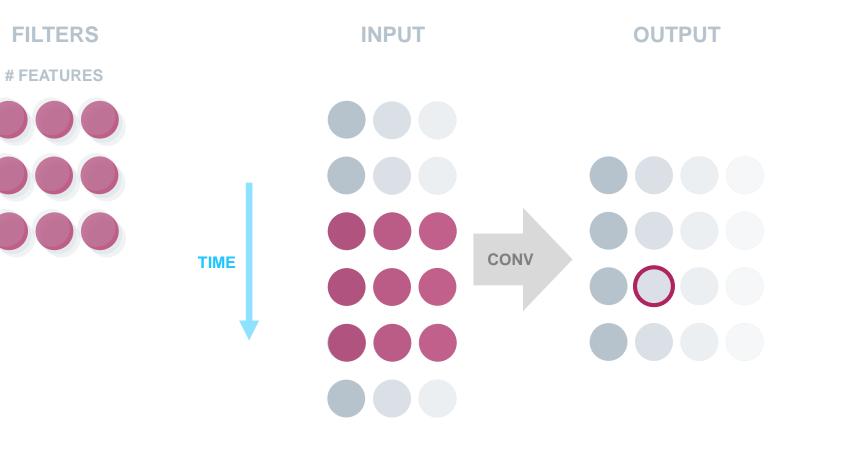


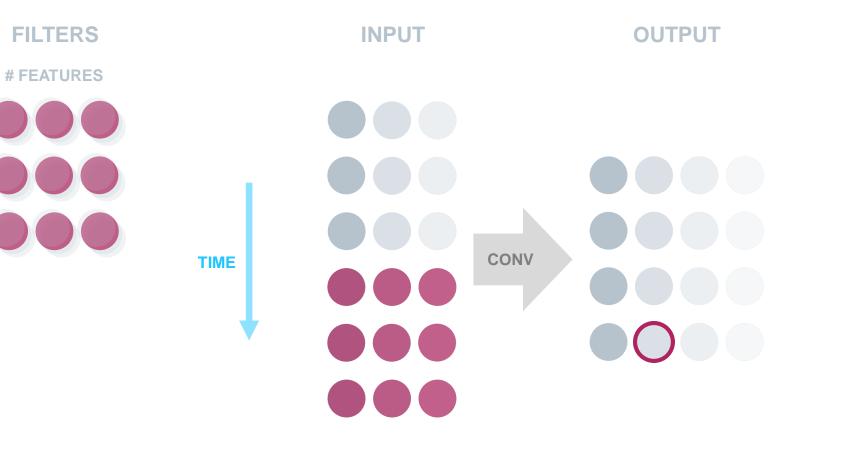


2016/06/01



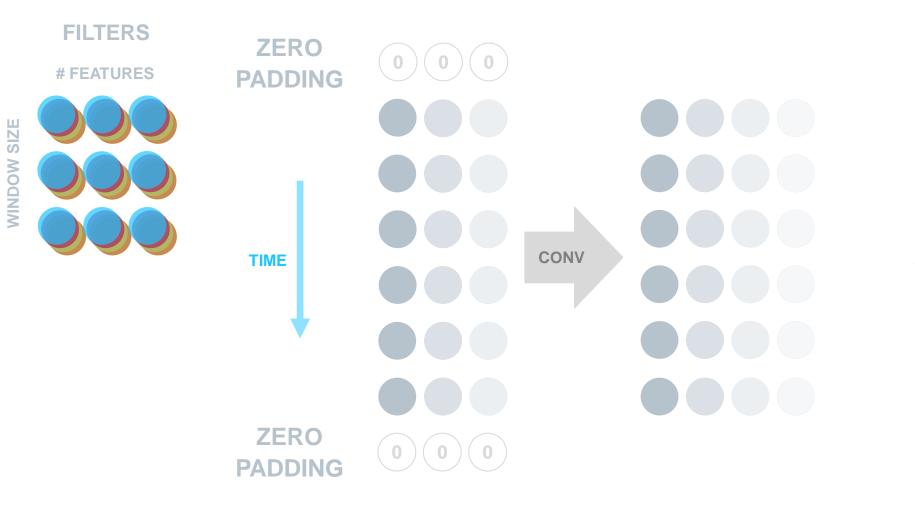




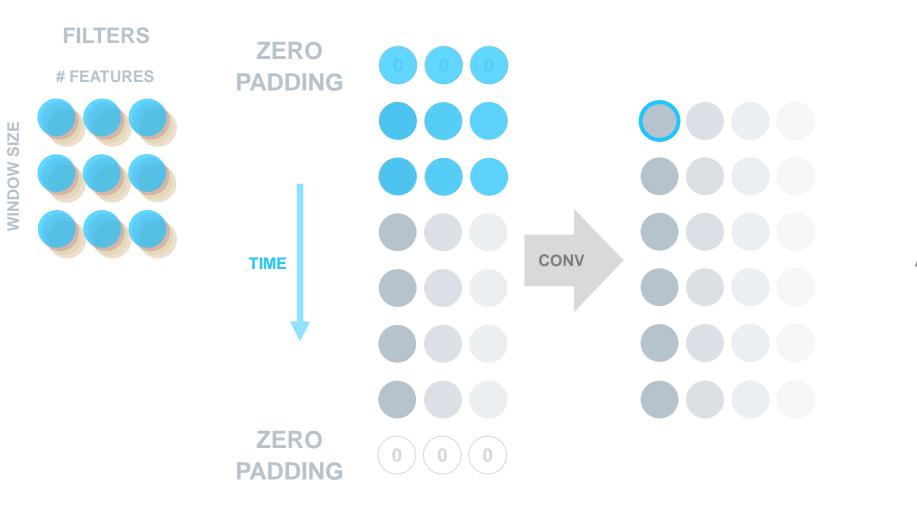


WINDOW SIZE

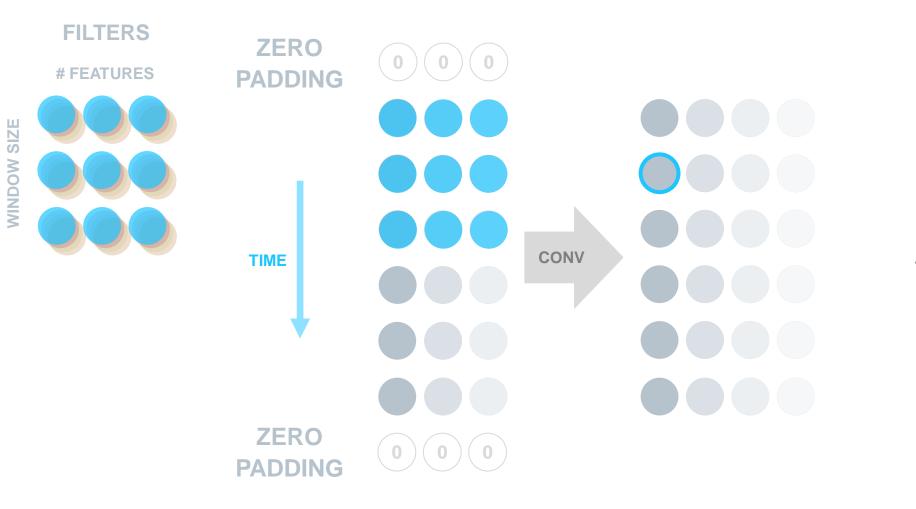




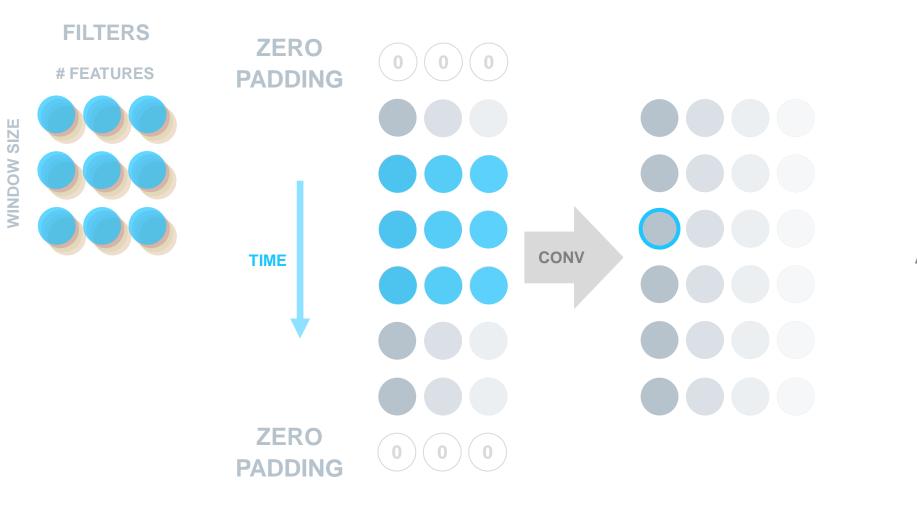
NOTE THAT THE INPUT AND OUTPUT SEQUENCES HAVE THE SAME LENGTH



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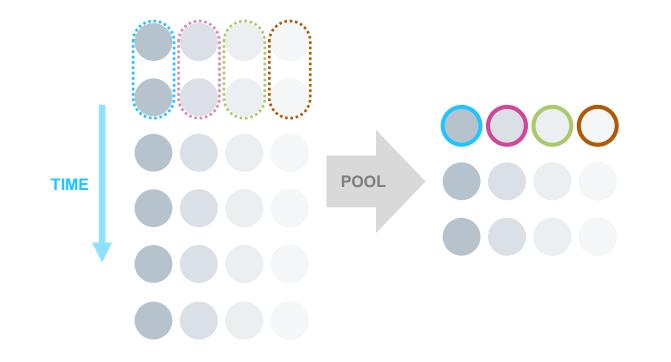
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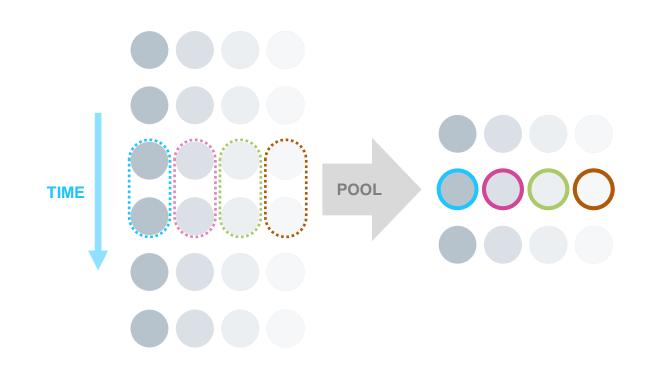
NOTE THAT THE INPUT AND OUTPUT SEQUENCES HAVE THE SAME LENGTH



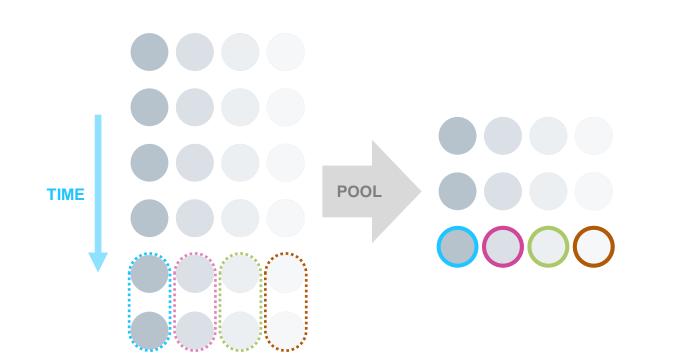
NOTE THAT THE INPUT AND OUTPUT SEQUENCES HAVE THE SAME LENGTH Neural Networks 1D Pooling (max, sum, average, ...)



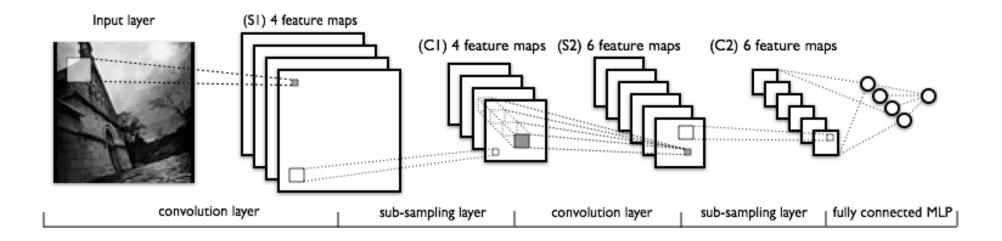
Neural Networks 1D Pooling (max, sum, average, ...)



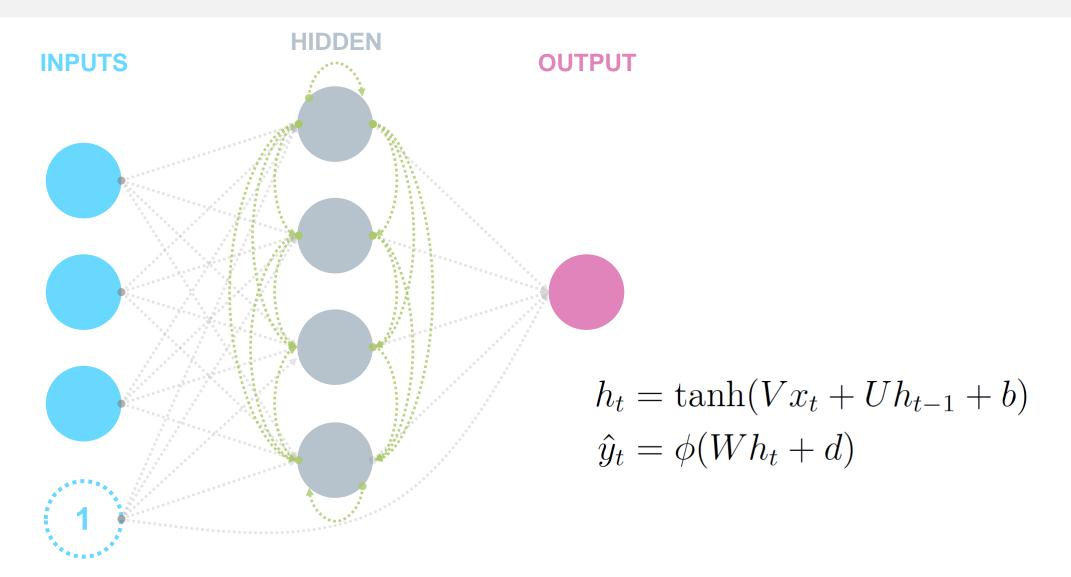
Neural Networks 1D Pooling (max, sum, average, ...)



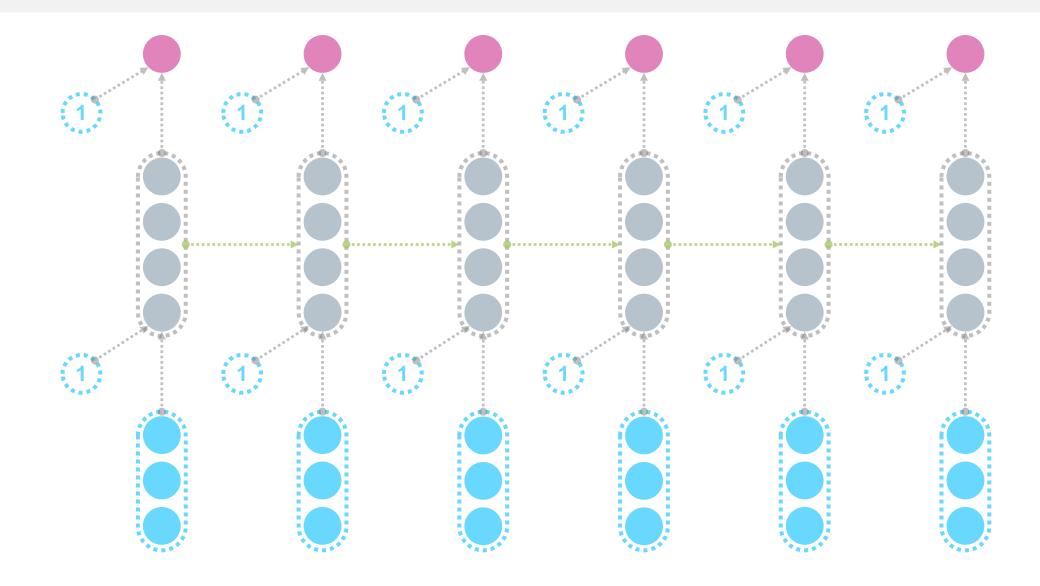
#### Neural Networks 2D Convolutional Feedforward Neural Network



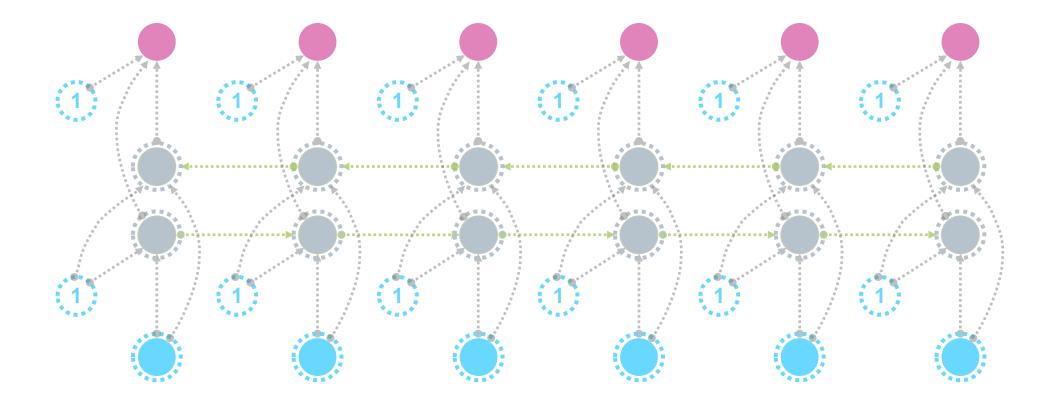
## Neural Networks Recurrent Neural Network (Elman architecture)



## Neural Networks Recurrent Neural Network (Elman architecture, unfolded)



## Neural Networks Bi-Directional Recurrent Neural Network (Elman architecture, unfolded)



## NEURAL NETWORKS HAVE BEEN AROUND FOR DECADES! SO WHAT'S NEW?

#### What's new?

#### **OPTIMIZATION & LEARNING**

#### **OPTIMIZATION ALGORITHMS**

- AdaGrad
- AdaDelta
- Adam
- RMSProp
- Hessian-Free Optimization
- ....

#### REPARAMETERIZATION

- Batch Normalization
- Weight Normalization
- •

#### REGULARIZATION

- Dropout
- DropConnect
- ...

#### **MODEL ARCHITECTURES**

#### **BUILDING BLOCKS**

- Spatial/Temporal Pooling
- Attention Mechanism
- Gated Recurrent Units
- Beam-search for sequence generation
- Variable-length sequence modeling
- •

#### ARCHITECTURES

- Inception (Google)
- VGG (Oxford University)
- Encoder-Decoder Framework
- End-to-end Models
- ....

#### SOFTWARE

- Theano
  - Blocks + Fuel
  - Keras
  - Lasagne
  - PyLearn2\*
- TensorFlow
- Torch7
- Caffe...

#### GENERAL

- GPUs
- Data

\* deprecated

# **OPTIMIZATION & LEARNING**

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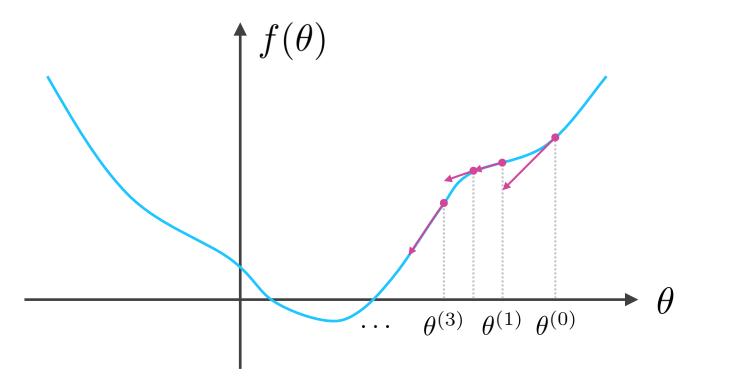
# GENERAL

- GPUs
- Data

deprecated

- Neural networks are composed of differentiable building blocks
- Training a neural network means minimization of some non-convex differentiable cost function using iterative gradient-based optimization methods

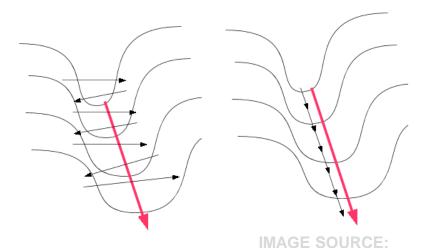
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- Gradients are computed using backpropagation
- The simplest optimization algorithm is "gradient descent"

$$\theta^{(i+1)} \leftarrow \theta^{(i)} - \eta \nabla_{\theta^{(i)}} f(\theta^{(i)})$$

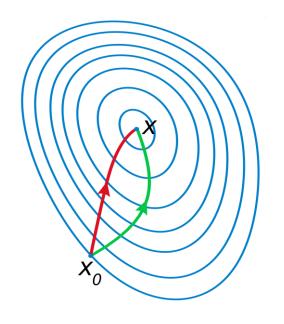
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- ... but it has limitations



Martens, J. (2010). Deep Learning via Hessian-Free Optimization. In *Proceedings* of the 27th International Conference on Machine Learning (pp. 735-742).

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- Training a neural network means minimization of some non-convex differentiable cost function using iterative gradient-based optimization methods
- Gradients are computed using backpropagation
- The simplest optimization algorithm is "gradient descent"
- ... but it has limitations
- Information about the local curvature of the cost function helps to adjust the direction and magnitude of the gradient for better progress (along the lines of Newton's method)
- Exact local curvature is infeasible to compute
- Recent optimization algorithms like AdaGrad, RMSProp, AdaDelta etc. try to approximate local curvature information efficiently

 First-order gradient-based optimization methods are not invariant to reparameterization of the optimization objective

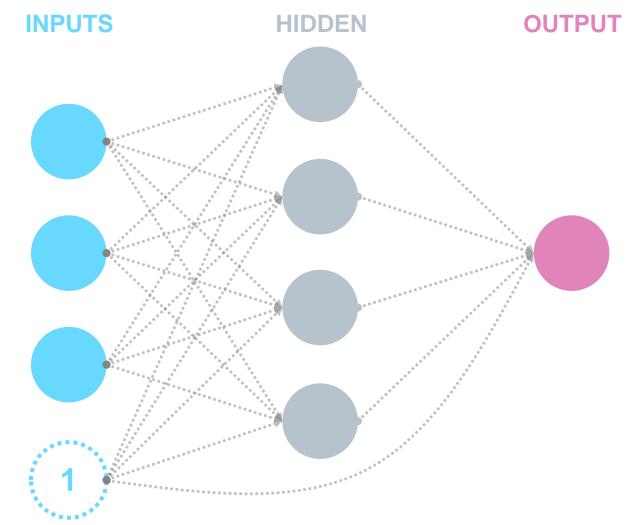


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- Instead of using more sophisticated optimization algorithms that are better at dealing with ill-conditioned optimization problems, reparameterize the objective function so that simpler optimization algorithms work better

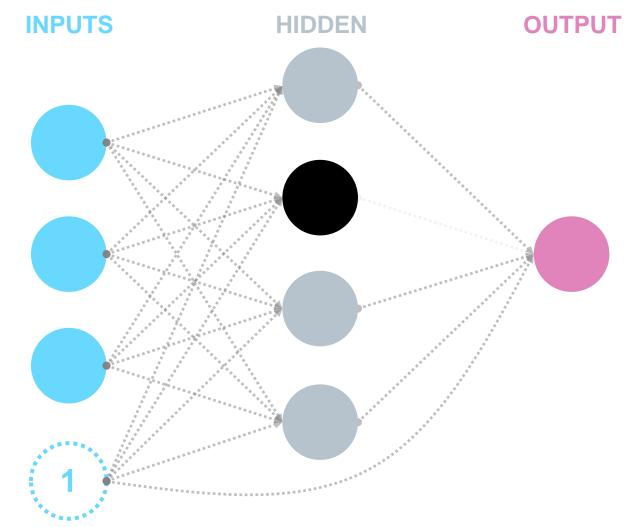
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- Why not do this in each (hidden) layer as well?
  - $\Rightarrow$  Batch Normalization

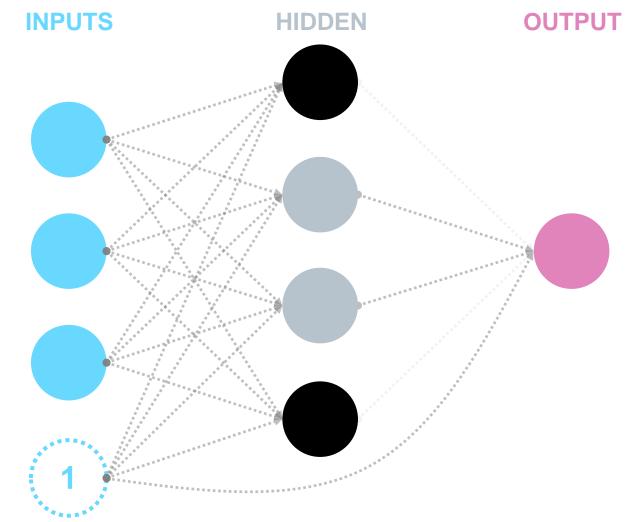
- Randomly set neurons to zero
- Results in an ensemble with an exponential number of members whose parameters are shared
- Primarily used in fully connected layers because of the large number of parameters
- Rarely used in convolutional layers
- Rarely used in recurrent neural networks (if at all between the hidden state and output)



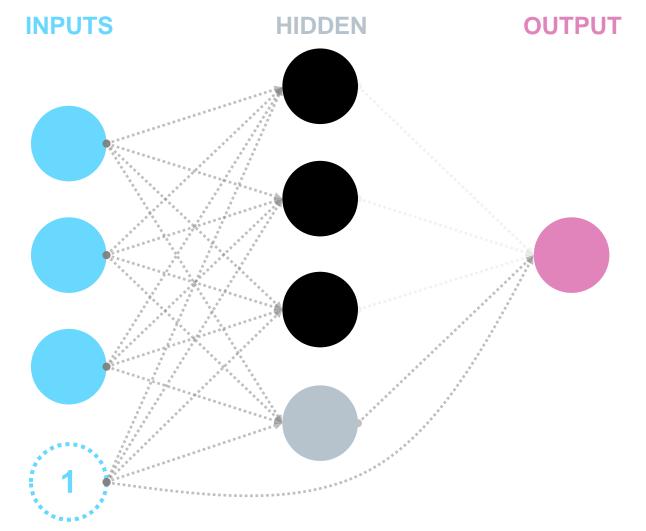
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- RMSProp
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- •

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# **GENERAL**

- GPUs
- Data

### deprecated

# What's new? Attention Mechanism in Image Caption Generation



A woman is throwing a <u>frisbee</u> in a park.



A dog is standing on a hardwood floor.



A <u>stop</u> sign is on a road with a mountain in the background.



A little <u>girl</u> sitting on a bed with A g a teddy bear. in t

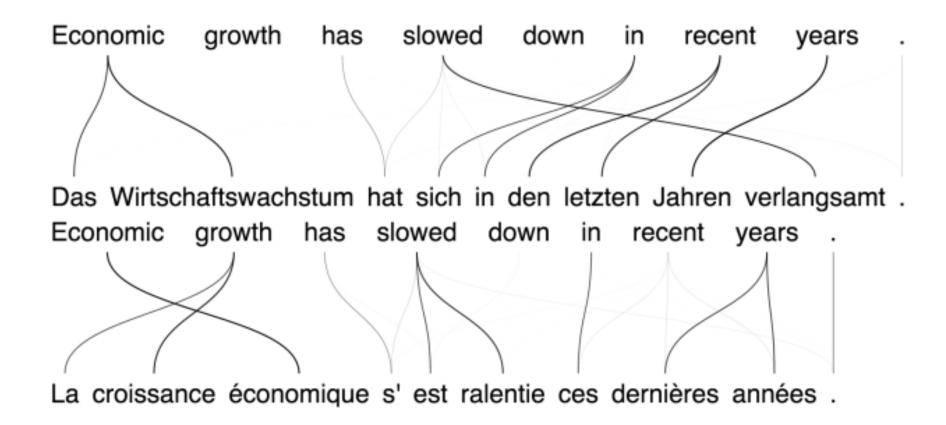
A group of <u>people</u> sitting on a boat in the water.

A giraffe standing in a forest with trees in the background.

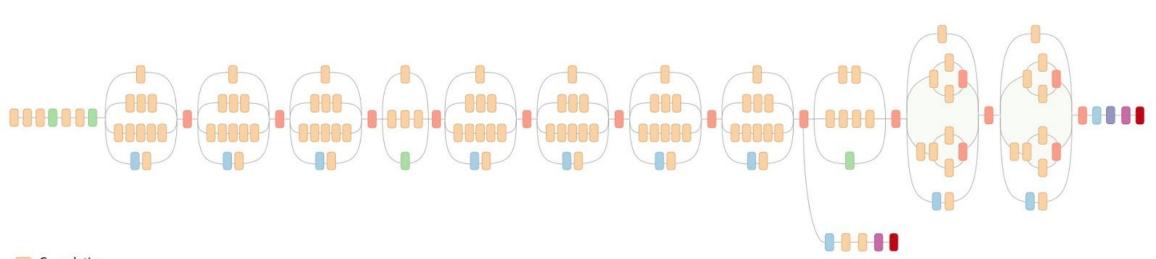
### SOURCE

Xu, K., Ba, J., Kiros, R., Cho, K., Courville, A., Salakhudinov, R., ... & Bengio, Y. (2015). Show, Attend and Tell: Neural Image Caption Generation with Visual Attention. In Proceedings of The 32nd International Conference on Machine Learning (pp. 2048-2057).

# What's new? Attention Mechanism in Text Translation



# What's new? Inception Architecture

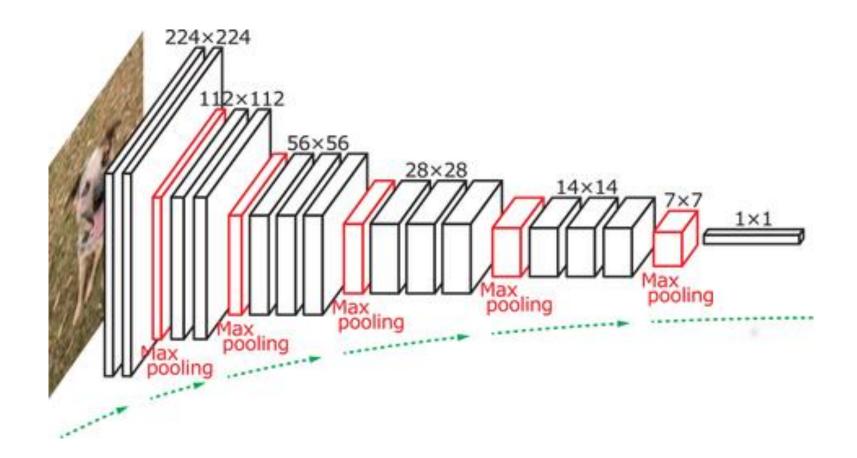


Convolution
AvgPool
MaxPool
Concat
Dropout
Fully connected
Softmax

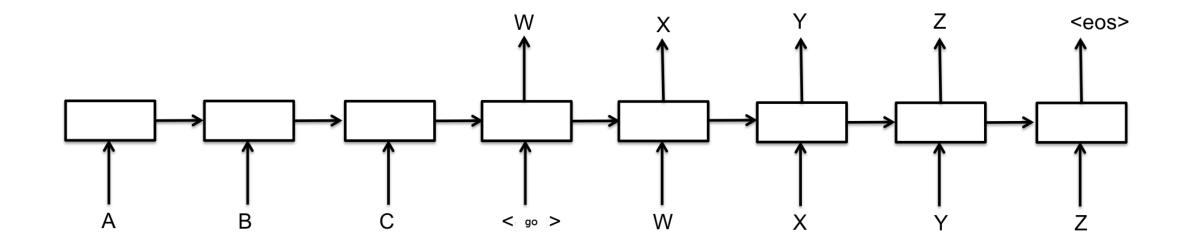
Google

# What's new? VGG-16 Architecture

- Filter size 3×3
- 2+ successive convolutions with before pooling instead of the common CONV → POOL chain
- Convolution mode "half"
- More layers  $\Rightarrow$  larger capacity
- Parameter-efficient due to small filters



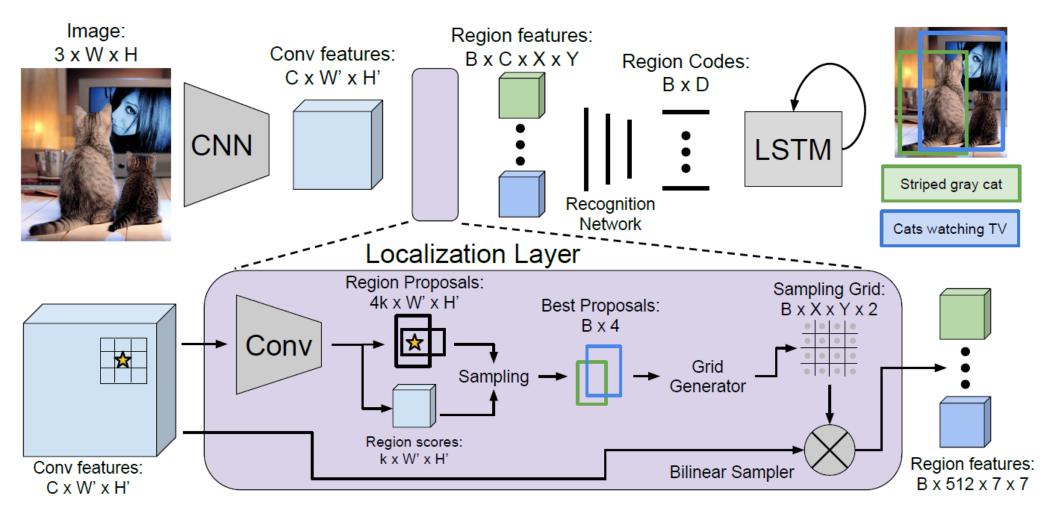
# What's new? Encoder-Decoder Framework



SOURCE: https://www.tensorflow.org/versions/r0.8/tutorials/seq2seq/index.html#sequence-to-sequence-models

# What's new? End-to-end model (object recognition)



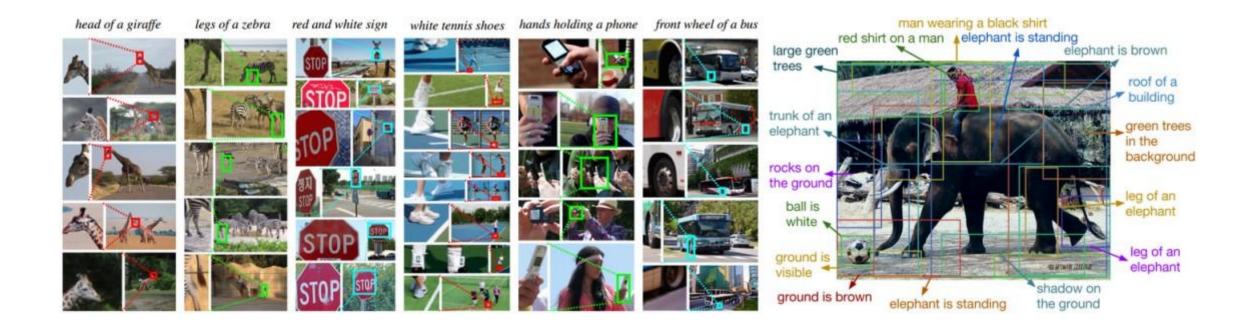


SOURCE:

Johnson, J., Karpathy, A., & Fei-Fei, L. (2015). DenseCap: Fully Convolutional Localization Networks for Dense Captioning. *arXiv preprint arXiv:1511.07571*.

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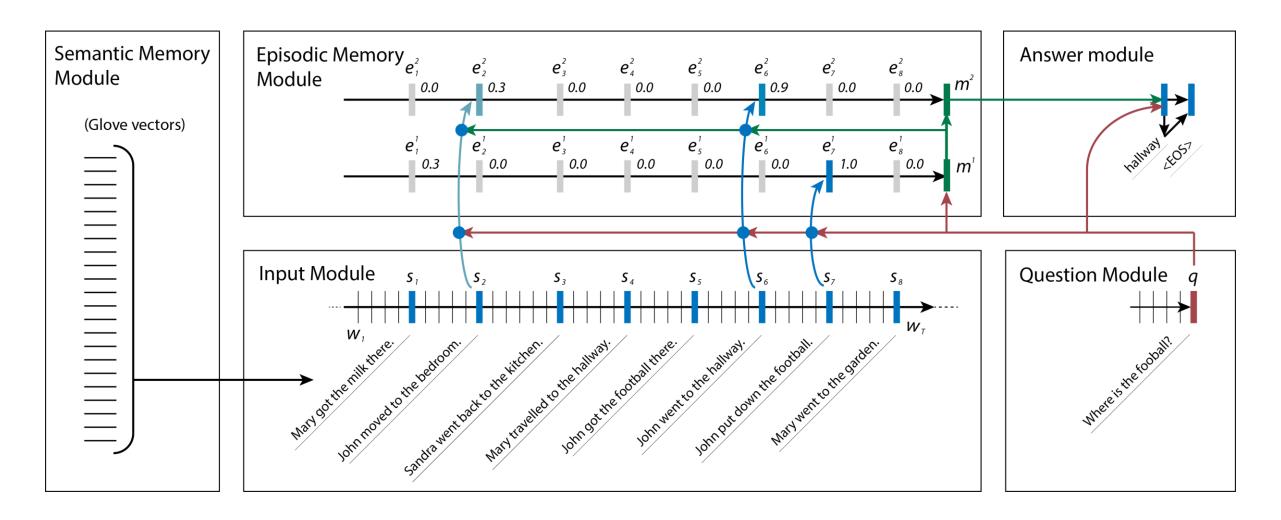




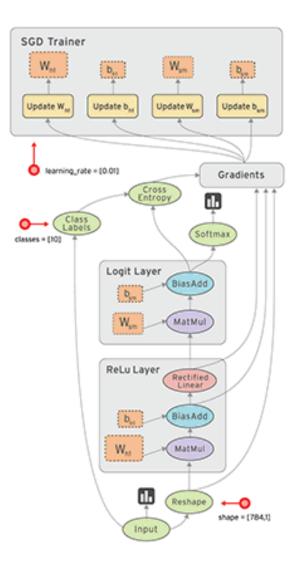
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# What's new? End-to-end model (question answering) Meta



# **Data Flow Graphs / Computation Graphs**



# **OPTIMIZATION & LEARNING**

# **OPTIMIZATION ALGORITHMS**

- AdaGrad
- AdaDelta
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- RMSProp
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# REPARAMETERIZATION

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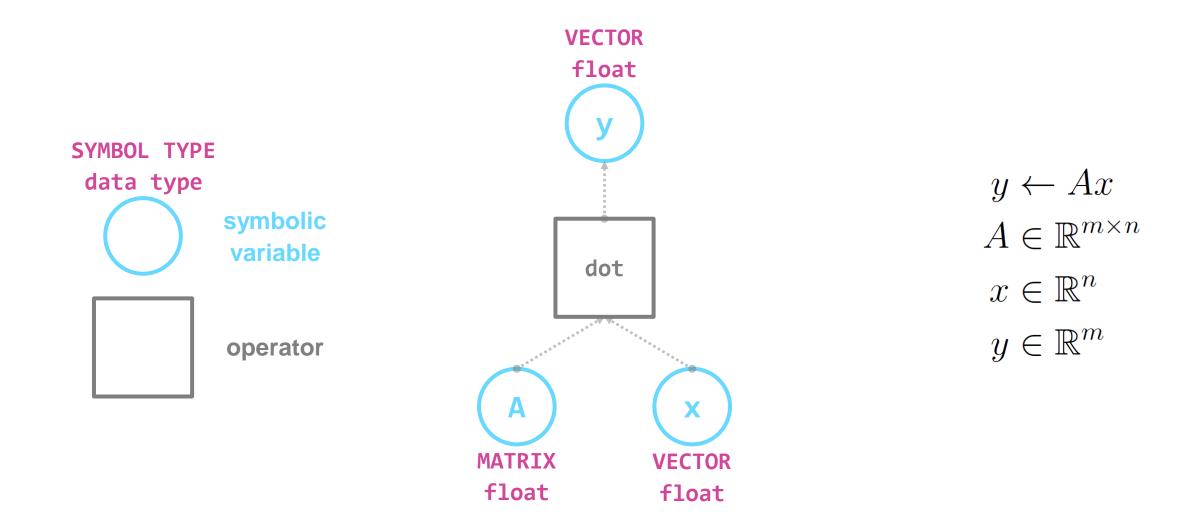
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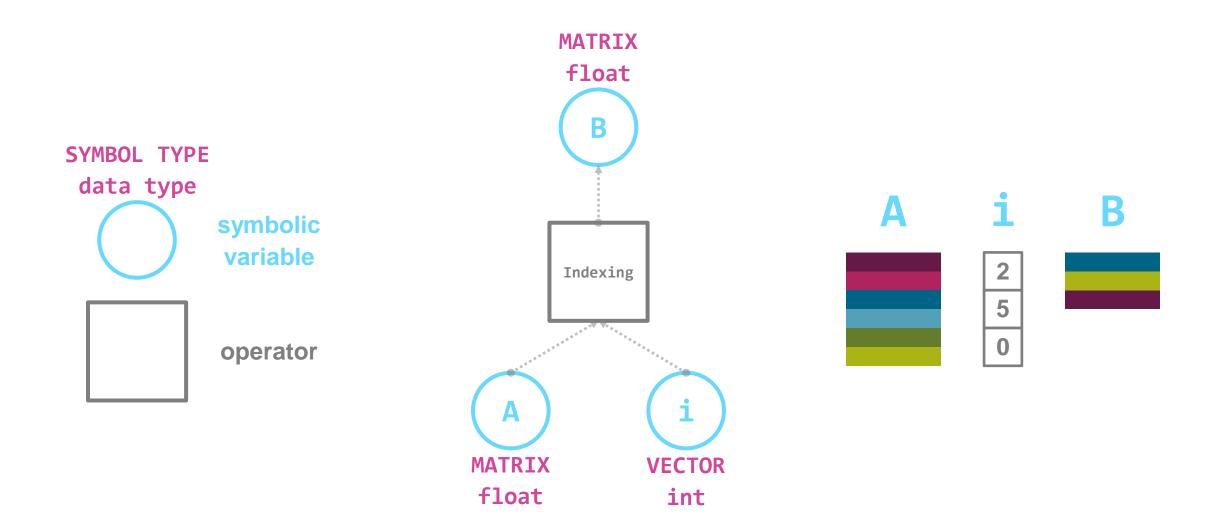
- GPUs
- Data

### \* deprecated

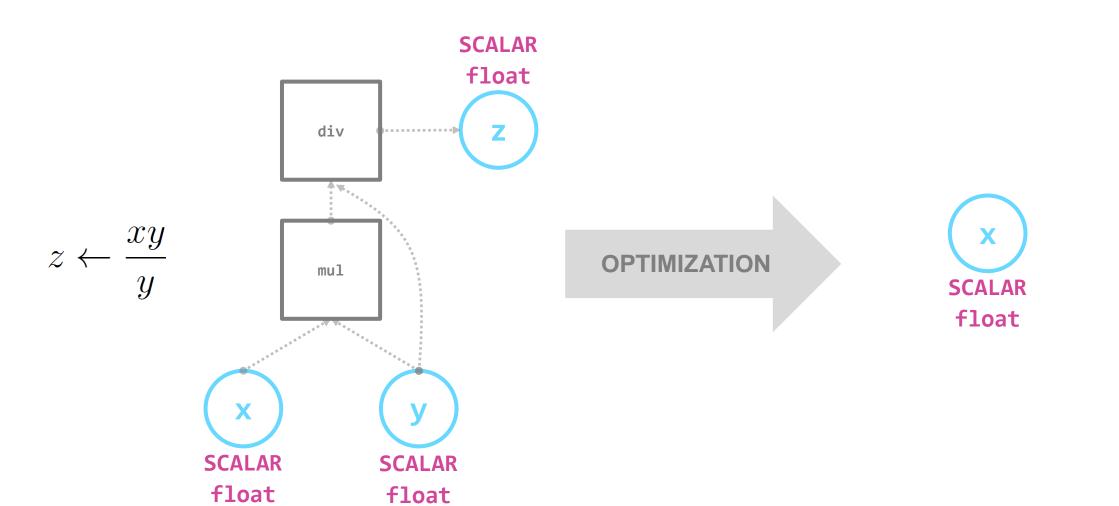
**Matrix-Vector Multiplication** 



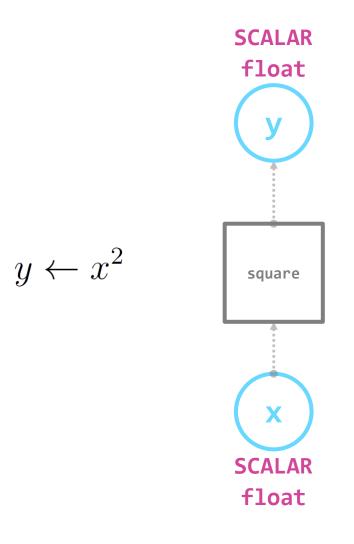
# Computation Graphs Indexing



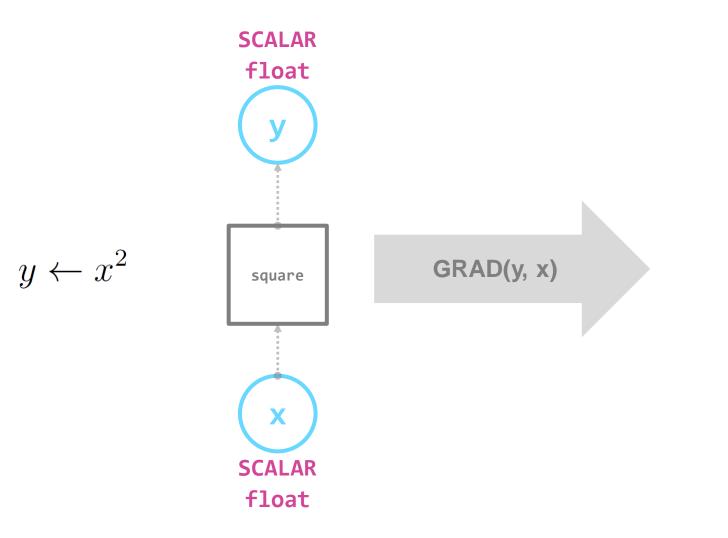
# Computation Graphs Graph Optimization



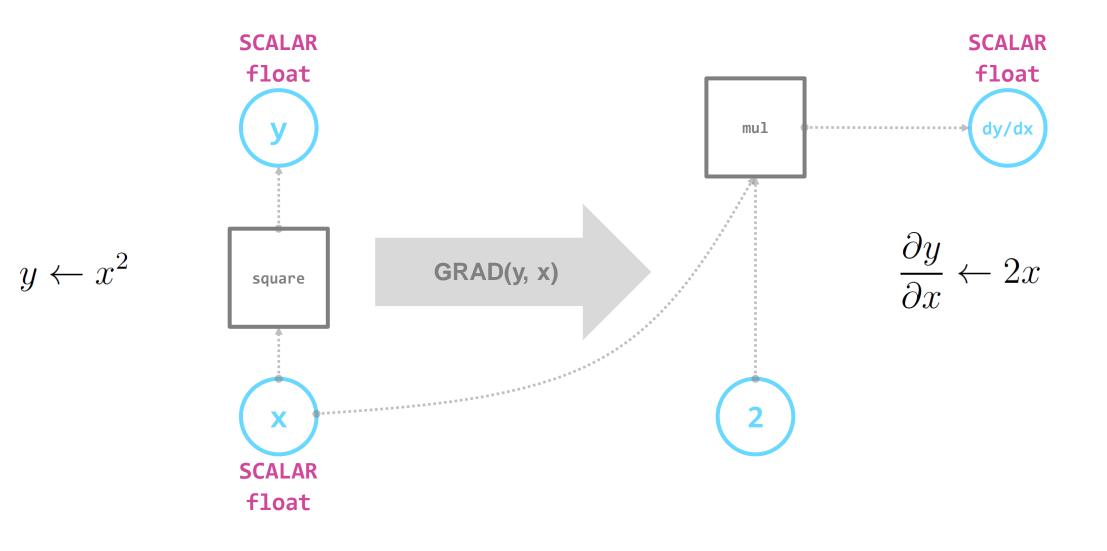
**Automatic Differentiation** 



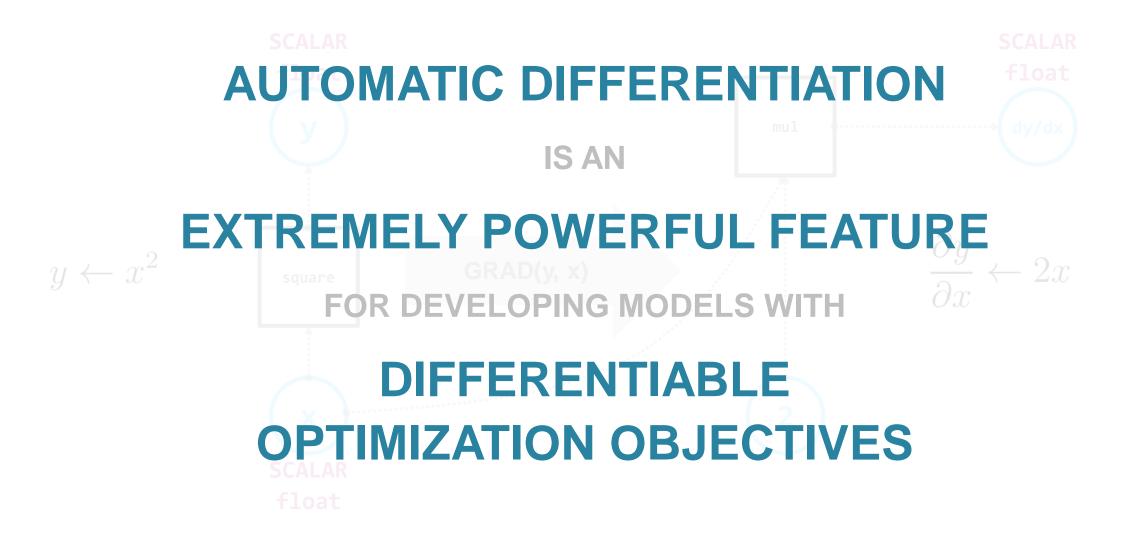
**Automatic Differentiation** 



**Automatic Differentiation** 



**Automatic Differentiation** 



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# GENERAL

- GPUs
- Data

# GPUS



# <u>DEEP</u> LEARNING is <u>NOT</u> only meant literally, but more importantly it is about learning solutions to problems in a fully automated way.

### Module 1: Neural Networks

Image Classification: Data-driven Approach, k-Nearest Neighbor, train/val/test splits

L1/L2 distances, hyperparameter search, cross-validation

Linear classification: Support Vector Machine, Softmax

parameteric approach, bias trick, hinge loss, cross-entropy loss, L2 regularization, web demo

Optimization: Stochastic Gradient Descent

optimization landscapes, local search, learning rate, analytic/numerical gradient

Backpropagation, Intuitions

chain rule interpretation, real-valued circuits, patterns in gradient flow

Neural Networks Part 1: Setting up the Architecture

model of a biological neuron, activation functions, neural net architecture, representational power

Neural Networks Part 2: Setting up the Data and the Loss

preprocessing, weight initialization, batch normalization, regularization (L2/dropout), loss functions

Neural Networks Part 3: Learning and Evaluation

gradient checks, sanity checks, babysitting the learning process, momentum (+nesterov), second-order methods, Adagrad/RMSprop, hyperparameter optimization, model ensembles

### Module 2: Convolutional Neural Networks

Convolutional Neural Networks: Architectures, Convolution / Pooling Layers

layers, spatial arrangement, layer patterns, layer sizing patterns, AlexNet/ZFNet/VGGNet case studies, computational considerations

Understanding and Visualizing Convolutional Neural Networks

tSNE embeddings, deconvnets, data gradients, fooling ConvNets, human comparisons

Transfer Learning and Fine-tuning Convolutional Neural Networks

# Course Instructors







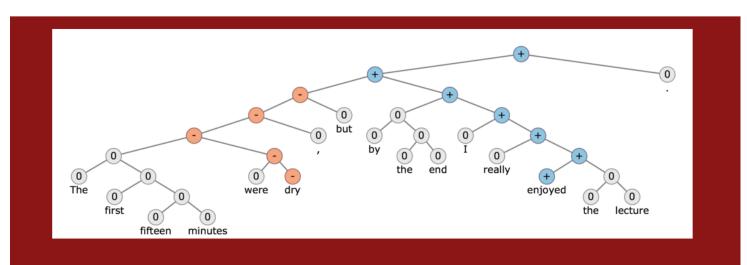
Fei-Fei Li

Andrej Karpathy

Justin Johnson

http://cs231n.stanford.edu/ http://cs231n.github.io

CS224d: Deep Learning for Natural Language Processing



### **Course Description**

Natural language processing (NLP) is one of the most important technologies of the information age. Understanding complex language utterances is also a crucial part of artificial intelligence. Applications of NLP are everywhere because people communicate most everything in language: web search, advertisement, emails, customer service, language translation, radiology reports, etc. There are a large variety of underlying tasks and machine learning models powering NLP applications. Recently, deep learning approaches have obtained very high performance across many different NLP tasks. These models can often be trained with a single end-to-end model and do not require traditional, task-specific feature engineering. In this spring quarter course students will learn to implement, train, debug, visualize and invent their own neural network models. The course provides a deep excursion into cutting-edge research in deep learning applied to NLP. The final project will involve training a complex recurrent neural network and applying it to a large scale NLP problem. On the model side we will cover word vector representations, window-based neural networks, recurrent neural networks, long-short-term-memory models, recursive neural networks, convolutional neural networks as well as some very novel models involving a memory component. Through lectures and programming assignments students will learn the necessary engineering tricks for making neural networks work on practical problems.

# Course Instructor



**Richard Socher** 

## http://cs224d.stanford.edu/

# INTRODUCTION

- Tutorial on Neural Networks (Deep Learning and Unsupervised Feature Learning): <u>http://deeplearning.stanford.edu/wiki/index.php/UFLDL\_Tutorial</u>
- Deep Learning for Computer Vision lecture: <u>http://cs231n.stanford.edu</u> (<u>http://cs231n.github.io</u>)
- Deep Learning for NLP lecture: <u>http://cs224d.stanford.edu</u> (<u>http://cs224d.stanford.edu/syllabus.html</u>)
- Deep Learning for NLP (without magic) tutorial: <u>http://lxmls.it.pt/2014/socher-lxmls.pdf</u> (Videos from NAACL 2013: <u>http://nlp.stanford.edu/courses/NAACL2013</u>)
- Bengio's Deep Learning book: <u>http://www.deeplearningbook.org</u>

# PARAMETER INITIALIZATION

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