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## Deep Learning and Artificial Intelligence WS 2018/19

### **Exercise 2: Math Primer**

## Exercise 2-1 Jacobian Matrices

Suppose  $F : \mathbb{R}^d \to \mathbb{R}^n$  is a vector-valued function that maps an input vector  $x \in \mathbb{R}^d$  to an output vector  $F(x) \in \mathbb{R}^n$ . The Jacobian matrix  $J_F$  is defined as:

$$J_F := \begin{pmatrix} \frac{\partial F}{\partial x_1} & \cdots & \frac{\partial F}{\partial x_d} \end{pmatrix} = \begin{pmatrix} \frac{\partial F_1}{\partial x_1} & \cdots & \frac{\partial F_1}{\partial x_d} \\ \vdots & \ddots & \vdots \\ \frac{\partial F_m}{\partial x_1} & \cdots & \frac{\partial F_m}{\partial x_d} \end{pmatrix} \in \mathbb{R}^{n \times d},$$

i.e. it contains the derivatives of each output with regard to each input:  $(J_F)_{ij} = \frac{\partial F_i}{\partial x_j}$ .

In the following, let  $x \in \mathbb{R}^d$  be a vector with d elements and  $W \in \mathbb{R}^{n \times d}$  be a matrix with n rows and d columns.

- (a) Given z = Wx. Calculate the Jacobian matrix  $J_z = \frac{\partial z}{\partial x}$ .
- (b) Given  $z = x^T W^T$ . Calculate the Jacobian matrix  $J_z = \frac{\partial z}{\partial x}$ .
- (c) Given z = f(x), where f is applied elementwise to the vector x, i.e.  $z_i = f(x_i)$ . Calculate the Jacobian matrix  $J_z = \frac{\partial z}{\partial x}$  (not the gradient  $\nabla f(x)$ ).
- (d) Given z = Wx and a loss function  $L : \mathbb{R}^n \to \mathbb{R}$  that maps z to a scalar loss L(z). Calculate  $\frac{\partial L}{\partial W} = \frac{\partial L}{\partial z} \frac{\partial z}{\partial W}$  (chain rule).

#### Exercise 2-2 Softmax and Cross-Entropy Loss

- (a) Given  $\hat{y} = softmax(z)$  with  $\hat{y}_i = \frac{e^{z_i}}{\sum_{k=1}^N e^{z_k}}$ , where  $\hat{y} \in \mathbb{R}^N$  and N is the number of classes of a classification problem. Calculate  $\frac{\partial \hat{y}_i}{\partial z_i}$ .
- (b) Given  $\hat{y} = softmax(z)$ , a target vector  $y \in \mathbb{R}^N$  and the cross-entropy loss function defined as

$$L(y,\hat{y}) = -\sum_{k=1}^{N} y_k \log \hat{y}_k$$

Calculate  $\frac{\partial L}{\partial z_i}$ . *Hint:* Make use of the chain rule  $\frac{\partial L}{\partial z_j} = \sum_i \left( \frac{\partial L}{\partial \hat{y}_i} \frac{\partial \hat{y}_i}{\partial z_j} + \frac{\partial L}{\partial y_i} \frac{\partial y_i}{\partial z_j} \right)$ . Moreover, reuse the results of exercise 2a) and the fact that vector y contains the probabilities for each class i that sum up to one, i.e:  $\sum_i y_i = 1$ .

# Exercise 2-3 Mean Squared Error

Consider the input dataset  $X \in \mathbb{R}^{n \times d}$  with *n* samples of size *d*, a target vector  $y \in \mathbb{R}^n$ , a weight vector  $w \in \mathbb{R}^d$ and a prediction  $\hat{y} = Xw$ . The mean squared error (MSE) is defined as the sum over the squared differences between the prediction  $\hat{y}_i$  and the true values  $y_i$  for each instance:

$$L(y, \hat{y}) = \frac{1}{n} \sum_{i=1}^{n} (\hat{y}_i - y_i)^2,$$

where  $\hat{y}_i = w^T x_i$  and  $x_i \in \mathbb{R}^d$  is one sample of the dataset (corresponding to one row in X).

Find the vector w that minimizes the MSE loss function!

*Hint:* You can write the sum above as a vector product! Moreover, you can use the following identities:  $(Ax)^T = x^T A^T$ ,  $\frac{\partial x^T Ax}{\partial x} = 2Ax$  and  $\frac{\partial x^T b}{\partial x} = b$  for vectors x and b and matrices A.