

Lecture notes

Knowledge Discovery in Databases

Summer Semester 2012

Lecture 7: Clustering I

Lecture: Dr. Eirini Ntoutsi

Tutorials: Erich Schubert

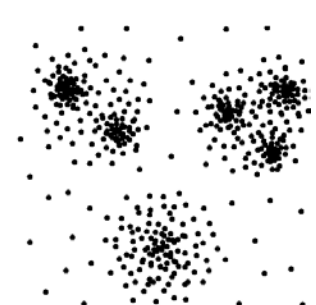
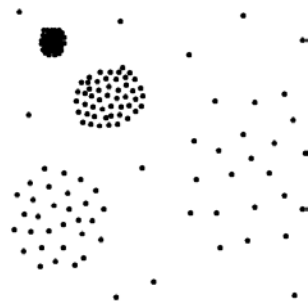
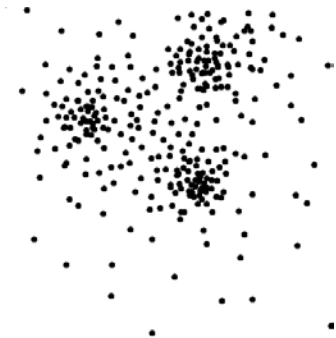
[http://www.dbs.ifi.lmu.de/cms/Knowledge_Discovery_in_Databases_I_\(KDD_I\)](http://www.dbs.ifi.lmu.de/cms/Knowledge_Discovery_in_Databases_I_(KDD_I))

- Previous KDD I lectures on LMU (Johannes Aßfalg, Christian Böhm, Karsten Borgwardt, Martin Ester, Eshref Januzaj, Karin Kailing, Peer Kröger, Jörg Sander, Matthias Schubert, Arthur Zimek)
- Jiawei Han, Micheline Kamber and Jian Pei, *Data Mining: Concepts and Techniques, 3rd ed.*, Morgan Kaufmann, 2011.
- Margaret Dunham, *Data Mining, Introductory and Advanced Topics*, Prentice Hall, 2002.
- Tan P.-N., Steinbach M., Kumar V., *Introduction to Data Mining*, Addison-Wesley, 2006

- Introduction
- Types of Data in Cluster Analysis
- A Categorization of Major Clustering Methods
- Partitioning Methods
- Things you should know
- Homework/tutorial

What is cluster analysis?

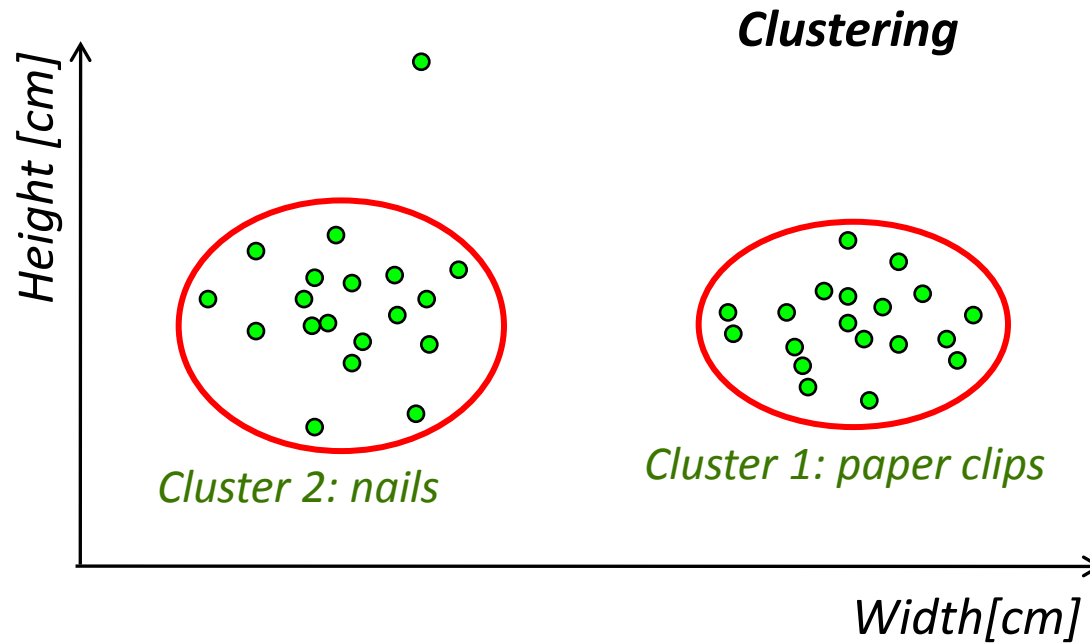
- Cluster: a collection of data objects
 - Similar to one another within the same cluster
 - Dissimilar to the objects in other clusters
- Cluster analysis
 - Finding similarities between data according to the characteristics found in the data and grouping similar data objects into clusters



An unsupervised learning task

- Clustering is an **unsupervised** learning task
 - Given a set of measurements, observations, etc., the goal is to group the data into groups of similar data (clusters)
 - We are given a dataset as input which we want to cluster but there are no class labels
 - We don't know how many clusters exist in the data
 - We don't know the characteristics of the individual clusters
- In contrast to classification, which is a **supervised** learning task
 - Supervision: The training data (observations, measurements, etc.) are accompanied by *labels* indicating the *class* of the observations
 - New data is classified based on the training set

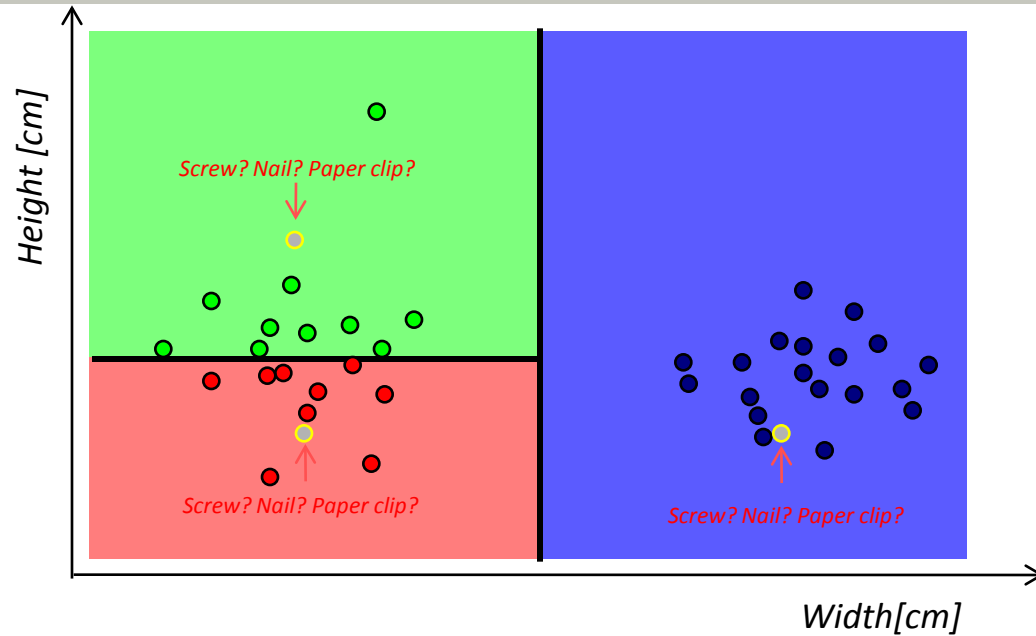
Unsupervised learning example



Question:

Is there any structure in data (based on their characteristics, i.e., width, height)?

Supervised learning example



Classification model

• Screw



• Nails



• Paper clips



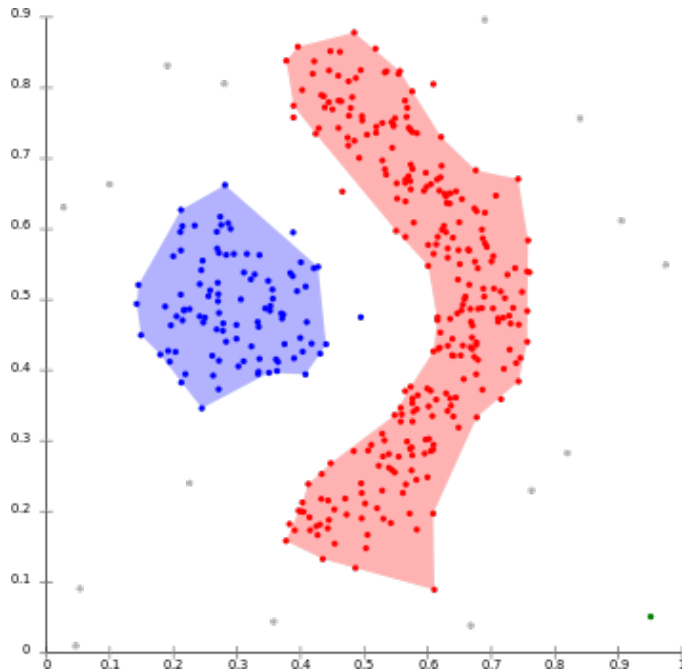
- New object (unknown class)

Question:

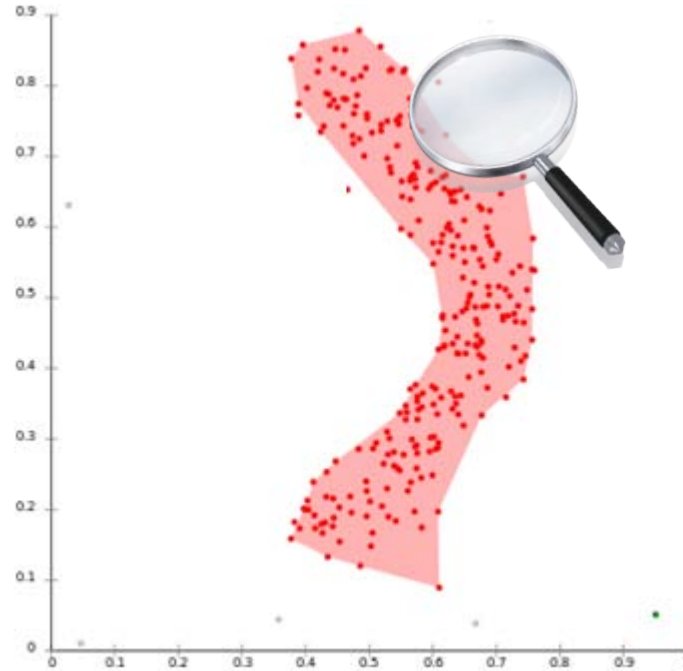
What is the class of a new object???
Is it a screw, a nail or a paper clip?

Why clustering?

- Clustering is widely used as:
 - As a **stand-alone tool** to get insight into data distribution
 - As a **preprocessing step** for other algorithms



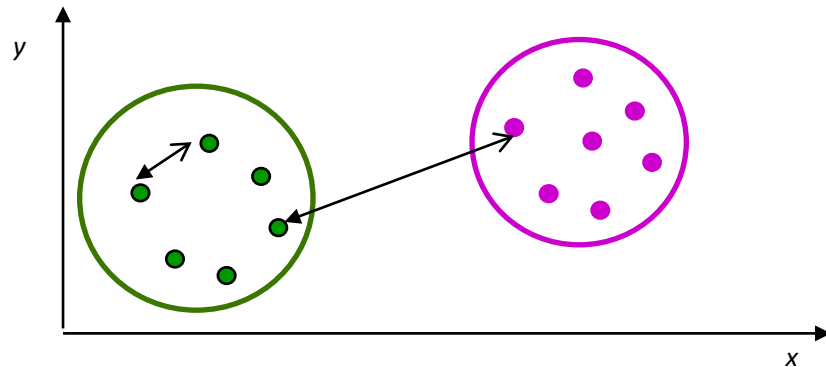
http://en.wikipedia.org/wiki/Cluster_analysis



Example applications

- Marketing:
 - Help marketers discover distinct groups in their customer bases, and then use this knowledge to develop targeted marketing programs
- Telecommunications:
 - Build user profiles based on usage and demographics and define profile specific tariffs and offers
- Land use:
 - Identification of areas of similar land use in an earth observation database
- City-planning:
 - Identifying groups of houses according to their house type, value, and geographical location
- Bioinformatics:
 - Cluster similar proteins together (similarity wrt chemical structure and/or functionality etc)
- Web:
 - Cluster users based on their browsing behavior
 - Cluster pages based on their content (e.g. News aggregators)

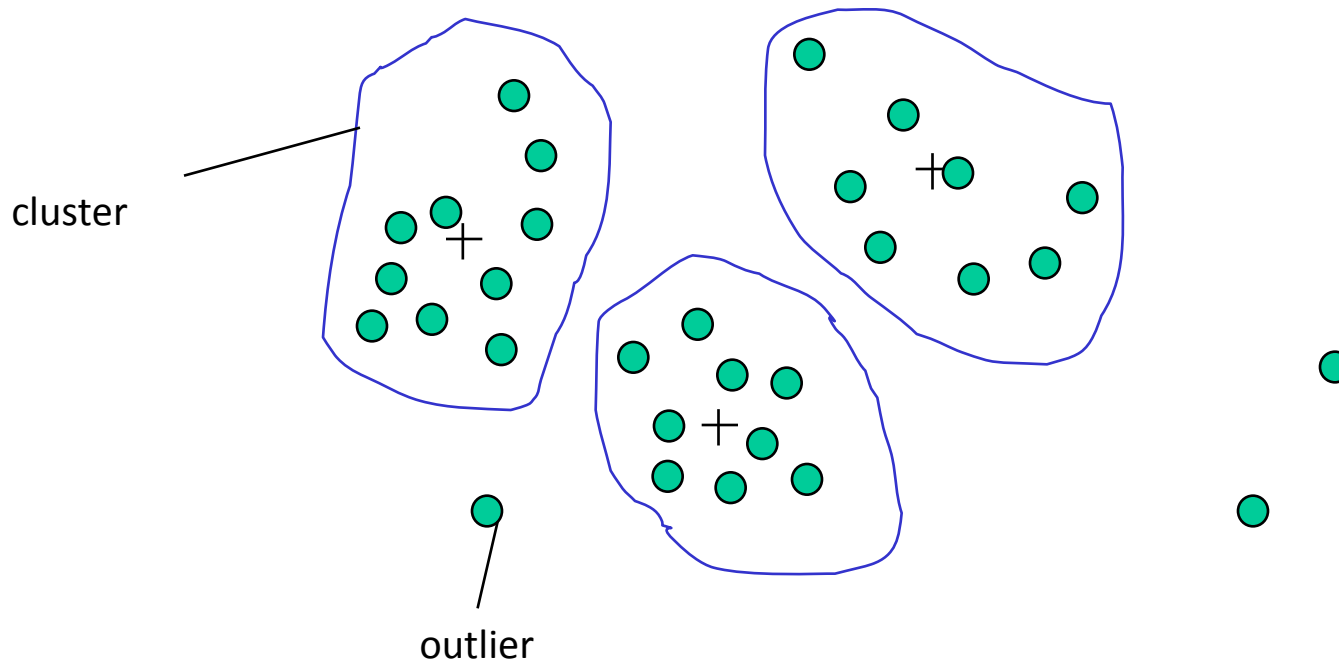
- **Goal:** Group objects into groups so that the objects belonging in the same group are similar (high intra-class similarity), whereas objects in different groups are different (low inter-class similarity)
- A good clustering method will produce high quality clusters with
 - high intra-class similarity
 - low inter-class similarity



- The quality of a clustering method is also measured by its ability to discover some or all of the hidden patterns
- The quality of a clustering result depends on both the similarity measure used by the method and its implementation

- Scalability
- Ability to deal with different types of attributes
- Ability to handle dynamic data
- Discovery of clusters with arbitrary shape
- Minimal requirements for domain knowledge to determine input parameters
- Able to deal with noise and outliers
- Insensitive to order of input records
- High dimensionality
- Incorporation of user-specified constraints
- Interpretability and usability

- There might be objects that do not belong to any cluster



- There are cases where we are interested in detecting outliers not clusters
- More on **outlier analysis** in an upcoming lecture

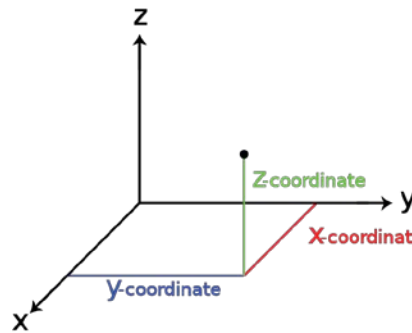
- Introduction
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Type of data in clustering analysis

- Real-value attributes
 - e.g., salary, height
- Binary/ Dichotomous attributes
 - e.g., gender (M/F), has_cancer(T/F)
- Categorical/ Nominal attributes
 - e.g., religion (Christian, Muslim, Buddhist, Hindu, etc.)
- Ordinal/Ranked attributes
 - e.g., military rank (soldier, sergeant, lutenant, captain, etc.)
- Variables of mixed types
 - multiple attributes with various types

Features/ Attributes/ Dimensions

- Objects are described through features/ attributes/ variables/ dimensions
 - e.g., (“J. Smith”, 20K, 30, 5)
- If all d dimensions are real-valued then we can visualize each data point as points in a d-dimensional space



http://en.wikipedia.org/wiki/Three-dimensional_space

- If all d dimensions are binary then we can think of each data point as a binary vector

0	1	0	0
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- The distance $d(x, y)$ between two objects x and y is a metric if
 - $d(i, j) \geq 0$ (*non-negativity*)
 - $d(i, i) = 0$ (*isolation*)
 - $d(i, j) = d(j, i)$ (*symmetry*)
 - $d(i, j) \leq d(i, h) + d(h, j)$ (*triangular inequality*)
- The definitions of distance functions are usually different for real, boolean, categorical, and ordinal variables.
- Weights may be associated with different variables based on applications and data semantics.

- Data matrix
 - Rows: objects
 - Columns: dimensions

$$\begin{bmatrix} x_{11} & \dots & x_{1f} & \dots & x_{1p} \\ \dots & \dots & \dots & \dots & \dots \\ x_{i1} & \dots & x_{if} & \dots & x_{ip} \\ \dots & \dots & \dots & \dots & \dots \\ x_{n1} & \dots & x_{nf} & \dots & x_{np} \end{bmatrix}$$

- Dissimilarity matrix
 - Rows: objects
 - Columns: objects

$$\begin{bmatrix} 0 & & & & \\ d(2,1) & 0 & & & \\ d(3,1) & d(3,2) & 0 & & \\ \vdots & \vdots & \vdots & & \\ d(n,1) & d(n,2) & \dots & \dots & 0 \end{bmatrix}$$

Dissimilarity between binary attributes (from Lecture 2)

- A binary attribute has two states: 0 (absence), 1 (presence)
- A contingency table for binary data

		<u>Object j</u>		
		1	0	sum
<u>Object i</u>	1	q	r	$q + r$
	0	s	t	$s + t$
sum		$q + s$	$r + t$	p

- Simple matching coefficient
(for symmetric binary variables)

$$d(i, j) = \frac{r + s}{q + r + s + t}$$

- for asymmetric binary variables:

$$d(i, j) = \frac{r + s}{q + r + s}$$

- Jaccard coefficient

(for *asymmetric* binary variables)

$$sim_{Jaccard}(i, j) = \frac{q}{q + r + s}$$

Example

Name	Fever	Cough	Test-1	Test-2	Test-3	Test-4
Jack	1	0	1	0	0	0
Mary	1	0	1	0	1	0
Jim	1	1	0	0	0	0

$$d(jack, mary) = \frac{0 + 1}{2 + 0 + 1} = 0.33$$

$$d(jack, jim) = \frac{1 + 1}{1 + 1 + 1} = 0.67$$

$$d(jim, mary) = \frac{1 + 2}{1 + 1 + 2} = 0.75$$

Dissimilarity measures between categorical/ nominal attributes (from Lecture 2)

- A categorical/ nominal attribute has >2 states (generalization of a binary attribute)
 - e.g. color={red, blue, green}
- Method 1: Simple matching
 - m: # of matches, p: total # of variables

$$d(i, j) = \frac{p - m}{p}$$

- Method 2: Map it to binary variables
 - create a new binary attribute for each of the M nominal states of the attribute

Dissimilarity between real-valued attributes (from Lecture 2)

- L_p norms or Minkowski distance: $L_p = (|p_1 - q_1|^p + |p_2 - q_2|^p + \dots + |p_d - q_d|^p)^{1/p}$
 - where p is a positive integer
- If $p = 1 \rightarrow$ Manhattan-norm (or city block) distance: $L_1 = |p_1 - q_1| + |p_2 - q_2| + \dots + |p_d - q_d|$
 - The sum of the absolute differences of their coordinates
- If $p = 2 \rightarrow$ Euclidean Norm (L_2): $L_2 = ((p_1 - q_1)^2 + (p_2 - q_2)^2 + \dots)^{1/2}$
 - The length of the line segment connecting p and q
- One can use weighted distance also
 - Weighted $L_1 = w_1 |p_1 - q_1| + w_2 |p_2 - q_2| + \dots + w_d |p_d - q_d|$
 - Weighted $L_2 = (w_1 (p_1 - q_1)^2 + w_2 (p_2 - q_2)^2 + \dots + w_d (p_d - q_d)^2)^{1/2}$

Normalization (from Lecture 2)

- Attributes with large ranges outweigh ones with small ranges
 - e.g. income [10K-100K]; age [10-100]
- To balance the “contribution” of each attribute in the resulting distance, the attributes are scaled to fall within a small, specified range
- min-max normalization: to $[new_min_A, new_max_A]$

$$v' = \frac{v - min_A}{max_A - min_A} (new_max_A - new_min_A) + new_min_A$$

- e.g. normalize age=30 in [0-1], when min=10,max=100. $new_age = (30-10)/(100-10) = 2/9$
- z-score normalization

$$v' = \frac{v - mean_A}{stand_dev_A}$$

e.g. normalize 70,000 iff $\mu=50,000$, $\sigma=15,000$.
 $new_value = (70,000-50,000)/15,000=1.33$

- Normalization by decimal scaling

$$v' = \frac{v}{10^j}$$

j is the smallest integer
 such that $Max(|v'|) < 1$

e.g., if v lies in $[1, 999]$, if we set $j=3$ then v' will
 lie in $[0.001, 0.999]$

- Vector objects: keywords in documents, gene features in micro-arrays, etc.
- Broad applications: information retrieval, biologic taxonomy, etc.
- Cosine measure

$$s(\vec{X}, \vec{Y}) = \frac{\vec{X}^t \cdot \vec{Y}}{|\vec{X}| |\vec{Y}|},$$

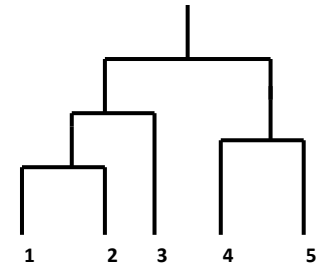
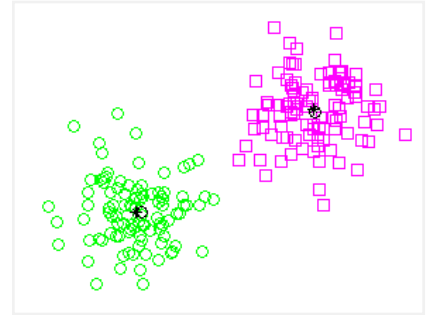
$\vec{X}^t$ is a transposition of vector $\vec{X}$, $|\vec{X}|$ is the Euclidean normal of vector $\vec{X}$, $|\mathbf{x}|_2 = |\mathbf{x}| = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$.

- A variant: Tanimoto coefficient

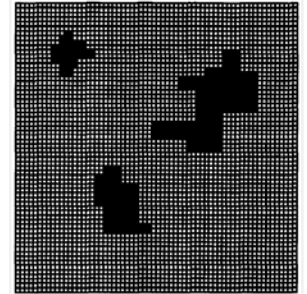
$$s(\vec{X}, \vec{Y}) = \frac{\vec{X}^t \cdot \vec{Y}}{\vec{X}^t \cdot \vec{X} + \vec{Y}^t \cdot \vec{Y} - \vec{X}^t \cdot \vec{Y}},$$

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- Partitioning approach:
 - Construct various partitions and then evaluate them by some criterion, e.g., minimizing the sum of square errors
 - Typical methods: k-means, k-medoids, CLARANS
- Hierarchical approach:
 - Create a hierarchical decomposition of the set of data (or objects) using some criterion
 - Typical methods: Diana, Agnes, BIRCH, ROCK, CHAMELEON
- Density-based approach:
 - Based on connectivity and density functions
 - Typical methods: DBSCAN, OPTICS, DenClue



- Grid-based approach:
 - based on a multiple-level granularity structure
 - Typical methods: STING, WaveCluster, CLIQUE
- Model-based:
 - A model is hypothesized for each of the clusters and tries to find the best fit of that model to each other
 - Typical methods: EM, SOM, COBWEB
- Frequent pattern-based:
 - Based on the analysis of frequent patterns
 - Typical methods: pCluster
- User-guided or constraint-based:
 - Clustering by considering user-specified or application-specific constraints
 - Typical methods: COD (obstacles), constrained clustering



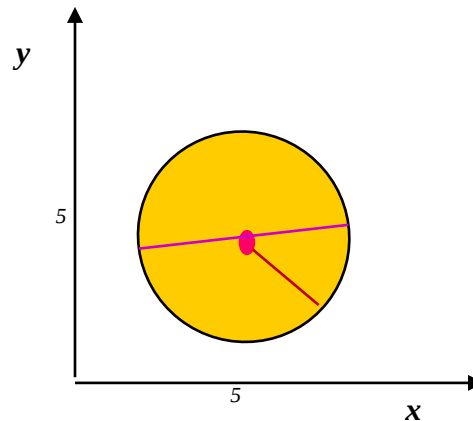
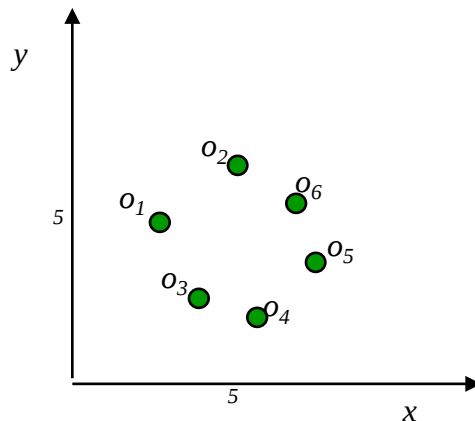
Cluster descriptors (numerical data)

- Centroid: the “middle” of a cluster
- Radius: square root of average distance from any point of the cluster to its centroid
- Diameter: square root of average mean squared distance between all pairs of points in the cluster

$$c_m = \frac{\sum_{i=1}^n p_i}{n}$$

$$r_m = \sqrt{\frac{\sum_{i=1}^n (p_i - c_m)^2}{n}}$$

$$d_m = \sqrt{\frac{\sum_{i=1}^n \sum_{j=1}^n (p_i - p_j)^2}{n(n-1)}}$$



Typical alternatives to calculate the distance between clusters

- Single link: smallest distance between an element in one cluster and an element in the other, i.e.,

$$dis_{sl}(C_i, C_j) = \min_{x,y} \{d(x, y) \mid x \in C_i, y \in C_j\}$$

- Complete link: largest distance between an element in one cluster and an element in the other, i.e.,

$$dis_{cl}(C_i, C_j) = \max_{x,y} \{d(x, y) \mid x \in C_i, y \in C_j\}$$

- Average: avg distance between an element in one cluster and an element in the other, i.e.,

$$dis_{avg}(C_i, C_j) = \frac{\sum_{x \in C_i, y \in C_j} d(x, y)}{|C_i| |C_j|}$$

- Centroid: distance between the centroids of two clusters, i.e.,

$$dis_{centroids}(C_i, C_j) = d(c_i, c_j)$$

- Medoid: distance between the medoids of two clusters, i.e., $dis(K_i, K_j) = dis(M_i, M_j)$
 - Medoid: one chosen, centrally located object in the cluster

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Partitioning methods idea

- Construct a partition of a database **D** of **n** objects into a set of **k** clusters
 - Each object belongs to exactly one cluster (hard clustering)
 - The number of clusters k is given in advance
- The partition should optimize the chosen partitioning criterion
 - e.g., minimize the intra-cluster variance, i.e., the sum of the squared distances from each data point to its cluster center.
 - Possible solutions:
 - o Global optimal: exhaustively enumerate all partitions
 - o Heuristic methods: k-means and k-medoids algorithms
 - o k-means (MacQueen'67): Each cluster is represented by the center of the cluster
 - o k-medoids or PAM (Partition around medoids) (Kaufman & Rousseeuw'87): Each cluster is represented by one of the objects in the cluster

The k-Means problem

- Given a set X of n points in a d -dimensional space and an integer k
- Task: choose a set of k points $\{c_1, c_2, \dots, c_k\}$ in the d -dimensional space to form clusters $\{C_1, C_2, \dots, C_k\}$ such that

$$Cost(C) = \sum_{i=1}^k \underbrace{\sum_{x \in C_i} (x - c_i)^2}_{\text{Cluster cost}}$$

Clustering cost

is minimized.

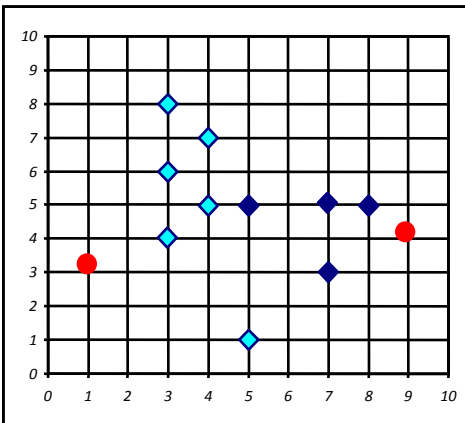
- Some special cases: $k = 1$, $k = n$

The k-Means algorithm

- Given k , the k-Means algorithm is implemented in four steps:
 - Randomly pick k objects as cluster centers $\{c_1, \dots, c_k\}$
 - Assign the rest of the points to their closest cluster centers.
 - Update the center of each cluster based on the new point assignments.
 - Repeat until convergence
- Complexity
 - Relatively efficient: $O(tkn)$, where n is # objects, k is # clusters, and t is # iterations. Normally, $k, t \ll n$.

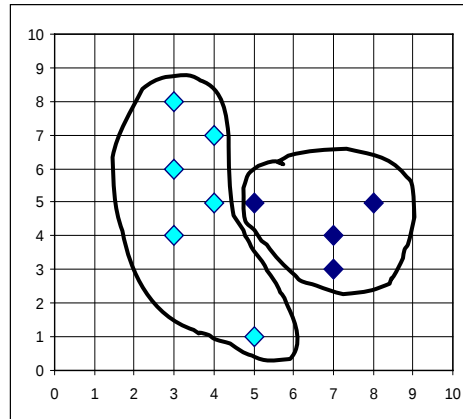
k-Means example

$k=2$

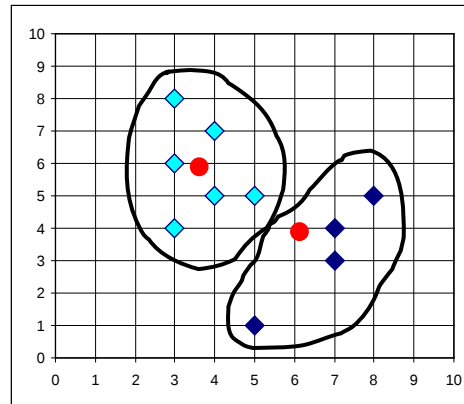


Arbitrarily choose K objects
as initial cluster center

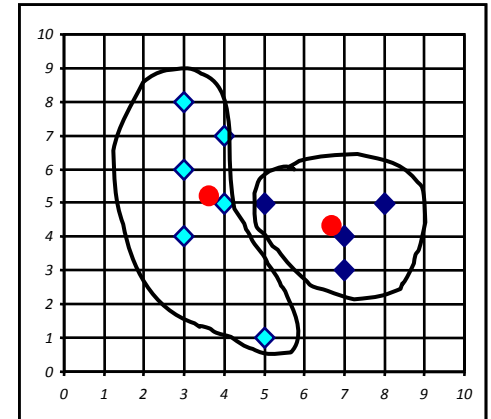
Assign
each
objects to
most
similar
center



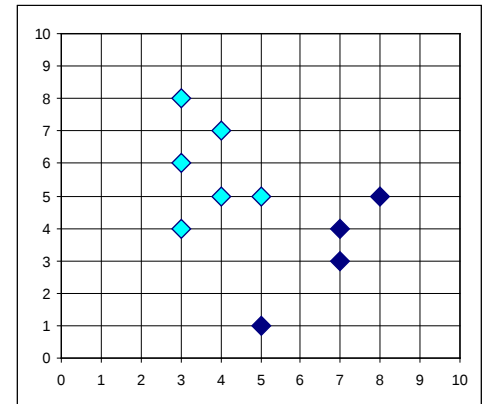
↑ *reassign*



Update
the
cluster
means



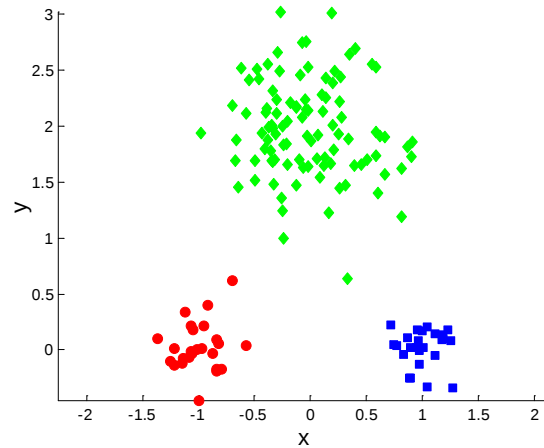
↓ Reassign



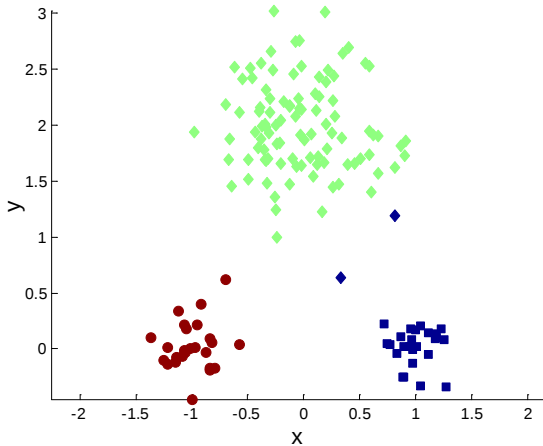
Update
the
cluster
means

- Relatively efficient: $O(tkn)$, where n is # objects, k is # clusters, and t is # iterations. Normally, $k, t \ll n$.
 - Comparing: PAM: $O(k(n-k)^2)$, CLARA: $O(ks^2 + k(n-k))$
- Finds a local optimum
 - The global optimum may be found using techniques such as: deterministic annealing and genetic algorithms
- The choice of initial points can have large influence in the result
- Weakness
 - Need to specify k , the number of clusters, in advance
 - Unable to handle noisy data and outliers
 - Not suitable to discover clusters with non-convex shapes
 - Applicable only when mean is defined, then what about categorical data?

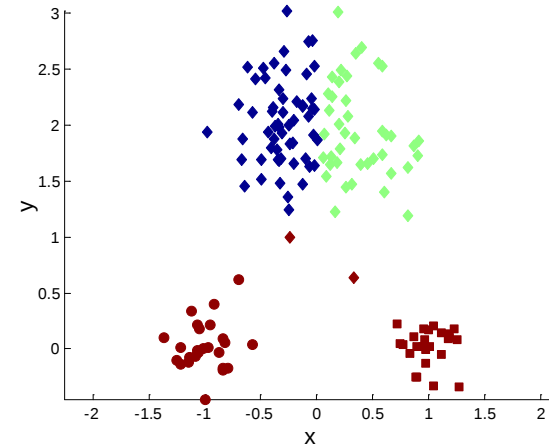
Two different K-means clusterings



Original Points



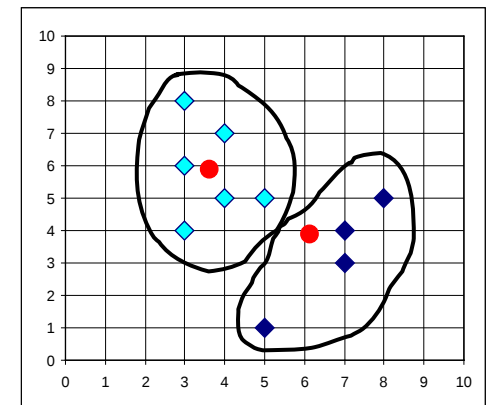
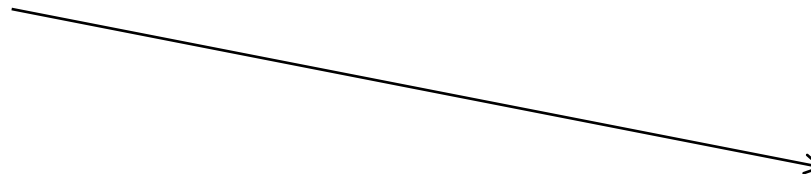
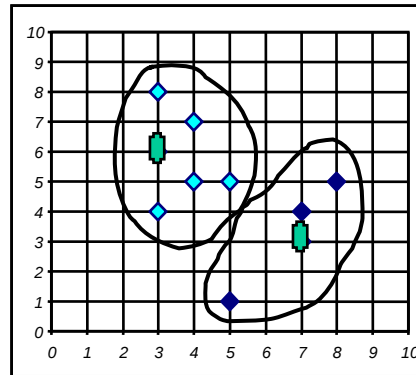
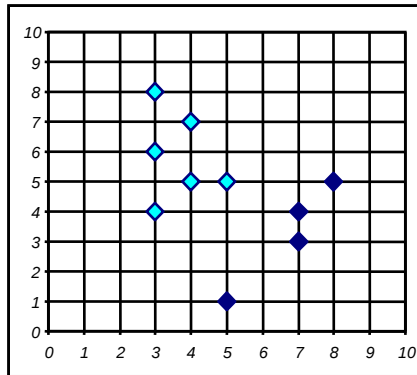
Optimal Clustering



Sub-optimal Clustering

The problem with outliers

- The k-Means algorithm is sensitive to outliers!
 - an object with an extremely large value may substantially distort the distribution of the data.
- K-Medoids: Instead of taking the mean value of the object in a cluster as a reference point, medoids can be used, which is the most centrally located object in a cluster.



k-Means variations

- A few variants of the *k-means* which differ in
 - Selection of the initial *k* means
 - o Multiple runs
 - o Not random selection of centers. e.g., pick the most distant (from each other) points as cluster centers (kMeans++ algorithm)
 - Dissimilarity calculations
 - Strategies to calculate cluster means
- Handling categorical data: *k-modes* (Huang'98)
 - Replacing means of clusters with modes
 - Using new dissimilarity measures to deal with categorical objects
 - Using a frequency-based method to update modes of clusters
 - A mixture of categorical and numerical data: *k-prototype* method

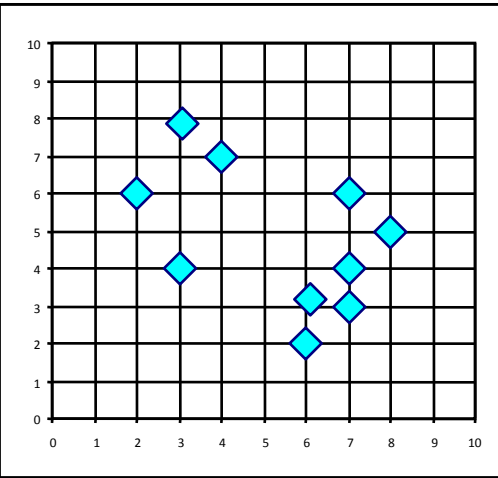
The k-Medoids clustering algorithm

- Clusters are represented by real objects called **medoids**.
- PAM (Partitioning Around Medoids, Kaufman and Rousseeuw, 1987)
 - starts from an initial set of k medoids and iteratively replaces one of the medoids by one of the non-medoids if it improves the total clustering cost
- Pseudocode:
 - Select k representative objects arbitrarily
 - Representative replacement: For each pair of non-selected object h and selected object i , check whether i could be replaced by h
 - Replacement is possible if the total clustering cost is improving
 - Repeat until no improvements can be achieved by any replacement

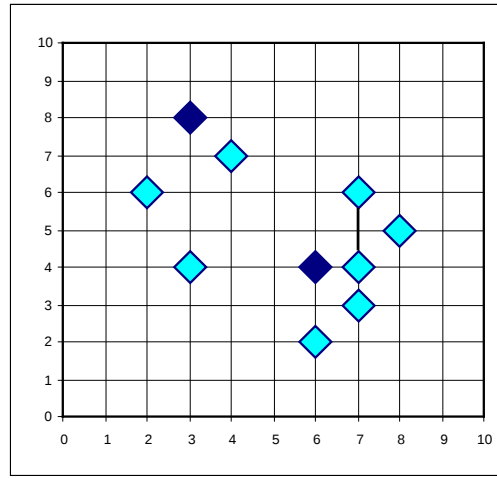
PAM example

K=2

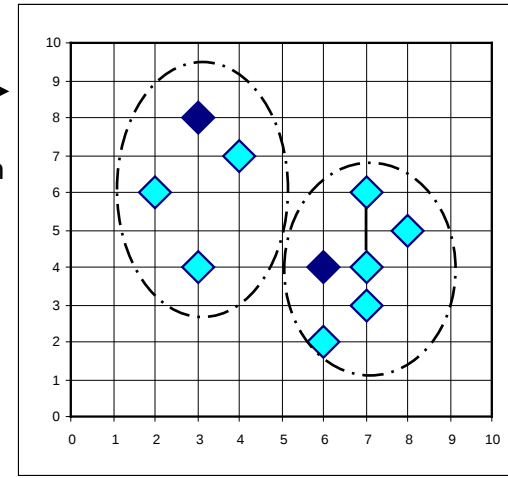
Total Cost = 20



Arbitrary
choose k
object as
initial
medoids



Assign each
remaining
object to
nearest
medoids



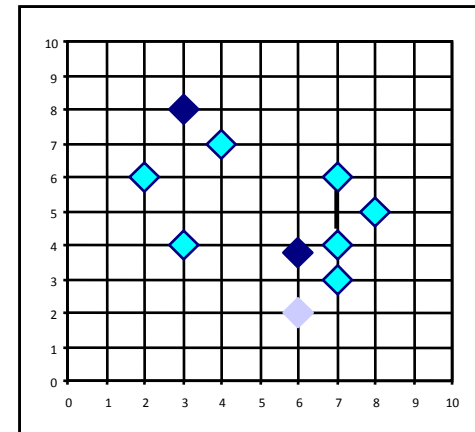
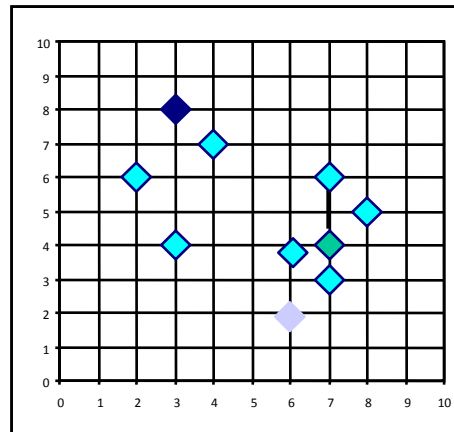
Randomly select a nonmedoid
object, O_{random}

Compute total
cost of
swapping

Total Cost = 26

Swapping O and
 O_{random}
If quality is
improved.

Do loop
Until no change



- Very similar to k-Means
 - PAM is more robust than k-Means in the presence of noise and outliers because a medoid is less influenced by outliers or other extreme values than a mean
 - PAM works efficiently for small data sets but does not scale well for large data sets.
 - $O(k(n-k)^2)$ for each iterationwhere n is # of data, k is # of clusters
- ➔ Sampling based method,
CLARA(Clustering LARge Applications)

- CLARA (Kaufmann and Rousseeuw in 1990)
- It draws multiple samples of the data set, applies PAM on each sample, and gives the best clustering as the output
- Strength: deals with larger data sets than PAM
- Weakness:
 - Efficiency depends on the sample size
 - A good clustering based on samples will not necessarily represent a good clustering of the whole data set if the sample is biased

CLARANS (“Randomized” CLARA) (1994)

- *CLARANS* (A Clustering Algorithm based on Randomized Search), Ng and Han’94
- *CLARANS* draws sample of neighbors dynamically
- The clustering process can be presented as searching a graph where every node is a potential solution, that is, a set of k medoids
- If the local optimum is found, *CLARANS* starts with new randomly selected node in search for a new local optimum
- It is more efficient and scalable than both *PAM* and *CLARA*
- Focusing techniques and spatial access structures may further improve its performance (Ester et al.’95)

What is the right number of clusters I

- The number of clusters k is required as input by the partitioning algorithms
- Silhouette coefficient (Kaufman & Rousseeuw 1990)
 - Let $a(o)$ the distance of an object o to the representative of its cluster and $b(o)$ the distance to the representatives of its "second best" cluster
 - Silhouette $s(o)$ of an object o :

$$s(o) = \frac{b(o) - a(o)}{\max\{a(o), b(o)\}}$$

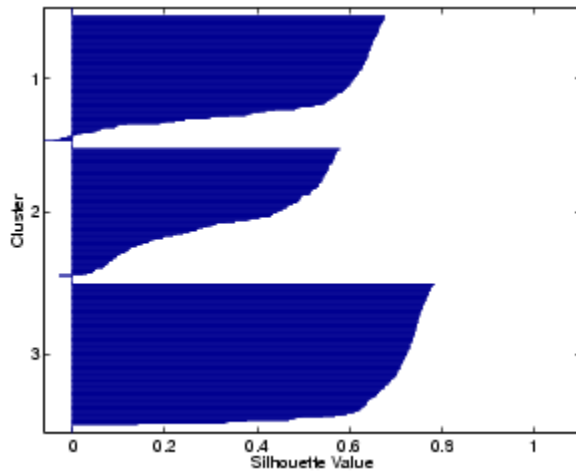
$$-1 \leq s(o) \leq +1$$

$s(o) \sim -1 / 0 / +1$: *bad / indifferent / good assignment*

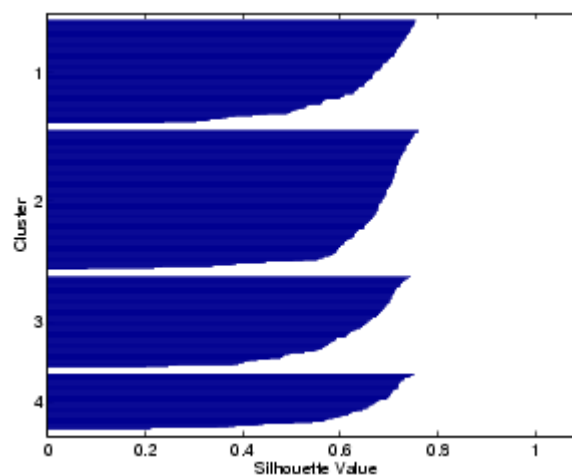
- $s(o) \sim 1 \rightarrow a(o) < b(o)$. Small $a(o)$ means it is well matched to its own cluster. Large $b(o)$ means is badly matched to its neighbouring cluster.
- $s(o) \sim -1 \rightarrow$ the neighbor cluster seems more appropriate
- $s(o) \sim 0 \rightarrow$ in the border between two natural clusters

What is the right number of clusters II

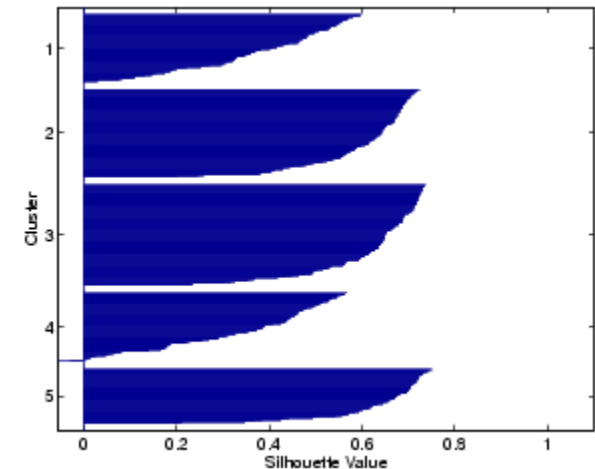
- The Silhouette coefficient of a cluster is the avg silhouette of all its objects
 - Is a measure of how tightly grouped all the data in the cluster are.
 - $> 0,7$: strong structure, $> 0,5$: usable structure
- The Silhouette coefficient of a clustering is the avg silhouette of all objects
 - is a measure of how appropriately the dataset has been clustered



K=3



K=4



K=5

- Introduction
- Types of Data in Cluster Analysis
- A Categorization of Major Clustering Methods
- Partitioning Methods
- Things you should know
- Homework/tutorial

Things you should know

- What is clustering
- Unsupervised vs supervised
- Dissimilarity measures
- Main cluster descriptors (for numerical data)
- Dissimilarity between clusters
- Main clustering methods
- Partitioning clustering methods
 - k-Means
 - k-Medoids

Tutorial: Tutorial this Thursday on classification

Homework:

- Run kMeans clustering in Elki, Weka on a numerical dataset
- Play with the number of clusters k
- Implement your own k-Means or k-Medoids method

Suggested reading:

- Han J., Kamber M., Pei J. *Data Mining: Concepts and Techniques 3rd ed.*, Morgan Kaufmann, 2011 (Chapter 10)
- Tan P.-N., Steinbach M., Kumar V., *Introduction to Data Mining*, Addison-Wesley, 2006 (Chapter 8).