"Veracity" Managing Uncertain Data

Skript zur Vorlesung Datenbanksystem II Dr. Andreas Züfle





Geo-Spatial Data

- Huge flood of geo-spatial data
 - Modern technology
 - New user mentality
- Great research potential
 - New applications
 - Innovative research
 - Economic Boost
 - "\$600 billion potential annual consumer surplus from using personal location data" [1]















[1] McKinsey Global Institute. Big data: The next frontier for innovation, competition, and productivity. June 2011.





Spatio-Temporal Data

- (object, location, time) triples
- Queries:
 - "Find friends that attended the same concert last saturday"
- Best case: Continuous function time → space

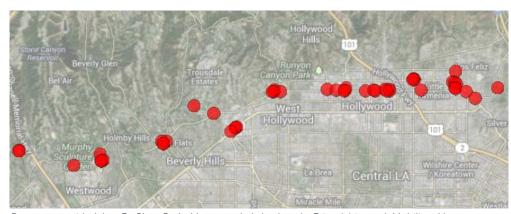


GPS log taken from a thirty minute drive through Seattle Dataset provided by: P. Newson and J. Krumm. Hidden Markov Map Matching Through Noise and Sparseness. ACMGIS 2009.



Sources of Uncertainty

- Missing Observations
 - Missing GPS signal
 - RFID sensors available in discrete locations only
 - Wireless sensor nodes sending infrequently to preserve energy
 - Infrequent check-ins of users of geo-social networks

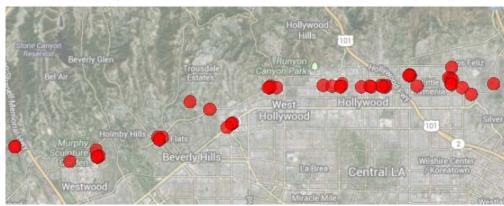


Dataset provided by: E. Cho, S. A. Myers and J. Leskovek. Friendship and Mobility: User Movement in Location-Based Social Networks. SIGKDD 2011.



Sources of Uncertainty

- Uncertain Observations
 - Imprecise sensor measurements (e.g. radio triangulation, Wi-Fi positioning)
 - Inconsistent information (e.g. contradictive sensor data)
 - Human errors (e.g. in crowd-sourcing applications)
- From database perspective, the position of a mobile object is uncertain



Dataset provided by: E. Cho, S. A. Myers and J. Leskovek. Friendship and Mobility: User Movement in Location-Based Social Networks. SIGKDD 2011.



Uncertainty in Spatial Data

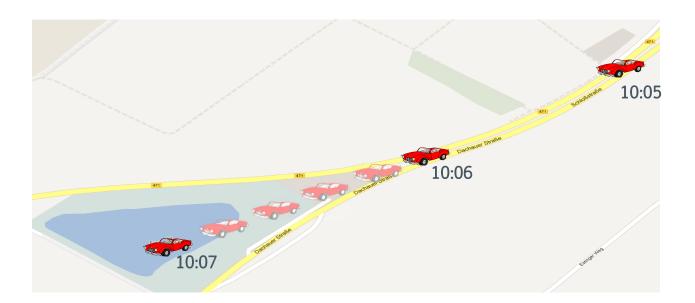
• At time 10:07: Where is an object having past observations at times 10:05am and 10:06am?





Previous Solution: Extrapolation

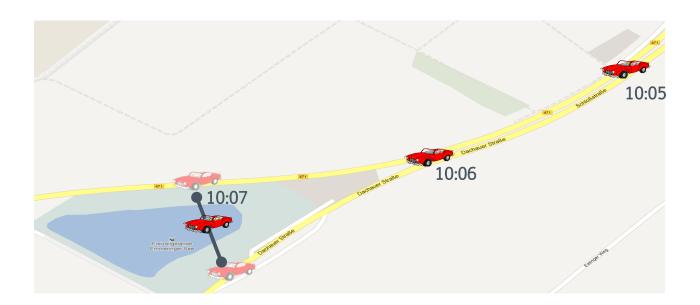
- Unknown positions are estimated using past observations
- No semantic information (road network, driver behaviour etc.)

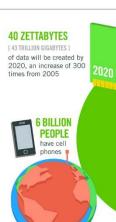




Previous Solution: Aggregation

- Exploit semantic knowledge to obtain possible positions of an object
- Aggregate possible positions (expected position, most-likely position)









SCALE OF DATA

Most companies in the U.S. have at least **100 TERABYTES**

[100,000 GIGABYTES] of data stored

The New York Stock Exchange captures

WORLD POPULATION: 7 BILLION

1 TB OF TRADE INFORMATION





Velocity ANALYSIS OF

By 2016, it is projected there will be

18.9 BILLION **NETWORK** CONNECTIONS

- almost 2.5 connections per person on earth



Modern cars have close to 100 SENSORS

that monitor items such as fuel level and tire pressure

STREAMING DATA



The FOUR V's of Big **Data**

4.4 MILLION IT JOBS



As of 2011, the global size of data in healthcare was estimated to be

150 EXABYTES

[161 BILLION GIGABYTES]



30 BILLION PIECES OF CONTENT are shared on Facebook

Variety DIFFERENT

FORMS OF DATA

By 2014, it's anticipated there will be **420 MILLION** WEARABLE, WIRELESS

HEALTH MONITORS 4 BILLION+

HOURS OF VIDEO are watched on YouTube each month



are sent per day by about 200 million monthly active users

1 IN 3 BUSINESS

don't trust the information they use to make decisions



in one survey were unsure of how much of their data was



Poor data quality costs the US economy around

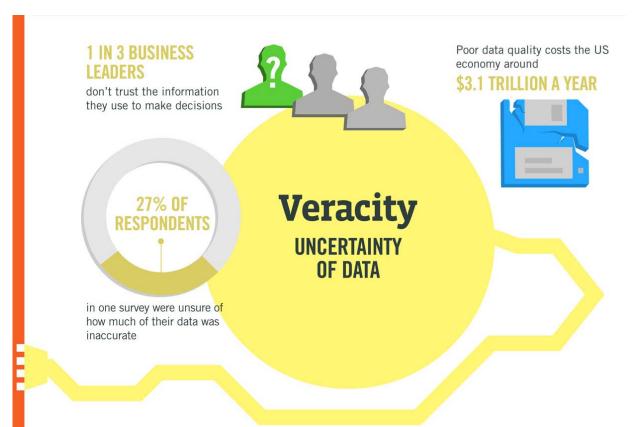
\$3.1 TRILLION A YEAR



Veracity UNCERTAINTY OF DATA









Research Challenge

Include the uncertainty directly in the querying and mining process.



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Assess the reliability of similarity search and data mining results



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Enhance the underlying decision-making process.



Overview

- 1. Introduction to Probability Theory
- 2. Case Study: Probabilistic Count Queries



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Probability Theory: Random Variables

A random variable *X* is a variable whose value is subject to variations due to chance.

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Example 2: Dice throw

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Example 4: Throw of two dice. \Omega = \{1,2,3,4,5,6\}^2 = \{(1,1),(1,2),...,(6,6)\}
Event B := "The sum of points thrown equals 4" = \{(1,3),(2,2),(3,1)\}\subseteq \Omega
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Let X be a random variable and let ω be a random event. Then $P(X = \omega)$ denotes the probability that random variable X takes a value in ω .



Probability Theory: Probability Mass Function

Let Ω be finite or countably infinite.

A function

$$p:\Omega\to[0,1]$$

such that

$$\sum_{w \in \Omega} p(w) = 1$$

is called probability mass function (pmf).



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Example 5: Dice throw $\Omega = \{1,2,3,4,5,6\}$

$$P(X=1) = p_X(1) = \frac{1}{6}$$



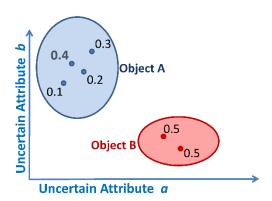
Uncertain Data

• In an uncertain database $DB = \{o_1, ..., o_N\}$, each object $o \in DB$ is a random variable.

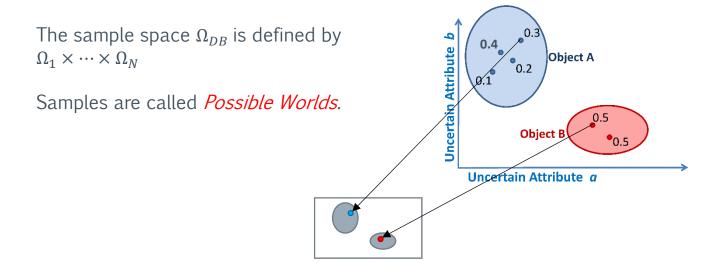


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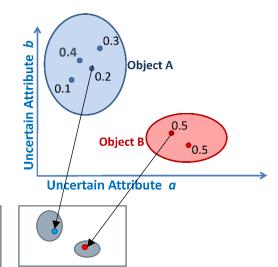


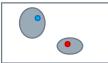






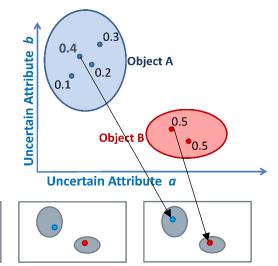
The sample space Ω_{DB} is defined by $\Omega_1\times\cdots\times\Omega_N$

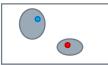






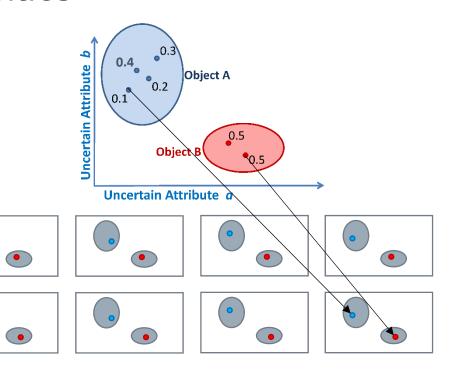
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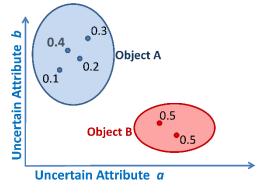


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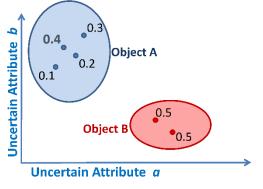
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Samples are called *Possible Worlds*.



Assumption: $p_{DB}: \Omega \to [0,1]$ can be computed efficiently.



Answering Queries using PWS

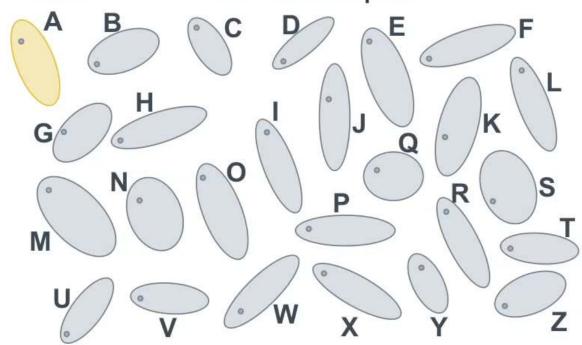
Let φ be a query predicate and let $I(\varphi, w \in \Omega_{DB})$ be an indicator function returning one if predicate φ holds in world w and zero otherwise.

The probability $P(\varphi, D)$ of the event that a query predicate φ holds on an uncertain database DB is defined as

$$P(\varphi, D) = \sum_{w \in \Omega_{DB}} I(\varphi, w) P(w)$$



Possible Worlds: Example II



STOP: 0x0000001E (0xC0000005,0x804A65B3,0x00000000,0x0000000B0) E_EXCEPTION_NOT_HANDLED	

*** Address 804A65B3 base at 80400000, DateStamp 45ec3c8f - ntoskrnl.exe

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Wenn diese Fehlermeldung zum ersten Mal angezeigt wird, starten Sie den Computer neu. Sollte diese Fehlermeldung dann erneut angezeigt werden, gehen Sie folgendermaßen vor:

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Erkundigen Sie sich beim Gerätehersteller nach BIOS-Aktualisierungen. Deaktivieren Sie BIOS-Speicheroptionen, wie "Caching" oder "Shadowing". Falls Sie Komponenten im abgesicherten Modus deaktivieren oder entfernen müssen, starten Sie den Computer neu, drücken Sie F8, um die erweiterten Startoptionen anzuzeigen, und wählen Sie den abgesicherten Modus.

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Too many possible worlds

Main challenge:

- Answer queries efficiently.
- Despite an exponential number of possible worlds

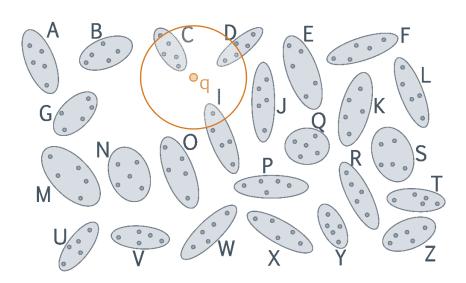


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- 2. Case Study: Probabilistic Count Queries

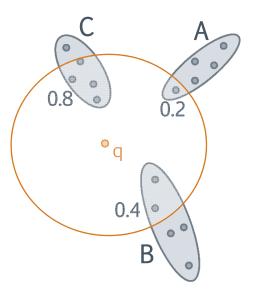


How many objects are located in the depicted circular region centered at query point q?



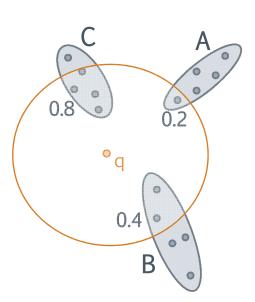


- \geq 2^{|DB|} possible worlds
- Main idea: Use polyomial multiplication to enumerate possible results





$$\mathcal{F} = (P(A) \cdot x + 1 - P(A)) \cdot (P(B) \cdot x + 1 - P(B)) \cdot (P(C) \cdot x + 1 - P(C))$$

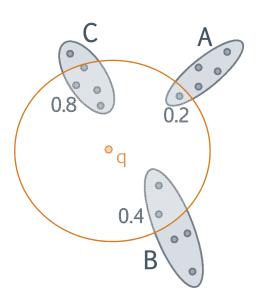




$$\mathcal{F} = (P(A) \cdot x + 1 - P(A)) \cdot (P(B) \cdot x + 1 - P(B)) \cdot (P(C) \cdot x + 1 - P(C)) =$$

$$(0.2x + 0.8) \cdot (0.4x + 0.6) \cdot (0.8x + 0.2) =$$

$$(0.08x^{2} + 0.12x + 0.32x + 0.48) \cdot (0.8x + 0.2)$$



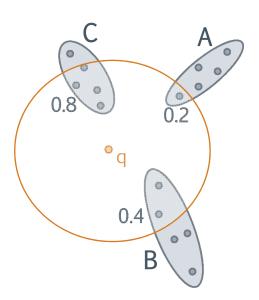


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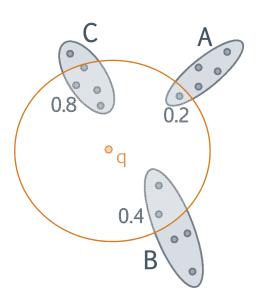
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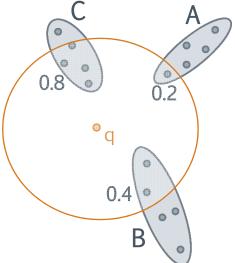
$$(0.032x^{3} + 0.224x^{2} + 0.456x^{1} + 0.288x^{0})$$





Example:

$$\mathcal{F} = (P(A) \cdot x + 1 - P(A)) \cdot (P(B) \cdot x + 1 - P(B)) \cdot (P(C) \cdot x + 1 - P(C)) = (0.2x + 0.8) \cdot (0.4x + 0.6) \cdot (0.8x + 0.2) = (0.08x^2 + 0.12x + 0.32x + 0.48) \cdot (0.8x + 0.2) = (0.08x^2 + 0.44x + 0.48) \cdot (0.8x + 0.2) = (0.032x^3 + 0.224x^2) + 0.456x^1 + 0.288x^0)$$





Probability that exactly two objects are inside the query region



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Polynomial time solution: Unify worlds that are equvalent with respect to the query predicate!

