

Machine Learning and Data Mining
 Summer 2015
Exercise Sheet 8

Presentation of Solutions to the Exercise Sheet on the 10.06.2015

Exercise 8-1 Human Height

Assume that the height of a human from a finite population is a Gaussian random variable:

$$P_{\mathbf{w}}(\mathbf{x}_i) = \mathcal{N}(\mathbf{x}_i; \mu, \sigma^2) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(\mathbf{x}_i - \mu)^2}{2\sigma^2}\right)$$

For independent $\mathbf{x}_i \in \mathbb{R}$ from such a population $\mathbf{w} = (\mu, \sigma)^T \in \mathbb{R}^2$ holds

$$\begin{aligned} P_{\mathbf{w}}(\mathbf{x}_1, \dots, \mathbf{x}_N) &= \prod_{i=1}^N P_{\mathbf{w}}(\mathbf{x}_i) = \prod_{i=1}^N \mathcal{N}(\mathbf{x}_i; \mu, \sigma^2) = \\ &= \frac{1}{(2\pi\sigma^2)^{\frac{N}{2}}} \exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^N (\mathbf{x}_i - \mu)^2\right) \end{aligned}$$

- a) Determine the maximum likelihood estimator of $P_{\mathbf{w}}(\mathbf{x}_1, \dots, \mathbf{x}_N)$.
- b) Compute the corresponding estimators for the four height datasets in the file `body_sizes.txt` and visualize the respective distributions. How does the estimator reflect the understanding of the underlying data?

Possible Solution:

a)

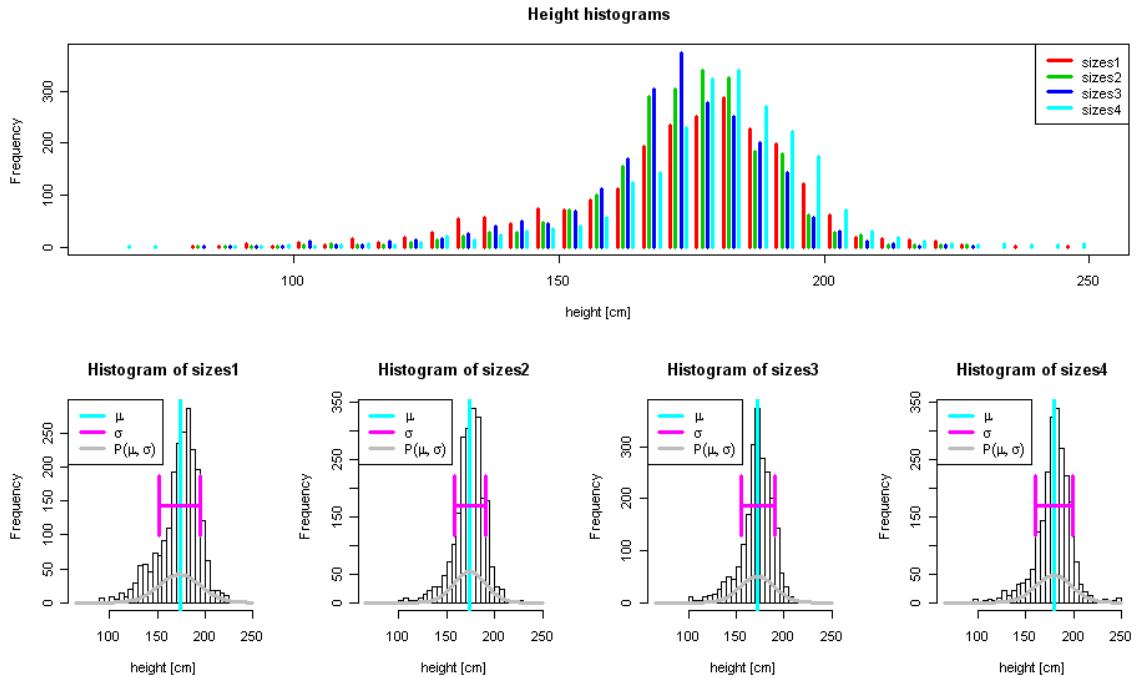
$$\begin{aligned}
 l(\mu, \sigma) &= \log P_{\mathbf{w}}(\mathbf{x}_1, \dots, \mathbf{x}_N) = \overbrace{\log 1}^{=0} - \log (2\pi\sigma^2)^{\frac{N}{2}} + \left(-\frac{1}{2\sigma^2} \sum_{i=1}^N (\mathbf{x}_i - \mu)^2 \right) \\
 \frac{\partial l(\mu, \sigma)}{\partial \mu} &= \frac{\partial \left(-\log(2\pi\sigma^2)^{\frac{N}{2}} - \left(\frac{1}{2\sigma^2} \sum_{i=1}^N (\mathbf{x}_i - \mu)^2 \right) \right)}{\partial \mu} = \\
 &= 0 - \left(\frac{1}{2\sigma^2} \sum_{i=1}^N 2 \cdot (\mathbf{x}_i - \mu) \cdot (-1) \right) = \frac{1}{\sigma^2} \sum_{i=1}^N (\mathbf{x}_i - \mu) = \\
 &= \frac{1}{\sigma^2} \left(\left(\sum_{i=1}^N \mathbf{x}_i \right) - N \cdot \mu \right) \\
 \frac{\partial l(\hat{\mu}^{\text{ML}}, \sigma)}{\partial \hat{\mu}^{\text{ML}}} &\stackrel{!}{=} 0 \Rightarrow \hat{\mu}^{\text{ML}} = \frac{1}{N} \sum_{i=1}^N \mathbf{x}_i \\
 \frac{\partial l(\mu, \sigma)}{\partial \sigma} &= \frac{\partial \left(-\frac{N}{2} \log(2\pi\sigma^2) - \left(\frac{1}{2\sigma^2} \sum_{i=1}^N (\mathbf{x}_i - \mu)^2 \right) \right)}{\partial \sigma} = \\
 &= -\frac{N}{2} \frac{1}{2\pi\sigma^2} \cdot 4\pi\sigma - \left(\frac{1}{2}(-2) \frac{1}{\sigma^3} \sum_{i=1}^N (\mathbf{x}_i - \mu)^2 \right) = \\
 &= -\frac{N}{\sigma} + \frac{1}{\sigma^3} \sum_{i=1}^N (\mathbf{x}_i - \mu)^2 \\
 \frac{\partial l(\mu, \hat{\sigma}^{\text{ML}})}{\partial \hat{\sigma}^{\text{ML}}} &\stackrel{!}{=} 0 \Rightarrow N = \frac{1}{(\hat{\sigma}^{\text{ML}})^2} \sum_{i=1}^N (\mathbf{x}_i - \mu)^2 \Rightarrow (\hat{\sigma}^{\text{ML}})^2 = \frac{1}{N} \sum_{i=1}^N (\mathbf{x}_i - \hat{\mu}^{\text{ML}})^2
 \end{aligned}$$

b) All values in cm:

$$\begin{aligned}
 \hat{\mu}_i^{\text{ML}} &= (161.5536, 153.7481, 154.5920) , \hat{\mu}^{\text{ML}} = 156.6312 \\
 \hat{\sigma}_i^{\text{ML}} &= (34.67525, 35.48248, 36.18142) , \hat{\sigma}^{\text{ML}} = 35.61861
 \end{aligned}$$

Estimator does not really help to understand the data.

Possible Solution:



Also the intervals $0 \pm \sigma$; $0 \pm 2\sigma$; $0 \pm 3\sigma$ have counterintuitive frequencies.

Exercise 8-2 Lineare Regression with Gaussian Noise

Let $D, d_i = (x_{i,1}, \dots, x_{i,M}, y_i)^T$, be a dataset of size N with M features and an output y which depends linearly on \mathbf{X} . Due to erroneous measurements the inputs are noisy, i.e.:

$$y_i = x_i^T \mathbf{w} + \epsilon_i ,$$

where ϵ_i is the noise of data point i . Furthermore, assume ϵ to be gaussian distributed:

$$P(\epsilon_i) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}\epsilon_i^2} .$$

Given the variables \mathbf{X} and the model \mathbf{w} , we can then model the distribution of y as follows:

$$P(y_i|x_i, \mathbf{w}) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(y_i - x_i^T \mathbf{w})^2} .$$

- a) Determine the parameter $\hat{\mathbf{w}}$ which maximizes the probability of the training data $P(D|\mathbf{w})$, using the *maximum-likelihood estimator*: $\hat{\mathbf{w}}^{\text{ML}} = \arg \max_{\mathbf{w}} P(D|\mathbf{w})$.

You may assume that the \mathbf{w} are distributed independently of the input data \mathbf{X} .

- b) A common assumption for the a priori distribution of random variables is:

$$P(\mathbf{w}) = \frac{1}{(2\pi\alpha^2)^{\frac{M}{2}}} e^{-\frac{1}{2\alpha^2} \sum_{j=0}^{M-1} w_j^2}$$

Compute the parameter $\hat{\mathbf{w}}$ which maximizes $P(\mathbf{w})P(D|\mathbf{w})$. Does this give an alternative interpretation to the λ -term of the penalized least squares function (PLS)?

Possible Solution:

- a) Observation: $L(\mathbf{w}) = P(D|\mathbf{w}) = P(\mathbf{y}, \mathbf{X}|\mathbf{w})$. $P(\mathbf{y}|\mathbf{X}, \mathbf{w})$ is given. We can use this by $P(\mathbf{y}, \mathbf{X}|\mathbf{w}) = P(\mathbf{y}|\mathbf{X}, \mathbf{w}) \cdot P(\mathbf{X}|\mathbf{w})$. We know that \mathbf{X} is independent of \mathbf{w} , hence, $P(\mathbf{X}|\mathbf{w}) = P(\mathbf{X})$. Thus, we have the following likelihood:

$$L(\mathbf{w}) = P(\mathbf{y}|\mathbf{X}, \mathbf{w}) \cdot P(\mathbf{X}).$$

However, we do not know $P(\mathbf{X})$. We will see later on, that this is not important, as $P(\mathbf{X})$ is independent of \mathbf{w} .

Also, we do not have $P(\mathbf{y}|\mathbf{X}, \mathbf{w})$, but “only” $P(y_i|x_i, \mathbf{w})$. Assuming that our samples have been drawn independently from the same distribution (i.i.d. = “independent, identically distributed”), we may write:

$$\begin{aligned} L(\mathbf{w}) &= \prod_{i=1}^N P(y_i, x_i|\mathbf{w}) = \prod_{i=1}^N P(y_i|x_i, \mathbf{w}) \cdot P(x_i) \\ &= \prod_{i=1}^N \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(y_i - x_i^T \mathbf{w})^2} \cdot P(x_i). \end{aligned}$$

which we have to derive now. Instead of deriving the product over all $(x_i, y_i) \in D$, we derive the log-likelihood, applying $\ln(a \cdot b) = \ln a + \ln b$ (which is not the same as $e^{a+b} = e^a \cdot e^b$).

$$\begin{aligned} l(\mathbf{w}) &= \ln L(\mathbf{w}) = \ln \left(\prod_{i=1}^N P(y_i|x_i, \mathbf{w}) \cdot P(x_i) \right) = \sum_{i=1}^N \ln (P(y_i|x_i, \mathbf{w}) \cdot P(x_i)) = \\ &= \sum_{i=1}^N \ln \left(\frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(y_i - x_i^T \mathbf{w})^2} \cdot P(x_i) \right) = \\ &= \underbrace{\sum_{i=1}^N \ln \frac{1}{\sqrt{2\pi\sigma^2}}}_{= N \ln 1} + \underbrace{\sum_{i=1}^N \ln e^{-\frac{1}{2\sigma^2}(y_i - x_i^T \mathbf{w})^2}}_{\ln e^{f(x)} = f(x)} + \sum_{i=1}^N \ln P(x_i) = \\ &= -N \ln \sqrt{2\pi\sigma^2} - \frac{1}{2\sigma^2} \sum_{i=1}^N (y_i - x_i^T \mathbf{w})^2 + \sum_{i=1}^N \ln P(x_i). \end{aligned}$$

$$\begin{aligned} \frac{\partial l(\mathbf{w})}{\partial \mathbf{w}} &= -\frac{1}{2\sigma^2} \sum_{i=1}^N (-x_i) \cdot 2 \cdot (y_i - x_i^T \mathbf{w}) = \\ &= \frac{1}{\sigma^2} \sum_{i=1}^N \underbrace{x_i}_{M \times 1} \cdot \underbrace{(y_i - x_i^T \mathbf{w})}_{1 \times 1} \end{aligned}$$

b.w.

Possible Solution:

We set this term equal to 0.

$$\begin{aligned}
 \frac{\partial l(\hat{\mathbf{w}}^{\text{ML}})}{\partial \hat{\mathbf{w}}^{\text{ML}}} = 0 &= \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix} = \frac{1}{\sigma^2} \underbrace{\mathbf{X}^T}_{M \times N} \underbrace{(\mathbf{y} - \mathbf{X} \hat{\mathbf{w}}^{\text{ML}})}_{N \times 1} = \\
 &\Leftrightarrow 0 = \mathbf{X}^T \mathbf{y} - \mathbf{X}^T \mathbf{X} \hat{\mathbf{w}}^{\text{ML}} \\
 &\Leftrightarrow \mathbf{X}^T \mathbf{X} \hat{\mathbf{w}}^{\text{ML}} = \mathbf{X}^T \mathbf{y} \\
 &\Leftrightarrow \hat{\mathbf{w}}^{\text{ML}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}
 \end{aligned}$$

This is exactly the solution of the Least Squares (LS) method.

Alternatively directly by matrix solution:

$$\begin{aligned}
 L(\mathbf{w}) &= P(\mathbf{X}) \cdot \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(\mathbf{y}-\mathbf{X}\mathbf{w})^2} = \\
 &= P(\mathbf{X}) \cdot \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(\mathbf{y}-\mathbf{X}\mathbf{w})^T(\mathbf{y}-\mathbf{X}\mathbf{w})} = \\
 &= P(\mathbf{X}) \cdot \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(\mathbf{y}^T \mathbf{y} - \mathbf{w}^T \mathbf{X}^T \mathbf{y} - \mathbf{y}^T \mathbf{X} \mathbf{w} + \mathbf{w}^T \mathbf{X}^T \mathbf{X} \mathbf{w})} = \\
 &= P(\mathbf{X}) \cdot \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(\mathbf{y}^T \mathbf{y} - 2\mathbf{w}^T \mathbf{X}^T \mathbf{y} + \mathbf{w}^T \mathbf{X}^T \mathbf{X} \mathbf{w})}.
 \end{aligned}$$

Derivative:

$$\begin{aligned}
 \frac{\partial l(\mathbf{w})}{\partial \mathbf{w}} &= \frac{\partial \ln L(\mathbf{w})}{\partial \mathbf{w}} = -\frac{1}{2\sigma^2}(0 - 2\mathbf{X}^T \mathbf{y} + 2\mathbf{X}^T \mathbf{X} \mathbf{w}) = \\
 &= \frac{1}{\sigma^2}(\mathbf{X}^T \mathbf{y} - \mathbf{X}^T \mathbf{X} \mathbf{w})
 \end{aligned}$$

Rest is as before

b.w.

Possible Solution:

b)

We are looking for $\hat{\mathbf{w}}^{\text{ML}}$ für $L(\mathbf{w}) = P(\mathbf{w})P(D|w) = P(\mathbf{w})P(\mathbf{y}|\mathbf{X}, \mathbf{w})P(\mathbf{X}) = \hat{\mathbf{w}}^{\text{MAP}}$, the *maximum-a-posteriori estimator*.

Log-Likelihood:

$$\begin{aligned} l(\mathbf{w}) &= \ln L(\mathbf{w}) = \ln P(\mathbf{w}) + \ln P(\mathbf{y}|\mathbf{X}, \mathbf{w}) + \ln P(\mathbf{X}) = \\ &= \ln \left(\frac{1}{\sqrt{2\pi\alpha^2}^M} e^{-\frac{1}{2\alpha^2}\mathbf{w}^T\mathbf{w}} \right) + \ln \left(\frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(\mathbf{y}^T\mathbf{y} - 2\mathbf{w}^T\mathbf{X}^T\mathbf{y} + \mathbf{w}^T\mathbf{X}^T\mathbf{X}\mathbf{w})} \right) + \ln P(\mathbf{X}) = \\ &= \ln \frac{1}{\sqrt{2\pi\alpha^2}^M} - \frac{1}{2\alpha^2}\mathbf{w}^T\mathbf{w} + \ln \frac{1}{\sqrt{2\pi\sigma^2}} - \frac{1}{2\sigma^2}(\mathbf{y}^T\mathbf{y} - 2\mathbf{w}^T\mathbf{X}^T\mathbf{y} + \mathbf{w}^T\mathbf{X}^T\mathbf{X}\mathbf{w}) + \ln P(\mathbf{X}). \end{aligned}$$

Derivative:

$$\begin{aligned} \frac{\partial l(\mathbf{w})}{\partial \mathbf{w}} &= -\frac{1}{2\alpha^2}2\mathbf{w} - \frac{1}{2\sigma^2}(-2\mathbf{X}^T\mathbf{y} + 2\mathbf{X}^T\mathbf{X}\mathbf{w}) = \\ &= -\frac{1}{\alpha^2}\mathbf{w} + \frac{1}{\sigma^2}(\mathbf{X}^T\mathbf{y} - \mathbf{X}^T\mathbf{X}\mathbf{w}) \end{aligned}$$

Set equal to 0:

$$\begin{aligned} \frac{\partial l(\hat{\mathbf{w}}^{\text{MAP}})}{\partial \hat{\mathbf{w}}^{\text{MAP}}} &= 0 \\ 0 &= \frac{1}{\sigma^2}\mathbf{X}^T\mathbf{y} - \frac{1}{\sigma^2}\mathbf{X}^T\mathbf{X}\hat{\mathbf{w}}^{\text{MAP}} - \frac{1}{\alpha^2}\hat{\mathbf{w}}^{\text{MAP}} \\ \frac{1}{\sigma^2}\mathbf{X}^T\mathbf{X}\hat{\mathbf{w}}^{\text{MAP}} + \frac{1}{\alpha^2}\hat{\mathbf{w}}^{\text{MAP}} &= \frac{1}{\sigma^2}\mathbf{X}^T\mathbf{y} \\ \left(\frac{1}{\sigma^2}\mathbf{X}^T\mathbf{X} + \frac{1}{\alpha^2}I \right) \hat{\mathbf{w}}^{\text{MAP}} &= \frac{1}{\sigma^2}\mathbf{X}^T\mathbf{y} \\ \left(\frac{1}{\sigma^2}\mathbf{X}^T\mathbf{X} + \frac{1}{\alpha^2}I \right)^{-1} \left(\frac{1}{\sigma^2}\mathbf{X}^T\mathbf{X} + \frac{1}{\alpha^2}I \right) \hat{\mathbf{w}}^{\text{MAP}} &= \left(\frac{1}{\sigma^2}\mathbf{X}^T\mathbf{X} + \frac{1}{\alpha^2}I \right)^{-1} \frac{1}{\sigma^2}\mathbf{X}^T\mathbf{y} \\ \hat{\mathbf{w}}^{\text{MAP}} &= \left(\frac{1}{\sigma^2}\mathbf{X}^T\mathbf{X} + \frac{1}{\alpha^2}I \right)^{-1} \frac{1}{\sigma^2}\mathbf{X}^T\mathbf{y} \\ \hat{\mathbf{w}}^{\text{MAP}} &= \frac{1}{\frac{1}{\sigma^2}} \left(\mathbf{X}^T\mathbf{X} + \frac{\sigma^2}{\alpha^2}I \right)^{-1} \frac{1}{\sigma^2}\mathbf{X}^T\mathbf{y} \\ \hat{\mathbf{w}}^{\text{MAP}} &= \left(\mathbf{X}^T\mathbf{X} + \frac{\sigma^2}{\alpha^2}I \right)^{-1} \mathbf{X}^T\mathbf{y} \end{aligned}$$

The MAP estimator corresponds to the model of the regularized cost function where $\lambda = \frac{\sigma^2}{\alpha^2}$. The noisy model is thereby a special case of the regularized cost function.

Recall:

$$\hat{\mathbf{w}}_{\text{pen}} = (\mathbf{X}^T\mathbf{X} + \lambda I)^{-1} \mathbf{X}^T\mathbf{y}, \text{ wobei } \text{cost}^{\text{pen}}(\mathbf{w}) = \sum_{i=1}^N (y_i - f(x_i, \mathbf{w}))^2 + \lambda \sum_{i=0}^{M-1} w_i^2.$$