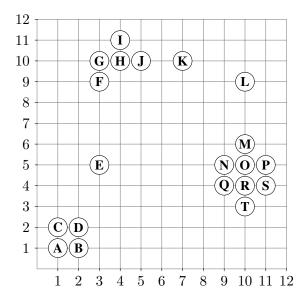
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Knowledge Discovery and Data Mining I WS 2019/20

Exercise 7: DBSCAN, Spectral Clustering

Exercise 7-1 DBSCAN

Given the following data set:



As distance function, use Manhattan Distance:

$$L_1(x,y) = |x_1 - y_1| + |x_2 - y_2|$$

Compute DBSCAN and indicate which points are core points, border points and noise points. Use the following parameter settings:

- Radius $\varepsilon = 1.1$ and minPts = 2
- Radius $\varepsilon = 1.1$ and minPts = 3
- Radius $\varepsilon = 1.1$ and minPts = 4
- Radius $\varepsilon = 2.1$ and minPts = 4
- Radius $\varepsilon = 4.1$ and minPts = 5
- Radius $\varepsilon = 4.1$ and minPts = 4

Exercise 7-2 Properties of DBSCAN

Discuss the following questions/propositions about DBSCAN:

- Using minPts = 2, what happens to the border points?
- The result of DBSCAN is deterministic w.r.t. the core and noise points but not w.r.t. the border points.
- A cluster found by DBSCAN cannot consist of less than *minPts* points.
- If the dataset consists of n objects, DBSCAN will evaluate exactly $n \epsilon$ -range queries.
- On uniformly distributed data, DBSCAN will usually either assign all points to a single cluster or classify every point as noise. *k*-means on the other hand will partition the data into approximately equally sized partitions.

Exercise 7-3 Spectral Clustering

- (a) Given the dataset from Exercise 7-1, apply spectral clustering to the first ten points (i.e. A J). When constructing the graph, make sure that each point is connected to its neighbours in an eps = 2 neighbourhood while still having at least two outgoing edges.
- (b) As shown in the lecture, spectral clustering uses the Laplacian matrix to determine its clusters. Given an arbitrary graph G and the Laplacian L for G, show that finding an indicator vector f_C that minimizes fLf^T leads to an optimal cluster C in G, where

$$\mathbf{f}_{C}^{(i)} = \begin{cases} 1 & \text{if } v_i \in C \\ 0 & \text{else} \end{cases}$$