## Chapter 3:

## Map Reduce / Hadoop / HDFS





## Outline

- Distributed File Systems (re-visited)
- MapReduce
  - Motivation
  - Programming Model
  - Example Applications
- Big Data in Apache<sup>™</sup> Hadoop®
  - HDFS
  - MapReduce in Hadoop
  - YARN





#### Outline

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## **Distributed File Systems**

- Difference to RDBMS
- Parallel Computing Architecture





## Past

- most computing is done on a single processor:
  - one main memory
  - one cache
  - one local disk, ...

## **New Challenges:**

- Files must be stored redundantly:
  - If one node fails, all of its files would be unavailable until the node is replaced (see File Management)
- Computations must be divided into tasks:
  - a task can be restarted without affecting other tasks (see MapReduce)
- use of commodity hardware





- Drawbacks of RDBMS
  - Database system are difficult to scale.
  - Database systems are difficult to configure and maintain
  - Diversification in available systems complicates its selection
  - Peak provisioning leads to unnecessary costs
- Advantages of NoSQL systems:
  - Elastic scaling
  - Less administration
  - Better economics
  - Flexible data models





## **Parallel computing architecture**

- Referred as cluster computing
- Physical Organisation:
  - compute nodes are stored on racks (8-64)
  - nodes on a single rack connected by a network





Racks of servers (and switches at the top), at Google's Mayes County, Oklahoma data center [extremetech.com]

Nodes within a rack are connected by a network, typically gigabit Ethernet





## **Parallel computing architecture**

## Large-Scale File-System Organisation:

- Characteristics:
  - files are several terabytes in size (Facebook's daily logs: 60TB; 1000 genomes project: 200TB; Google Web Index; 10+ PB)
  - files are rarely updated
  - Reads and appends are common

## **Exemplary distributed file systems:**

- Google File System (GFS)
- Hadoop Distributed File System (HDFS, by Apache)
- CloudStore
- HDF5
- S3 (Amazon EC2)
- ...





## **Parallel computing architecture**

- Large-Scale File-System Organisation:
  - Organisation:
    - files are divided into chunks (typically 16-64MB in size)
    - chunks are replicated n times (i.e default in HDFS: n=3) at n different nodes (optimally: replicas are located on different racks optimising fault tolerance)
  - how to find files?
    - existence of a master node
    - holds a meta-file (directory) about location of all copies of a file -> all participants using the DFS know where copies are located







## MapReduce

- Motivation
- Programming Model
  - Recap Functional Programming
- Examples





## **Motivation: MapReduce - Comparison to Other Systems**

#### MapReduce vs. RDBMS

	MapReduce	RDBMS
Data size	Petabytes	Gigabytes
Access	Batch	Interactive and Batch
Updates	Write once, read many times	Read & Write many times
Structure	Dynamic schema	Static schema
Integrity	Low	High (normalized data)
Scaling	Linear	Non-linear





## **Motivation: MapReduce - Comparison to Other Systems**

## MapReduce vs. Grid Computing

- Accessing large data volumes becomes a problem in High performance computing (HPC), as the **network bandwidth** is the bottleneck <-> Data Locality in MapReduce
- in HPC, programmers have to explicitly handle the data flow <-> MapReduce operates only in higher level, i.e. data flow is implicit
- handling partial failures <-> MapReduce as a shared-nothingarchitecture (no dependence of tasks); detects failures and reschedules missing operations





## **Motivation: Large Scale Data Processing**

In General:

- MapReduce can be used to manage large-scale computations in a way that is tolerant of hardware faults
- System itself manages automatic parallelisation and distribution, I/O scheduling, coordination of tasks that are implemented in map() and reduce() and copes with unexpected system failures or stragglers
- several implementations: Google's internal implementation, open-source implementation Hadoop (using HDFS), ...





- Input & Output: each a set of key/value pairs
- Programmer specifies two functions:

## map (in\_key, in\_value) -> list (out\_key, intermediate\_value)

- ·Processes input key/value pair; one Map()-Call for every pair
- ·Produces a set of intermediate pairs

#### reduce (out\_key, list(intermediate\_value)) -> list (out\_value)

- combines all intermediate values for a particular key; one Reduce()-call per unique key
- ·produces a set of merged output values (usually just one output value)





## **Programming Model – Recap: Functional Programming**

- MapReduce is inspired by similar primitives in LISP, SML, Haskell and other languages
- The general idea of higher order functions (map and fold) in functional programming (FP) languages are transferred in the environment of MapReduce:
  - map in MapReduce <-> map in FP
  - reduce in MapReduce <-> fold in FP





## **Programming Model – Recap: Functional Programming**

- MAP:
  - 2 parameters: applies a function on each element of a list
  - the type of the elements within the result list can differ from the type of the input list
  - the size of the result list remains the same

```
In Haskell:

map :: (a->b) -> [a] -> [b]

map f [] = []

map f (x:xs) = f x : map f xs
```

#### Example:

```
*Main> map (\x -> (x,1)) ["Big","Data","Management","and","Analysis"]
[("Big",1),("Data",1),("Management",1),("and",1),("Analysis",1)]
```





## **Programming Model – Recap: Functional Programming**

- FOLD:
  - 3 parameters: traverse a *list* and apply a function *f()* to each element plus an *accumulator*. *f()* returns the next *accumulator* value
  - in functional programming: foldI and foldr

```
In Haskell (analog foldr): foldl :: (b->a->b) -> b -> [a] -> b
foldl f acc [] = acc
foldl f acc (x:xs) = fold f (f acc x) xs
```

## Example:

```
*Main> foldl (\acc (key,value) -> acc + value) 0 [("Big", 1), ("Big", 1), ("Big", 1)]
3
```





## **Programming Model - General Processing of MapReduce**

- 1. Chunks from a DFS are attached to Map tasks turning each chunk into a sequence of *key-value* pairs.
- 2. key-value pairs are collected by a master controller and sorted by key. The keys are divided among all Reduce tasks.
- 3. Reduce tasks work on each key separately and combine all the values associated with a specific key.





## **Programming Model - High-level MapReduce diagram**







## **Programming Model - High-level MapReduce diagram**







- Programmer's task: specify map() and reduce();
- MapReduce environment takes care of:
  - Partitioning the input data
  - Scheduling
  - Shuffle and Sort (performing the group-by-key step)
  - Handling machine failures and stragglers
  - Managing of required inter-machine **communication**





## Partitioning the input data

- data files are divided into blocks (default in GFS/HDFS: 64 MB) and replicas of each are stored on different nodes
- Master schedules map() tasks in close proximity to data storage
  - map() tasks are executed physically on the same machine where one replica of an input file is storaged (or, at least on the same rack -> communication via network switch)
  - —> Goal: conserve network bandwidth (c.f Grid Computing)

·—> achieves to read input data at local disk speed, rather than limiting read rate by rack switches





## Scheduling

- One master, many workers
  - split input data into M map tasks
  - reduce phase partitioned into R tasks
  - tasks are assigned to workers dynamically
- Master assigns each map task to a free worker
  - considers proximity of data to worker
    - —> worker reads task input (optimal: from local disk)
    - —> output: files containing intermediate (key,value)-pairs sorted by key
- Master assigns each reduce task to a free worker
  - worker reads intermediate (key, value)-pairs
  - worker merges and applies reduce()-function for output





**Shuffle and Sort** (performing the group-by-key step)

- input to every reducer is sorted by key
- Shuffle: sort and transfer the map outputs to the reducers as inputs
- Mappers need to separate output intended for different reducers
- Reducers need to collect their data from all(!) mappers
  - keys at each reducer are processed in order





## **Shuffle and Sort** (performing the group-by-key step)



Quelle: Oreilly, Hadoop - The Definitive Guide 3rd Edition, May 2012





## Handling machine **failures** and **stragglers**

- General: master pings workers periodically to detect failures
  - Map worker failure
    - Map tasks completed or in-progress at worker are reset to idle
    - all reduce workers will be notified about any re-execution

## - Reduce worker failure

- only in-progress tasks at worker will be re-executed
- —> output stored in global FS
- Master failure
  - master node is replicated itself. 'Backup' master recovers last updated log files (metafile) and continues
  - if no 'backup' master -> MR task is aborted and client is notified



# Handling machine **failures** and **stragglers** - Failures







## Handling machine **failures** and **stragglers**

#### - Stragglers

- slow workers lengthen the termination of a task
- close to completion, backup copies of the remaining in-progress tasks are created
- Causes: hardware degradation, software misconfiguration, ...
- if a task is running slower than expected, another equivalent task will be launched as backup -> speculative execution of tasks
- when a task completes successfully, any duplicate task are killed



## Handling machine **failures** and **stragglers**

- Stragglers







Managing required inter-machine **communication** 

- Task status (idle, in-progress, completed)
- Idle tasks get scheduled as workers become available
- In completion of a map task, the worker sends the location and sizes of its intermediate files to the master
- Master pushes this info to reducers
- Fault tolerance: master pings workers periodically to detect failures





#### **Programming Model - General Processing - Workflow**

Workflow of MapReduce (as original implemented by Google):

**1.** Initiate the MapReduce environment on a cluster of machines

2. One Master, the rest are workers that are assigned tasks by the master

**3.** A map task reads the contents of an input split and passes them to the MAP-function. The results are buffered in memory

**4.** The buffered (key,value)-pairs are written to local disk. The location of these (intermediate) files are passed back to the master

**5.** A reduce worker who has been notified by the master, uses remote procedure calls to read the buffered data.

**6.** Reduce worker iterates over the sorted intermediate (key,value)-pairs and passes them to the REDUCE-function

—> On completion of all tasks, the master notifies the user program.





#### **Programming Model - Low-level MapReduce diagram**







#### Example #1 WordCount

- Setting: text documents, e.g. web server logs
- *Task:* count occurrence of distinct words appearing in the input file, e.g find popular URLs in server logs

## Challenges:

- File is too large for to fit in a single machines's memory
- parallel execution
- ---> Solution: Apply MapReduce





#### Example #1 WordCount

- Goal: Count word occurrence in a set of documents
- Input: "Wer A sagt, muss auch B sagen! Wer B sagt, braucht B nicht nochmal sagen!"

map (k1, v1) -> list (k2, v2)

map (String key, String value):
 //key:document name
 //value: content of document
 for each word w in value do:
 emitIntermediate(w, "1")

reduce (k2, list(v2)) -> list(v2)

reduce (String key, Iterator values):
 //key:a word
 //values: a list of counts
 int result = 0;
 for each v in values do:
 result += parseInt(v);
 emit(result.toString())





#### Example #1 WordCount

In a parallel environment:
 worker: 2





## Example #2 k-Means

Randomly initialize k centers:

 $\mu^{(0)} = \mu_1^{(0)}, \dots, \mu_k^{(0)}$ 

**Classify:** Assign each point  $j \in \{1, ..., m\}$  to nearest centre:

$$z^j \leftarrow rgmin_i ||\mu_i - x^j||_2^2$$

**Recenter:**  $\mu_i$  becomes centroid of its points:  $\mu_i^{(t+1)} \leftarrow \arg\min_{\mu} \sum_{j:z^j=i} ||\mu - x^j||_2^2$ 









#### Example #2 k-Means - MapReduce - Scheme







## **Example #2 k-Means - Classification Step As Map**

**Classify**: Assign each point  $j \in \{1, ..., m\}$ to nearest center:

$$z^j \leftarrow rgmin_i || \mu_i - x^j ||_2^2$$

Map:

Input:

- subset of d-dimensional objects of  $M = \{x_1, \ldots, x_m\}$  in each mapper

- initial set of centroids  $\mu^{(0)} = \mu_1^{(0)}, \dots, \mu_k^{(0)}$ 

Output:

- list of objects assigned to nearest centroid. This list will later be read by the reducer program





## **Example #2 k-Means - Classification Step As Map**

**Classify**: Assign each point  $j \in \{1, ..., m\}$ to nearest center:

```
for all x_i in M do
    bestCentroid <- null
    minDist <- inf
    for all c in C do
        dist <- l2Dist(x, c)
        if bestCentroid == null || dist < mindist then
            minDist <- dist
            bestCentroid <- c
        endif
    endfor
    outputlist << (bestCentroid, x_i)
endfor
return outputlist</pre>
```





## **Example #2 k-Means - Recenter Step as Reduce**

**Recenter:**  $\mu_i$  becomes centroid of its points:  $\mu_i^{(t+1)} \leftarrow \arg\min_{\mu} \sum_{j:z^j=i} ||\mu - x^j||_2^2$ 

Note: equivalent to averaging its points!

$$\mu_i^{(t+1)} \leftarrow \sum_{j:z^j=i} x^j / \sum_{j:z^j=i} 1$$

Reduce:

Input:

 list of (key,value)-pairs, where key = bestCentroid and value = objects assigned to this centroid

Output:

 (key,value), where key = oldcentroid and value = newBestCentroid, which is the new centroid calculated for that bestCentroid





#### **Example #2 k-Means - Recenter Step as Reduce**

## **Recenter**: *µ* becomes centroid of its points:

```
assignmentList <- outputlists // lists from mappers are merged together (shuffle)
```

```
for all (key,values) in assignmentList do
    newCentroid, sumOfObjects, numOfObjects <- null
    for all obj in values do
        sumOfObjects += obj
        numOfObjects ++
    endfor
    newCentroid <- (sumOfObjects / numOfObjects)
    newCentroidList << (key, newCentroid)
endfor
return newCentroidList</pre>
```