

- 1) Introduction to clustering
- 2) Partitioning Methods
 - K-Means
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 - Choice of parameters: Initialization, Silhouette coefficient
- 3) Expectation Maximization: a statistical approach
- 4) Density-based Methods: DBSCAN
- 5) Hierarchical Methods
 - Agglomerative and Divisive Hierarchical Clustering
 - Density-based hierarchical clustering: OPTICS
- 6) Evaluation of Clustering Results
- 7) Further Clustering Topics
 - Ensemble Clustering

Ein paar Grundgedanken:

- Clustering: Anwendung eines Verfahrens auf ein konkretes Problem (einen bestimmten Datensatz, über den man Neues erfahren möchte).

Zur Erinnerung: KDD ist der Prozess der (semi-) automatischen Extraktion von Wissen aus Datenbanken, das gültig, bisher **unbekannt** und potentiell nützlich ist.

- Frage: Was kann man mit den Ergebnissen anfangen?
 - nicht unbedingt neue Erkenntnisse, aber gut überprüfbare
 - Anwendung auf Daten, die bereits gut bekannt sind
 - Anwendung auf künstliche Daten, deren Struktur by design bekannt ist
 - Frage: Werden Eigenschaften/Strukturen gefunden, die der Algorithmus nach seinem Model finden sollte? Besser als andere Algorithmen?
 - Überprüfbarkeit alleine ist aber fragwürdig!
- grundsätzlich: Clustering ist unsupervised
 - ein Clustering ist nicht richtig oder falsch, sondern mehr oder weniger sinnvoll
 - ein “sinnvolles” Clustering wird von den verschiedenen Verfahren auf der Grundlage von verschiedenen Annahmen (Heuristiken!) angestrebt
 - Überprüfung der Sinnhaftigkeit erfordert Fachwissen über die Datengrundlage

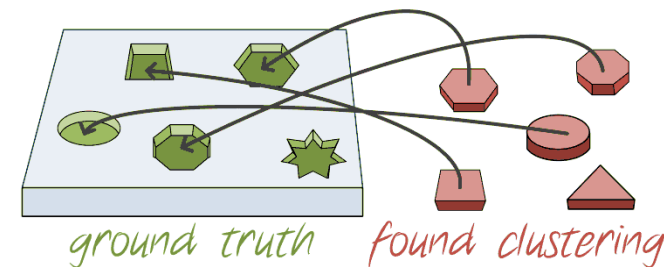
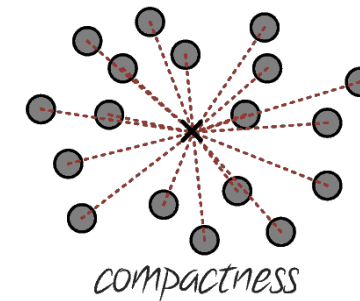
General approaches:

- Evaluation based on **expert's** opinion
 - + may reveal new insight into the data
 - very expensive, results are not comparable

- Evaluation based on **internal** measures
 - + no additional information needed
 - approaches optimizing the evaluation criteria will always be preferred

- Evaluation based on **external** measures
 - + objective evaluation
 - needs „ground truth“

e.g., comparison of two clusterings



Idea:

- Make some assumptions on the characteristics of clusters and define an evaluation criteria thereof
- Measure how good the clusters of the clustering reflect those characteristics
- Example: Clusters
 - Minimize intra-cluster distances
 - Maximize inter-cluster distances
- Obvious downside: approaches optimizing the evaluation criteria will always be preferred (k-means-like are preferred over density-based in the above example)

Popular Measures

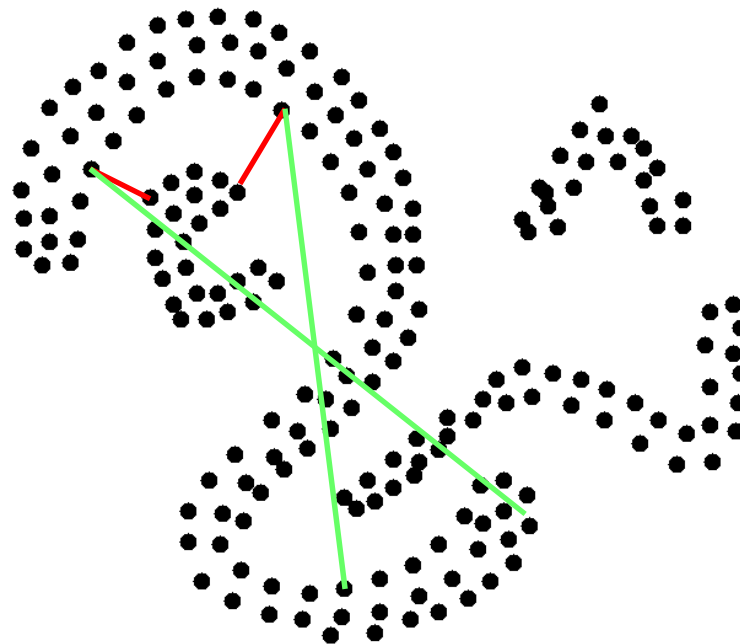
Given a clustering $C = (C_1, \dots, C_k)$ for Dataset DB

- Sum of square distances:

$$SSD(C) = \frac{1}{|DB|} \sum_{C_i \in C} \sum_{p \in C_i} (dist(p, \mu(C_i)))^2$$

- Cohesion: measures the similarity of objects within a cluster
- Separation: measures the dissimilarity of one cluster to another one
- Silhouette Coefficient: combines cohesion and separation

- Suitable for globular cluster, but not for stretched clusters



Idea:

Given

- a clustering $\mathcal{C} = (C_1, \dots, C_k)$ and
- a “ground truth” $\mathcal{G} = (G_1, \dots, G_l)$ for dataset DB

Measure the „similarity“ between $\mathcal{C}$ and $\mathcal{G}$.

Popular Measures

- Recall: $rec(C_i, G_j) = \frac{|C_i \cap G_j|}{|G_j|}$
- Precision: $prec(C_i, G_j) = \frac{|C_i \cap G_j|}{|C_i|}$
- F-Measure: $F(C_i, G_j) = \frac{2 * rec(C_i, G_j) * prec(C_i, G_j)}{rec(C_i, G_j) + prec(C_i, G_j)}$
- Purity (P): $P(\mathcal{C}, \mathcal{G}) = \sum_{C_i \in \mathcal{C}} \frac{|C_i|}{|DB|} pur(C_i, \mathcal{G})$ $pur(C_i, \mathcal{G}) = \max_{G_j \in \mathcal{G}} prec(C_i, G_j)$
- Rand Index: „normalized number of agreements “
- Jaccard Coefficient (JC)
- ...

Rand Index:

$$RI = \frac{a + d}{a + b + c + d}$$

a: #Paare in gleicher Klasse und gleichem Cluster

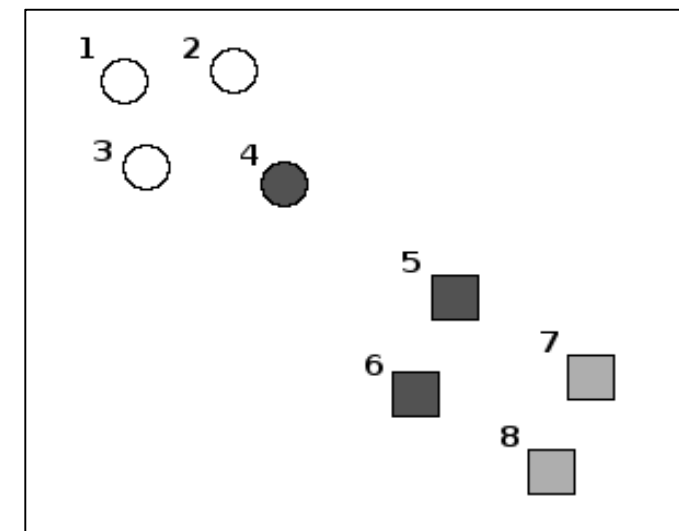
b: #Paare in gleicher Klasse aber versch. Clustern

c: #Paare in versch. Klassen aber gleichem Cluster

d: #Paare in versch. Klassen und versch. Cluster

Beispiel:

- Ground Truth: 2 Klassen (Kreise und Quadrate)
- 3 Cluster (Schwarz, Weiß, Grau)



$$a = 5; b = 7; c = 2; d = 14$$

$$RI = 5 + 14 / (5 + 7 + 2 + 14) = 0.6785$$

Jaccard Coefficient $J_c = \frac{a}{a+b+c}$

a: #Paare in gleicher Klasse und gleichem Cluster

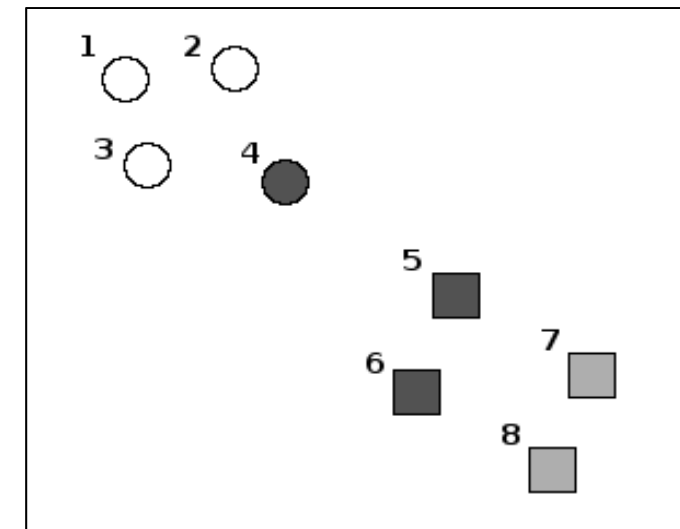
b: #Paare in gleicher Klasse aber versch. Clustern

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Beispiel:

- 2 Klassen (Kreise und Quadrate)
- 3 Cluster (Schwarz, Weiß, Grau)



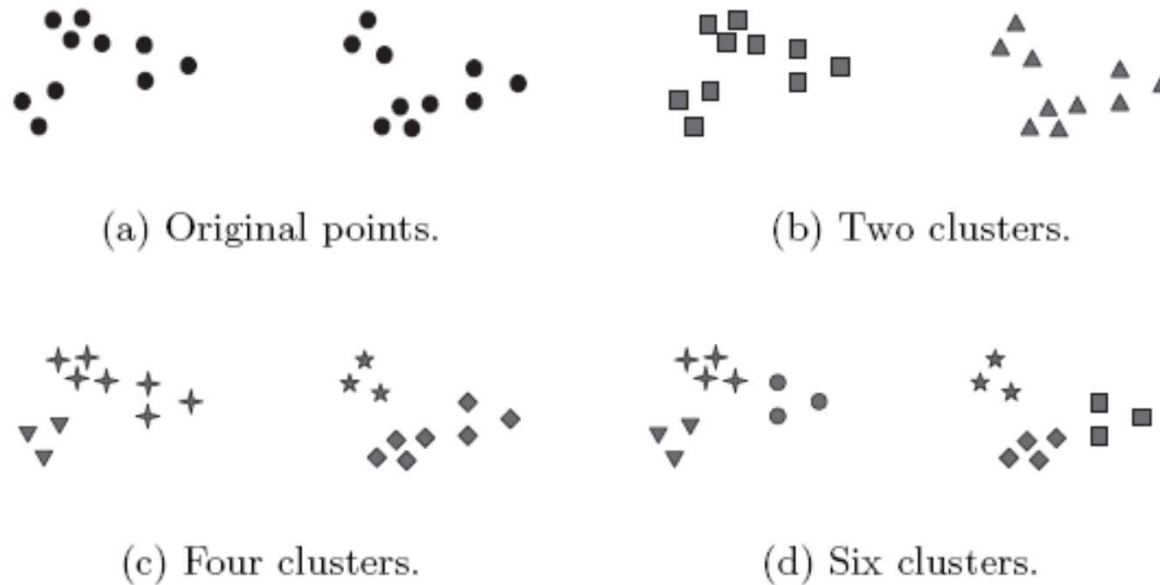
$$a = 5; b = 7; c = 2$$

$$J_c = 5 / (5 + 7 + 2) = 0.3571$$

Further methods:

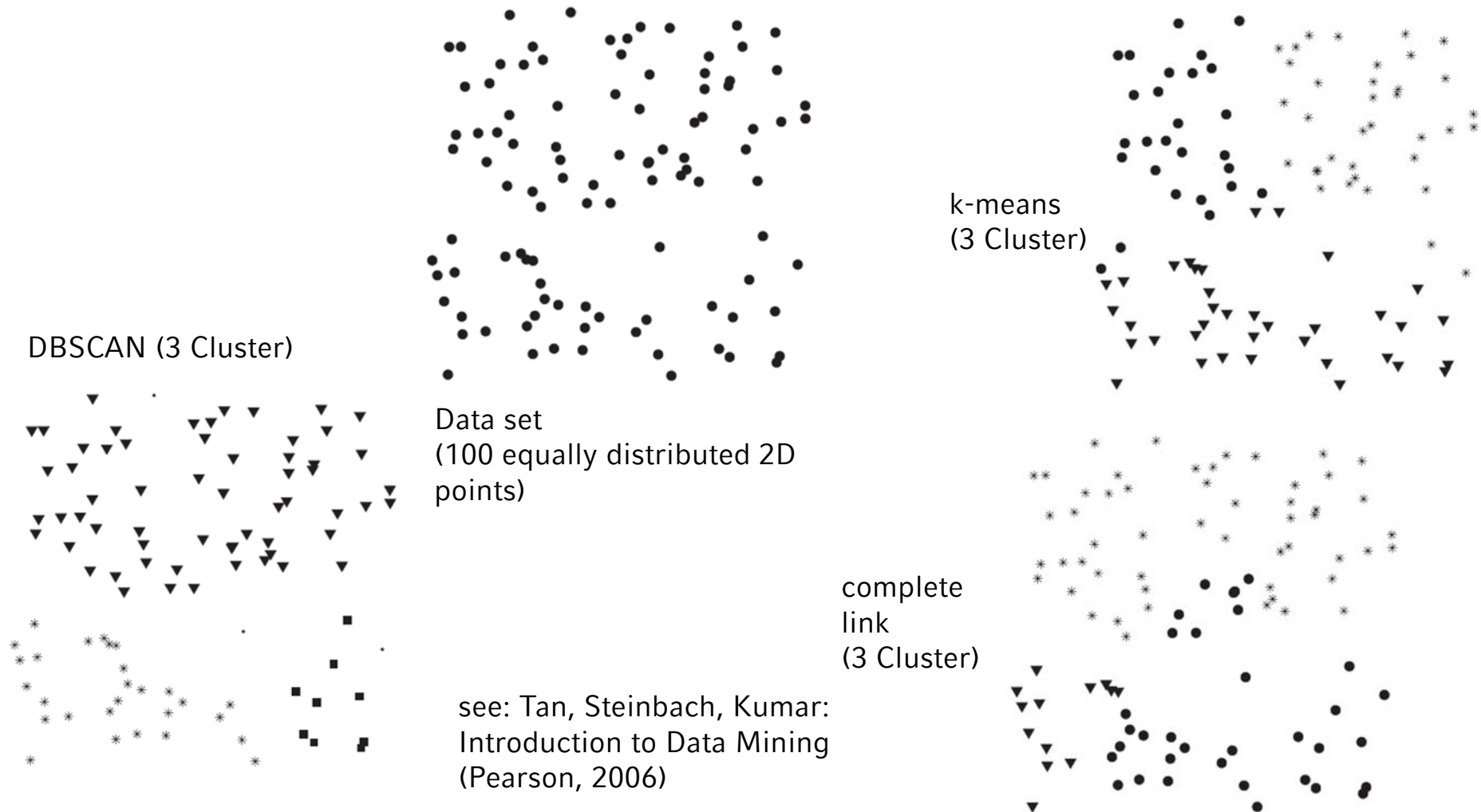
- Mutual Entropy: $H(\mathcal{C}|\mathcal{G}) = -\sum_{C_i \in \mathcal{C}} p(C_i) \sum_{G_j \in \mathcal{G}} p(G_j|C_i) \log p(G_j|C_i)$
$$= -\sum_{C_i \in \mathcal{C}} \frac{|C_i|}{|DB|} \sum_{G_j \in \mathcal{G}} \frac{|C_i \cap G_j|}{|C_i|} * \log_2 \left(\frac{|C_i \cap G_j|}{|C_i|} \right)$$
- Mutual Information: $I(\mathcal{C}, \mathcal{G}) = H(\mathcal{C}) - H(\mathcal{C}|\mathcal{G}) = H(\mathcal{G}) - H(\mathcal{G}|\mathcal{C})$
where entropy $H(\mathcal{C}) = -\sum_{C_i \in \mathcal{C}} p(C_i) \cdot \log p(C_i) = -\sum_{C \in \mathcal{C}} \frac{|C_i|}{|DB|} \cdot \log \frac{|C_i|}{|DB|}$
- Normalized Mutual Information: $NMI(\mathcal{C}, \mathcal{G}) = \frac{I(\mathcal{C}, \mathcal{G})}{\sqrt{H(\mathcal{C})H(\mathcal{G})}}$

Different possibilities to cluster a set of objects

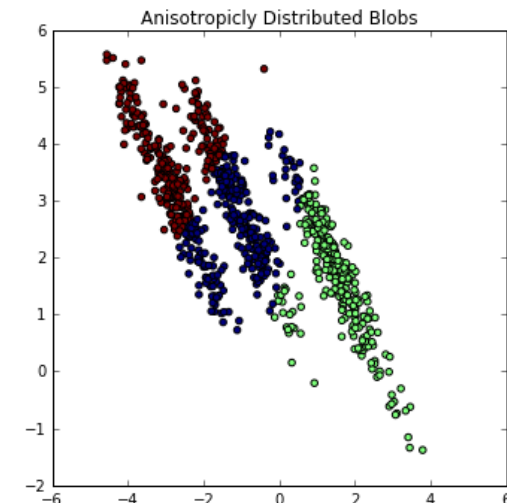
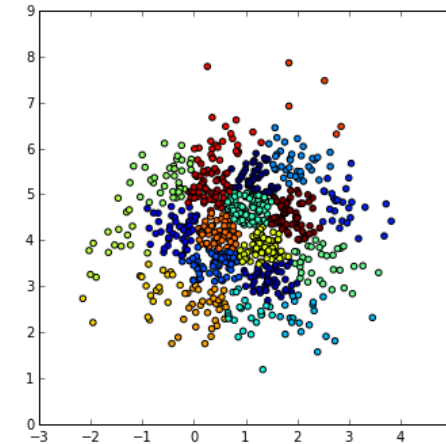


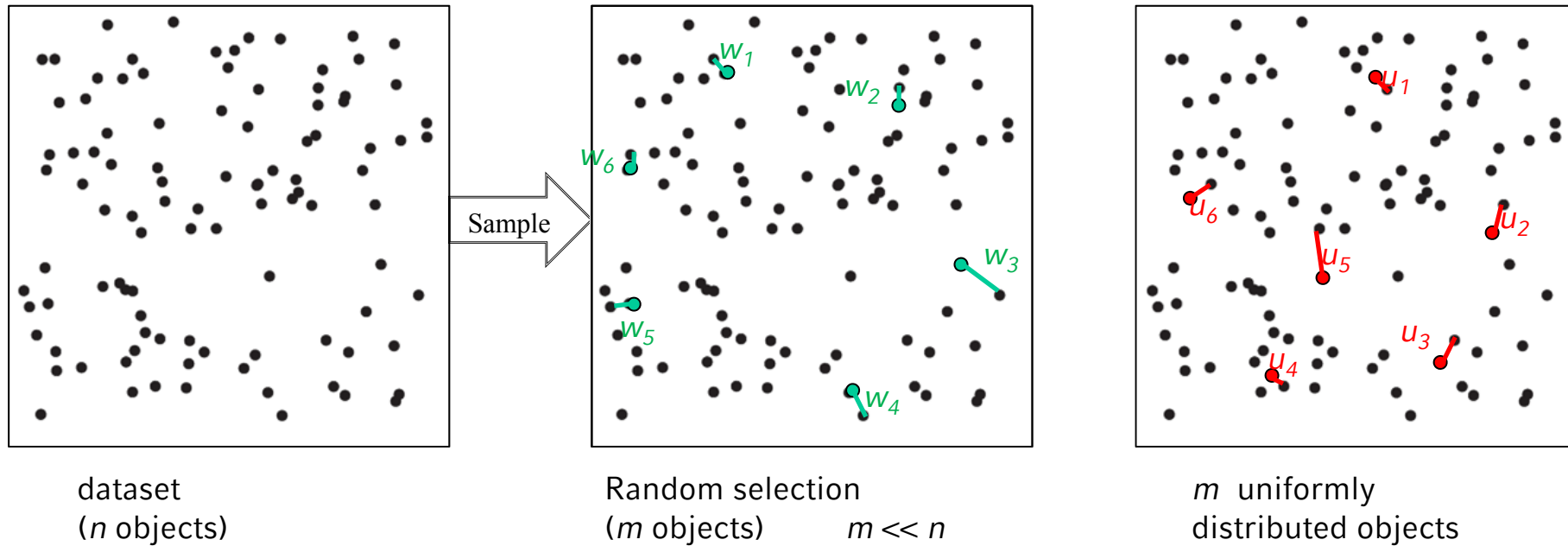
from: Tan, Steinbach, Kumar: Introduction to Data Mining (Pearson, 2006)

Clusters on randomized data (equally distributed data)



- Kind of a philosophical problem:
“What is a correct clustering?”
- Most approaches find clusters in every dataset, even in uniformly distributed object
- Are there clusters?
 - Apply clustering algorithm
 - Check for reasonability of clusters
- Problem: No clusters found $\nRightarrow$ no clusters existing
 - Maybe clusters exists only in certain models, but can not be found by used clustering approach
- Independent of clustering: Is there a data-given cluster tendency?





w_i : distances of selected objects to the next neighbor in dataset

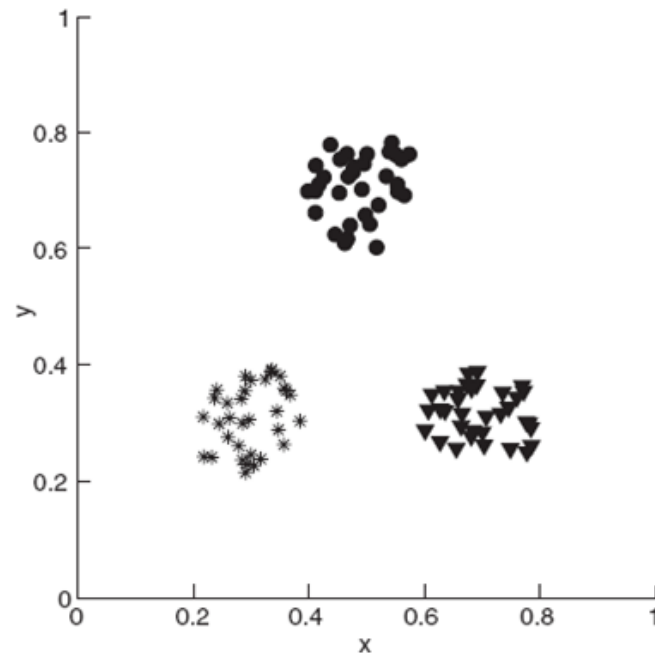
u_i : distances of uniformly distributed objects to the next neighbor in dataset

$$H = \frac{\sum_{i=1}^m u_i}{\sum_{i=1}^m u_i + \sum_{i=1}^m w_i} \quad 0 \leq H \leq 1$$

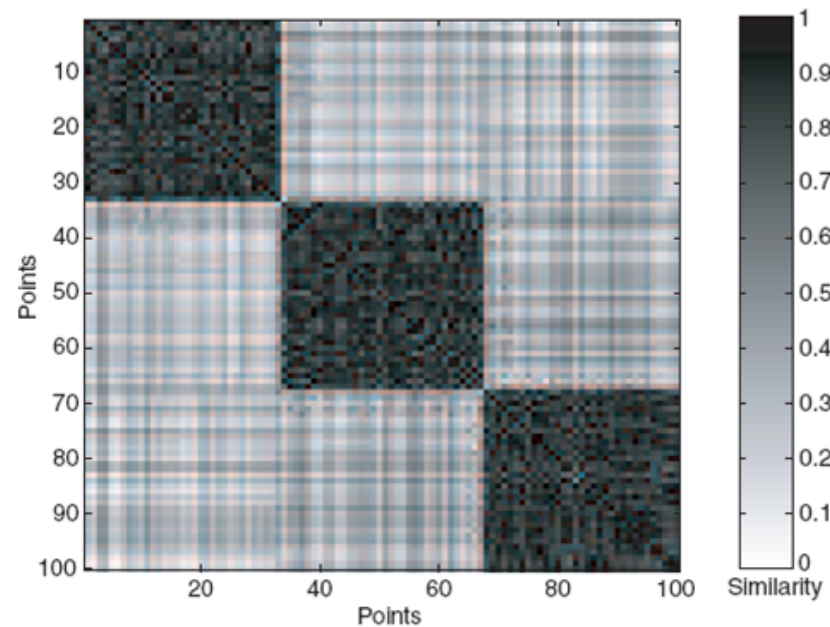
$H \approx 0$: data are very regular (e.g. on grid)

$H \approx 0,5$: data are uniformly distributed

$H \approx 1$: data are strongly clustered



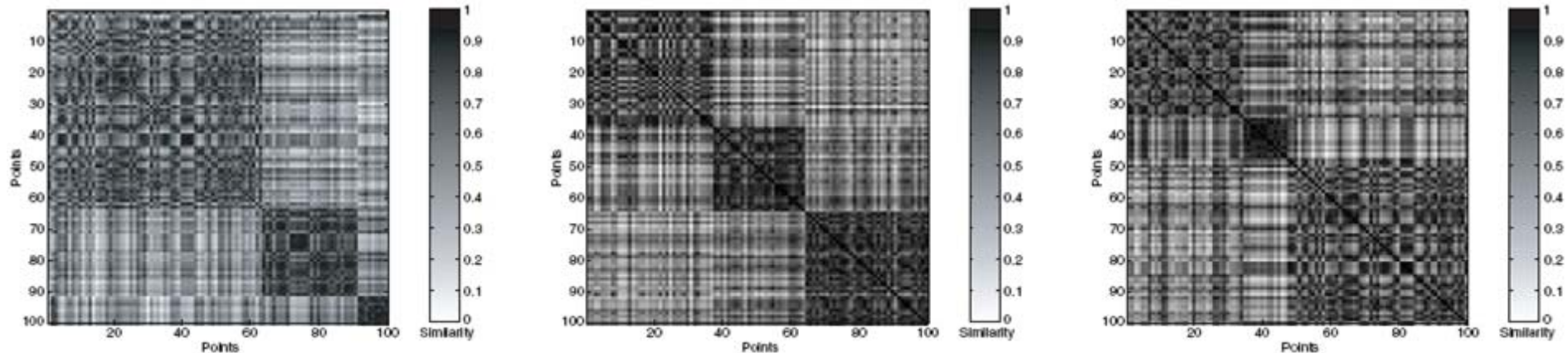
dataset
(well separated clusters)



Similarity matrix
(sorted by k-means Cluster-labels)

from: Tan, Steinbach, Kumar: Introduction to Data Mining (Pearson, 2006)

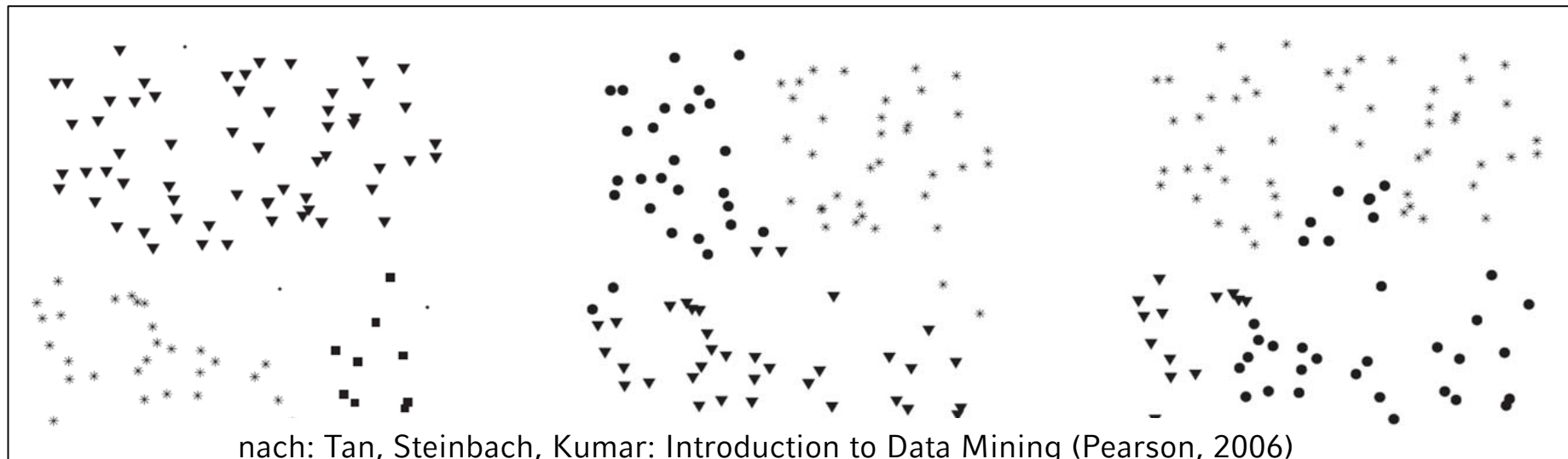
similarity matrices differ for different clustering approaches



DBSCAN

k-means

complete link



nach: Tan, Steinbach, Kumar: Introduction to Data Mining (Pearson, 2006)

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Problem:

- Many differing cluster definitions
- Parameter choice usually highly influences the result
- What is a ‚good‘ clustering?

Idea: Find a consensus solution (also ensemble clustering) that consolidates multiple clustering solutions.

Benefits of Ensemble Clustering:

- **Knowledge Reuse:** possibility to integrate the knowledge of multiple known, good clusterings
- **Improved quality:** often ensemble clustering leads to “better” results than its individual base solutions.
- **Improved robustness:** combining several clustering approaches with differing data modeling assumptions leads to an increased robustness across a wide range of datasets.
- **Model Selection:** novel approach for determining the final number of clusters
- **Distributed Clustering:** if data is inherently distributed (either feature-wise or object-wise) and each clusterer has only access to a subset of objects and/or features, ensemble methods can be used to compute a unifying result.

Given: a set of L clusterings $\mathcal{C} = \{\mathcal{C}_1, \dots, \mathcal{C}_L\}$ for dataset $\mathbf{X} = \{\mathbf{x}_1, \dots, \mathbf{x}_N\} \in \mathbb{R}^D$

Goal : find a consensus clustering $\mathcal{C}^*$

What exactly is a consensus clustering?

We can differentiate between 2 categories for ensemble clustering:

- Approaches based on pairwise similarity

Idea: find a consensus clustering $\mathcal{C}^*$ for which the similarity function

$$\phi(\mathcal{C}, \mathcal{C}^*) = \frac{1}{L} \sum_{l=1}^L \phi(\mathcal{C}_l, \mathcal{C}^*) \text{ is maximal.}$$



*basically our external evaluation measures,
which compare two clusterings*

- Probabilistic approaches :

Assume that the L labels for the objects $\mathbf{x}_i \in \mathbf{X}$ follow a certain distribution

→ We will present one exemplary approach for both categories in the following

Given: a set of L clusterings $\mathcal{C} = \{\mathcal{C}_1, \dots, \mathcal{C}_L\}$ for dataset $\mathbf{X} = \{\mathbf{x}_1, \dots, \mathbf{x}_N\} \in \mathbb{R}^D$

- Goal : find a consensus clustering $\mathcal{C}^*$ for which the similarity function $\phi(\mathcal{C}, \mathcal{C}^*) = \frac{1}{L} \sum_{l=1}^L \phi(\mathcal{C}_l, \mathcal{C}^*)$ is maximal.
 - Popular choices for ϕ in the literature:
 - Pair counting-based measures: Rand Index (RI), Adjusted RI, Probabilistic RI
 - Information theoretic measures: Mutual Information (I), Normalized Mutual Information (NMI), Variation of Information (VI)

Problem: the above objective is intractable

Solutions:

- Methods based on the co-association matrix (related to RI)
- Methods using cluster labels without co-association matrix (often related to NMI)
 - Mostly graph partitioning
 - Cumulative voting

Given: a set of L clusterings $\mathfrak{C} = \{\mathcal{C}_1, \dots, \mathcal{C}_L\}$ for dataset $\mathbf{X} = \{\mathbf{x}_1, \dots, \mathbf{x}_N\} \in \mathbb{R}^D$

The co-association matrix $\mathbf{S}^{(\mathfrak{C})}$ is an $N \times N$ matrix representing the label

similarity of object pairs: $s_{i,j}^{(\mathfrak{C})} = \sum_{l=1}^L \delta \left(\underbrace{C(\mathcal{C}_l, \mathbf{x}_i)}_{\substack{\uparrow \\ \text{cluster label of } \mathbf{x}_i \text{ in clustering } \mathcal{C}_l}}, \underbrace{C(\mathcal{C}_l, \mathbf{x}_j)}_{\substack{\uparrow \\ \text{cluster label of } \mathbf{x}_j \text{ in clustering } \mathcal{C}_l}} \right)$

where $\delta(a, b) = \begin{cases} 1 & \text{if } a = b \\ 0 & \text{else} \end{cases}$

cluster label of $\mathbf{x}_i, \mathbf{x}_j$ in clustering $\mathcal{C}_l$

Based on the similarity matrix defined by $\mathbf{S}^{(\mathfrak{C})}$ traditional clustering approaches can be used

Often $\mathbf{S}^{(\mathfrak{C})}$ is interpreted as weighted adjacency matrix, such that methods for graph partitioning can be applied.

In [Mirkin'96] a connection of consensus clustering based on the co-association matrix and the optimization of the pairwise similarity based on the Rand Index ($\mathcal{C}^{best} = \operatorname{argmax}_{\mathcal{C}^*} \left\{ \frac{1}{L} \sum_{\mathcal{C}_l \in \mathfrak{C}} RI(\mathcal{C}_l, \mathcal{C}^*) \right\}$) has been proven.

[Mirkin'96] B. Mirkin: *Mathematical Classification and Clustering*. Kluwer, 1996.

- Consensus clustering $\mathcal{C}^*$ for which $\frac{1}{L} \sum_{\mathcal{C}_l \in \mathcal{C}} \phi(\mathcal{C}_l, \mathcal{C}^*)$ is maximal
 - Information theoretic approach: choose ϕ as mutual information (I), normalized mutual information (NMI), information bottleneck (IB),...
- Problem: Usually a hard optimization problem
 - Solution 1: Use meaningful optimization approaches (e.g. gradient descent) or heuristics to approximate the best clustering solution (e.g. [SG02])
 - Solution 2: Use a similar but solvable objective (e.g. [TJP03])
 - Idea: use as objective $\mathcal{C}_{best} = \operatorname{argmax}_{\mathcal{C}^*} \left\{ \frac{1}{L} \sum_{\mathcal{C}_l \in \mathcal{C}} I^s(\mathcal{C}_l, \mathcal{C}^*) \right\}$
 where I^s is the mutual information based on the generalized entropy of degree s :

$$H^s(X) = (2^{1-s} - 1)^{-1} \sum_{x_i \in X} (p_i^s - 1)$$
 - For $s = 2$, $I^s(\mathcal{C}_l, \mathcal{C}^*)$ is equal to the category utility function whose maximization is proven to be equivalent to the minimization of the square-error clustering criterion
 - Thus apply a simple label transformation and use e.g. K-Means

[SG02] A. Strehl, J. Ghosh: *Cluster ensembles - a knowledge reuse framework for combining multiple partitions*. Journal of Machine Learning Research, 3, 2002, pp. 583-617.

[TJP03] A. Topchy, A.K. Jain, W. Punch. *Combining multiple weak clusterings*. In ICDM, pages 331-339, 2003.

Assumption 1: all clusterings $\mathcal{C}_l \in \mathfrak{C}$ are partitionings of the dataset $\mathbf{X}$.

Assumption 2: there are K^* consensus clusters

The dataset $\mathbf{X}$ is represented by the set

$$\mathbf{Y} = \{\mathbf{y}_n \in \mathbb{N}_0^L \mid \exists \mathbf{x}_n \in \mathbf{X}. \forall \mathcal{C}_l \in \mathfrak{C}. y_{nl} = \mathcal{C}(\mathcal{C}_l, \mathbf{x}_n)\}$$

we have a new feature Space $\mathbb{N}_0^L$, where the l^{th} feature represents the cluster labels from partition $\mathcal{C}_l$

Assumption 3: the dataset $\mathbf{Y}$ (labels of base clusterings) follow a multivariate mixture distribution:

$$P(\mathbf{Y}|\boldsymbol{\Theta}) = \prod_{n=1}^N \sum_{k=1}^{K^*} \alpha_k P_k(\mathbf{y}_n | \boldsymbol{\theta}_k) = \prod_{n=1}^N \sum_{k=1}^{K^*} \alpha_k \prod_{l=1}^L P_{kl}(y_{nl} | \boldsymbol{\theta}_{kl})$$

$P_{kl}(y_{nl} | \boldsymbol{\theta}_{kl}) \sim M\left(1, (p_{k,l,1}, \dots, p_{k,l,|\mathcal{C}_l|})\right)$ follows a $|\mathcal{C}_l|$ -dimensional multinomial

distribution: $P_{kl}(y_{nl} | \boldsymbol{\theta}_{kl}) = \prod_{k'=1}^{|\mathcal{C}_l|} p_{k,l,k'}^{\delta(y_{nl}, k')}$

therefore: $\boldsymbol{\theta}_{kl} = (p_{k,l,1}, \dots, p_{k,l,|\mathcal{C}_l|})$

Goal: find the parameters $\boldsymbol{\Theta} = (\alpha_1, \boldsymbol{\theta}_1, \dots, \alpha_{K^*}, \boldsymbol{\theta}_{K^*})$ such that the likelihood $P(\mathbf{Y}|\boldsymbol{\Theta})$ is maximized

Solution: optimizing the parameters via the EM approach. *(details omitted)*

Presented approach: Topchy, Jain, Punch: A mixture model for clustering ensembles. In ICDM, pp. 379-390, 2004.

Later extensions: H. Wang, H. Shan, A. Banerjee: Bayesian cluster ensembles. In ICDM, pp. 211-222, 2009.

P. Wang, C. Domeniconi, K. Laskey: Nonparametric Bayesian clustering ensembles. In PKDD, pp. 435-450, 2010.

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 - Discussion: an alternative view on DBSCAN

Reconsider DBSCAN algorithm

- Standard DBSCAN evaluation is based on recursive database traversal.
- Böhm et al. (2000) observed that DBSCAN, among other clustering algorithms, may be efficiently built on top of similarity join operations.

Similarity joins

- An ε -similarity join yields all pairs of ε -similar objects from two data sets P, Q :

$$P \bowtie_{\varepsilon} Q = \{(p, q) \mid p \in P \wedge q \in Q \wedge \text{dist}(p, q) \leq \varepsilon\}$$

- SQL-Query: `SELECT * FROM P, Q WHERE  $\text{dist}(P, Q) \leq \varepsilon$`

- An ε -similarity self join yields all pairs of ε -similar objects from a database DB :

$$DB \bowtie_{\varepsilon} DB = \{(p, q) \mid p \in DB \wedge q \in DB \wedge \text{dist}(p, q) \leq \varepsilon\}$$

- SQL-Query: `SELECT * FROM DB p, DB q WHERE  $\text{dist}(p, q) \leq \varepsilon$`

Böhm C., Braunmüller, B., Breunig M., Kriegel H.-P.: High performance clustering based on the similarity join. CIKM 2000: 298-305.

ε -Similarity self join:

$$DB \bowtie_{\varepsilon} DB = \{(p, q) \mid p \in DB \wedge q \in DB \wedge \text{dist}(p, q) \leq \varepsilon\}$$

Relation „directly ε , *MinPts*-density reachable“ may be expressed in terms of an ε -similarity self join:

$$\begin{aligned} ddr_{\varepsilon, \mu} &= \{(p, q) \mid p \text{ is } \varepsilon, \mu\text{-core point} \wedge q \in N_{\varepsilon}(p)\} \\ &= \{(p, q) \mid p, q \in DB \wedge \text{dist}(p, q) \leq \varepsilon \wedge \exists_{\geq \mu} q' \in DB: \text{dist}(p, q') \leq \varepsilon\} \\ &= \{(p, q) \mid (p, q) \in DB \bowtie_{\varepsilon} DB \wedge \exists_{\geq \mu} q': (p, q') \in DB \bowtie_{\varepsilon} DB\} \\ &= \sigma_{|\pi_p(DB \bowtie_{\varepsilon} DB)| \geq \mu}(DB \bowtie_{\varepsilon} DB) =: DB \bowtie_{\varepsilon, \mu} DB \end{aligned}$$

- SQL-Query: SELECT * FROM DB p, DB q WHERE $\text{dist}(p, q) \leq \varepsilon$
GROUP BY p.id HAVING count(p.id) $\geq \mu$
- Remark: $DB \bowtie_{\varepsilon} DB$ is a symmetric relation, $ddr_{\varepsilon, \mu} = DB \bowtie_{\varepsilon, \mu} DB$ is not.

DBSCAN then computes the connected components within $DB \bowtie_{\varepsilon, \mu} DB$.

Partitioning Methods: K-Means, K-Medoid, K-Mode, K-Median

Probabilistic Model-Based Clusters: Expectation Maximization

Density-based Methods: DBSCAN

Hierarchical Methods

- Agglomerative and Divisive Hierarchical Clustering
- Density-based hierarchical clustering: OPTICS

Evaluation of Clustering Results

- Evaluation based on an expert's knowledge; internal evaluation measures; external evaluation measures

Further Clustering Topics

- Ensemble Clustering: finding a consensus clustering agreeing with multiple base clustering and its advantages
 - co-association matrix, information theoretic approaches, probabilistic approaches
- Discussion of DBSCAN as Join operation

Data Clustering – Algorithms and Applications

by C. C. Aggarwal and C. K. Reddy

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- [Link to publisher](#)
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Contents:

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 - Clustering Validation Measures
 - Feature Selection for Clustering
 - Clustering High-Dimensional Data
 - Spectral Clustering
 - Network Clustering
 - A Survey of Stream Clustering Algorithms
 - Alternative Clustering Analysis: A Review
 - Time-Series Data Clustering
 - Clustering Multimedia Data
 - ...
 - And many many more (e.g. Big Data Clustering, Document Clustering, ...)

