

Random Forests

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Introduction

- Random forests (Breiman, 2001) is a substantial modification of bagging that builds a large collection of de-correlated trees, and then averages them.
- On many problems the performance of random forests is very similar to boosting, and they are simpler to train and tune. As a consequence, random forests are popular, and are implemented in a variety of packages.
- The essential idea in bagging is to average many noisy but approximately unbiased models, and hence reduce the variance. Trees are ideal candidates for bagging, since they can capture complex interaction
- The idea in random forests is to improve the variance reduction of bagging by reducing the correlation between the trees, without increasing the variance too much.
- This is achieved in the tree-growing process through random selection of the input variables.

Algorithm

1. For $b = 1$ to B :
 - (a) Draw a bootstrap sample Z^* of size N from the training data.
 - (b) Grow a random-forest tree T_b to the bootstrapped data, by recursively repeating the following steps for each terminal node of the tree, until the minimum node size n_{\min} is reached.
 - i. Select m variables at random from the p variables.
 - ii. Pick the best variable/split-point among the m .
 - iii. Split the node into two daughter nodes.
2. Output the ensemble of trees $\{T_b\}_{b=1}^B$

Prediction

- To make a prediction at a new point x : Regression: $f(x) = \frac{1}{B} \sum_{b=1}^T T_b(x)$
- Classification: Do a majority vote on the predicted classes.

Default Parameters

- For classification, the default value for m is \sqrt{p} and the minimum node size is one.
- For regression, the default value for m is $p/3$ and the minimum node size is five

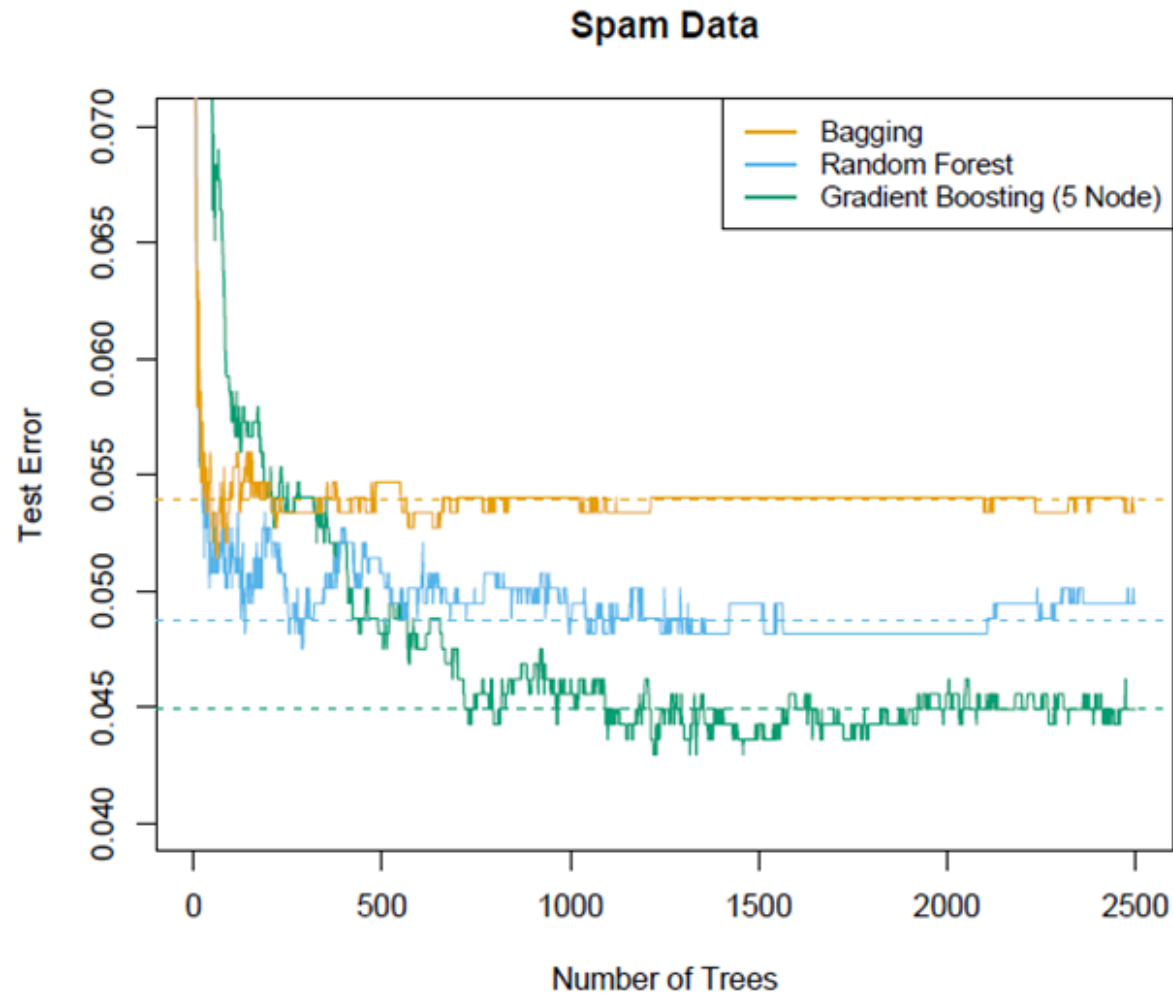


FIGURE 15.1. *Bagging, random forest, and gradient boosting, applied to the spam data. For boosting, 5-node trees were used, and the number of trees were chosen by 10-fold cross-validation (2500 trees). Each “step” in the figure corresponds to a change in a single misclassification (in a test set of 1536).*

California Housing Data

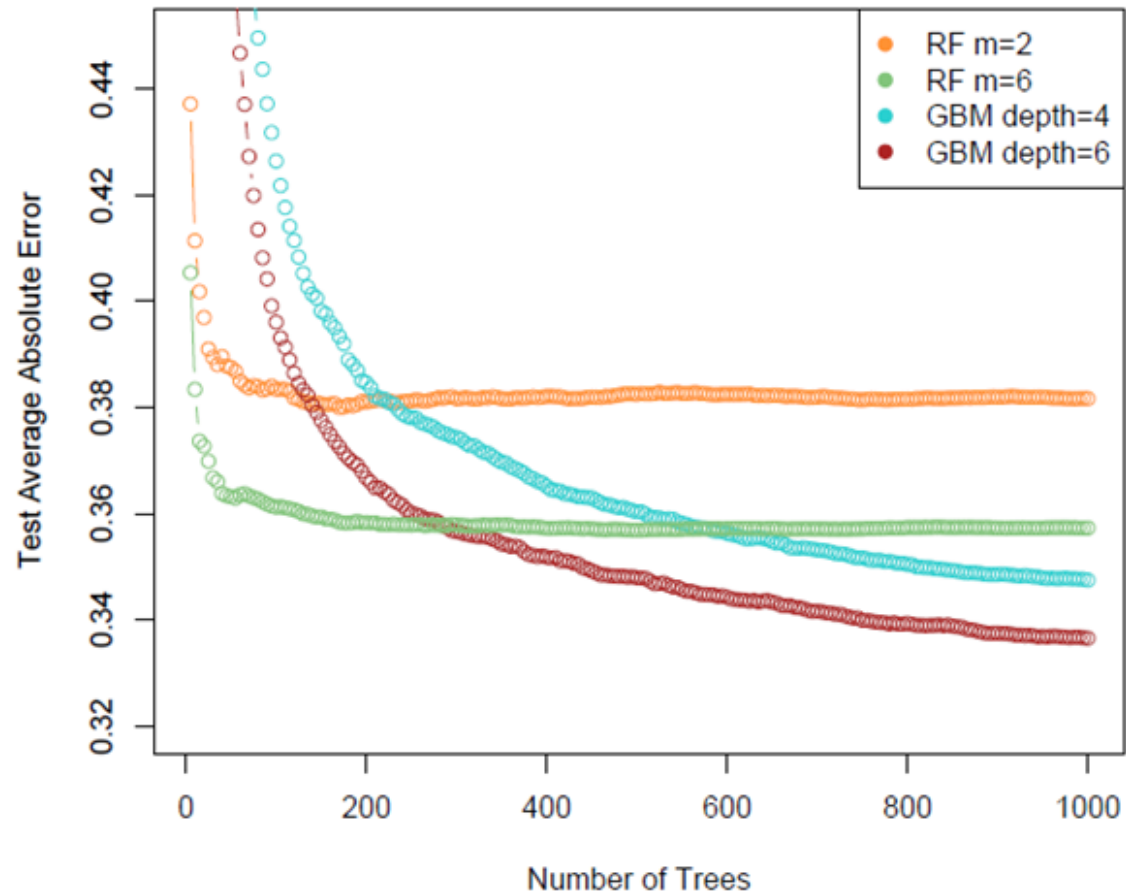
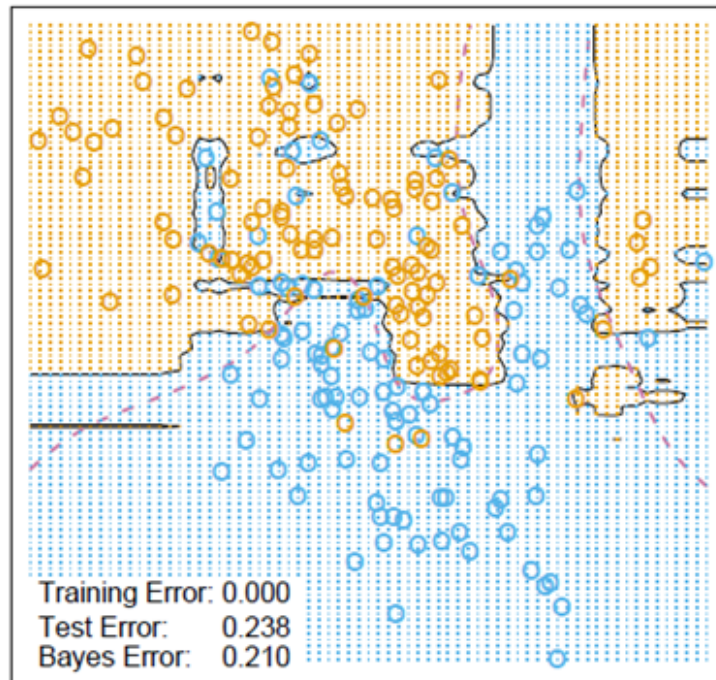


FIGURE 15.3. *Random forests compared to gradient boosting on the California housing data. The curves represent mean absolute error on the test data as a function of the number of trees in the models. Two random forests are shown, with $m = 2$ and $m = 6$. The two gradient boosted models use a shrinkage parameter $\nu = 0.05$ in (10.41), and have interaction depths of 4 and 6. The boosted models outperform random forests.*

Random Forest Classifier



3-Nearest Neighbors

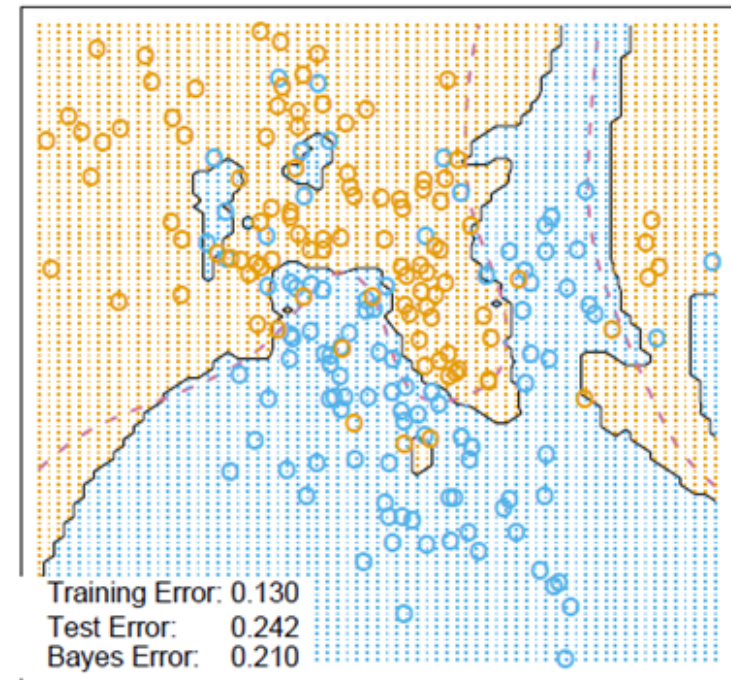


FIGURE 15.11. *Random forests versus 3-NN on the mixture data. The axis-oriented nature of the individual trees in a random forest lead to decision regions with an axis-oriented flavor.*